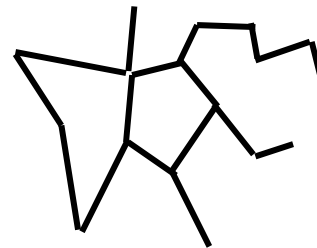
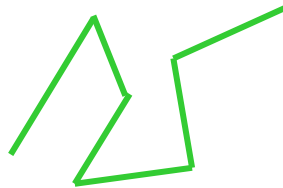
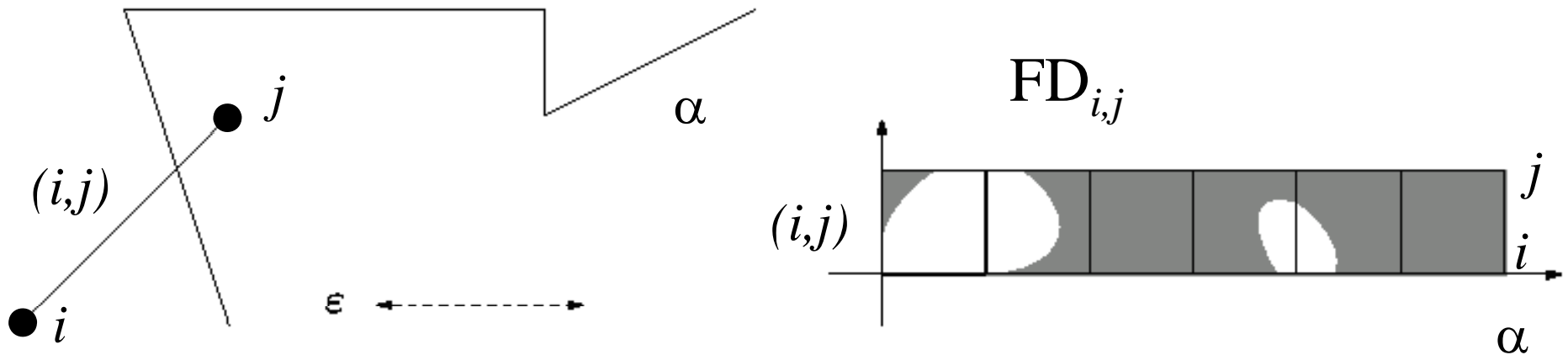


Curve - Graph

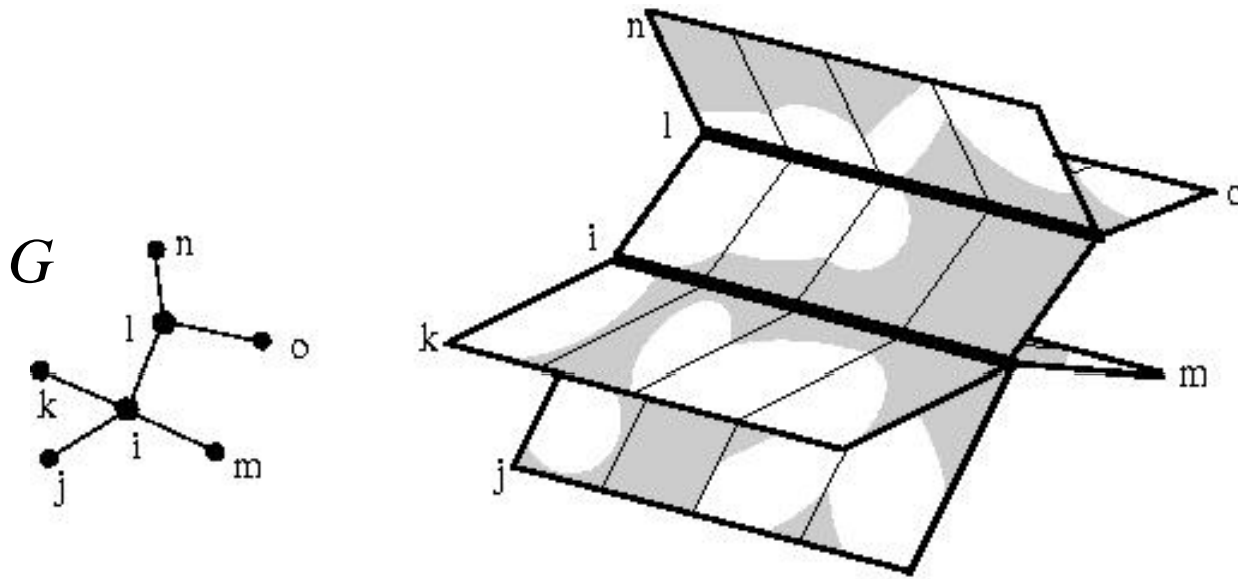


Free Space Diagram



- For each edge (i,j) in G let $FD_{i,j} = FD(\alpha, (i,j))$

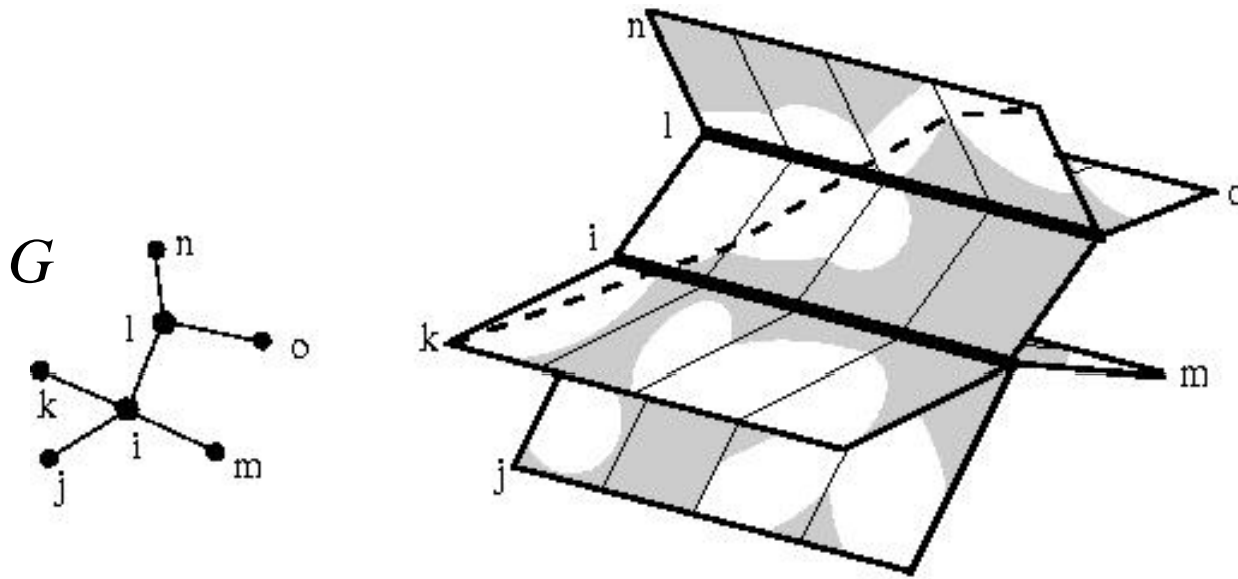
Free Space Surface



- Glue free space diagrams $FD_{i,j}$ together according to adjacency information in G

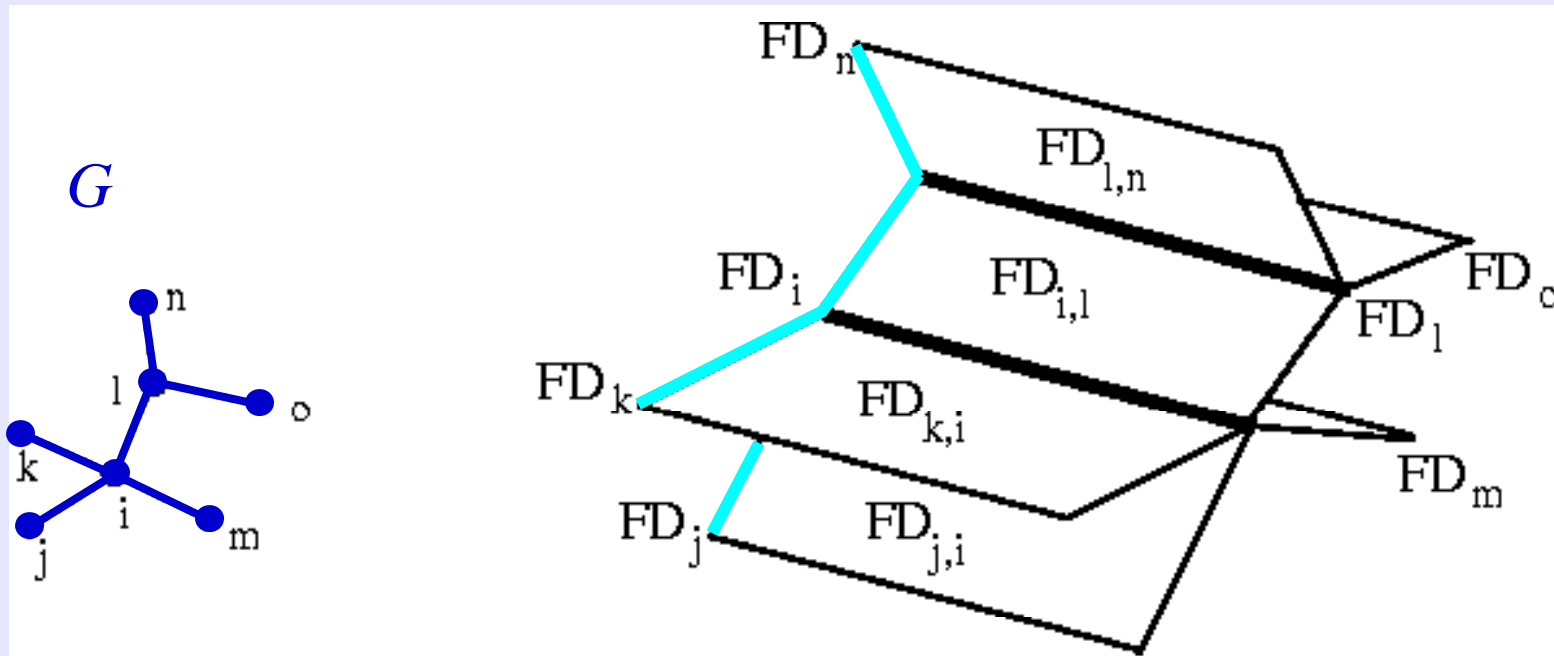
➔ **Free space surface of α and G**

Free Space Surface



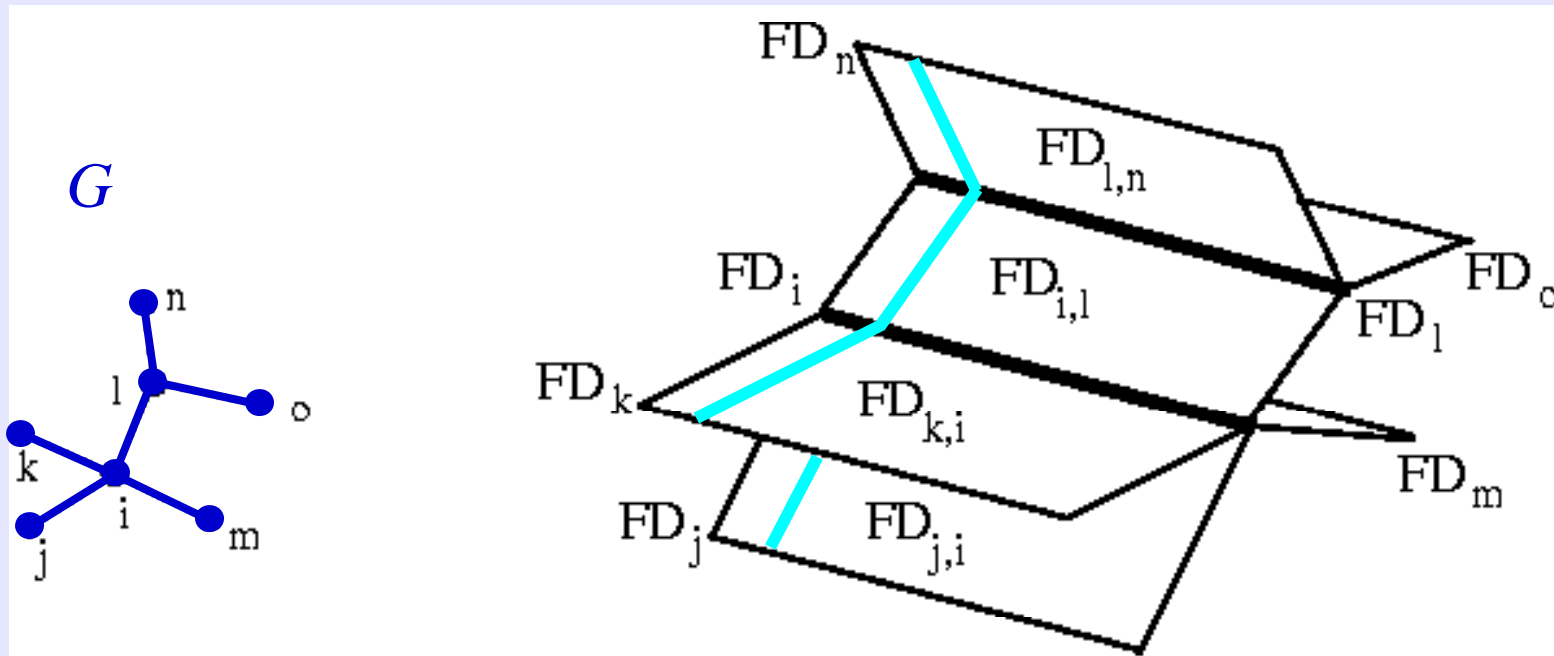
- **TASK:** Find **monotone path** in free space surface
 - starting in some lower left corner, and
 - ending in some upper right corner

Sweep



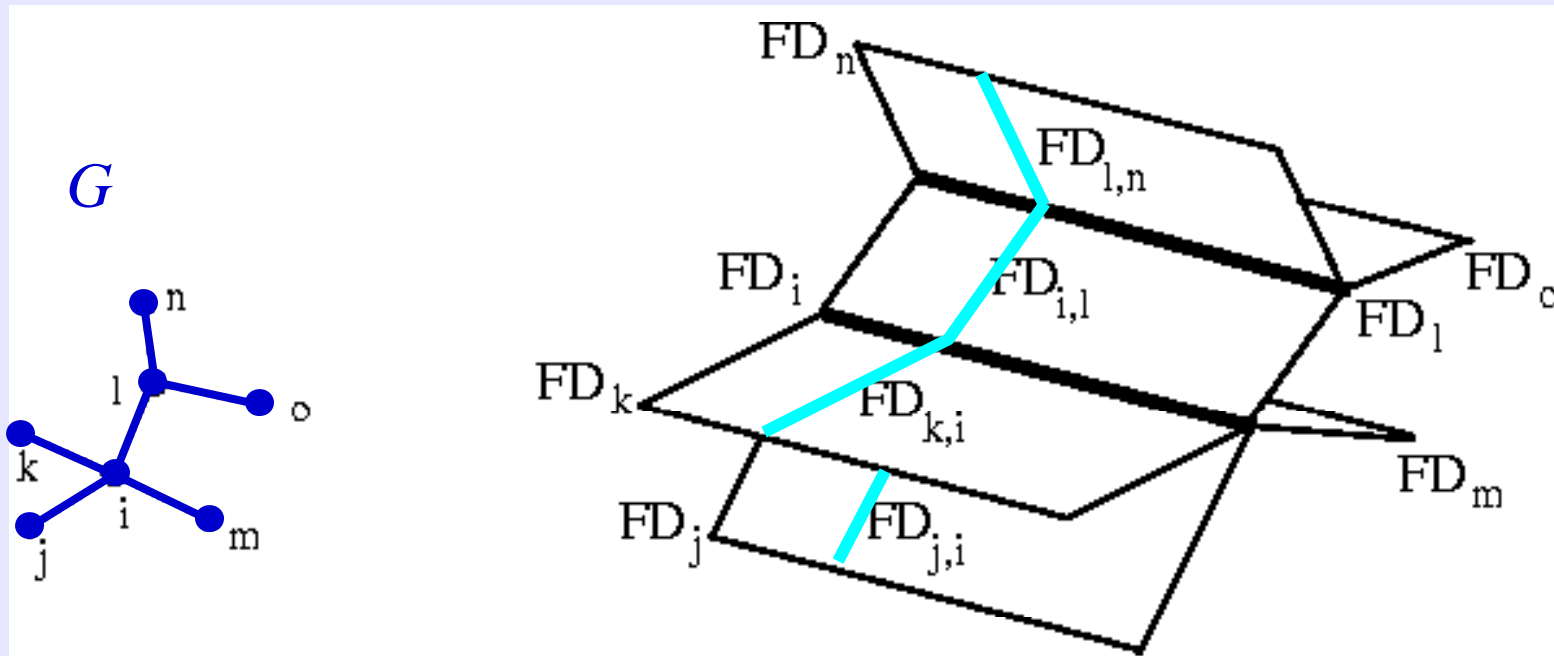
- Sweep all $FD_{i,j}$ at once with a **sweep line** from left to right

Sweep



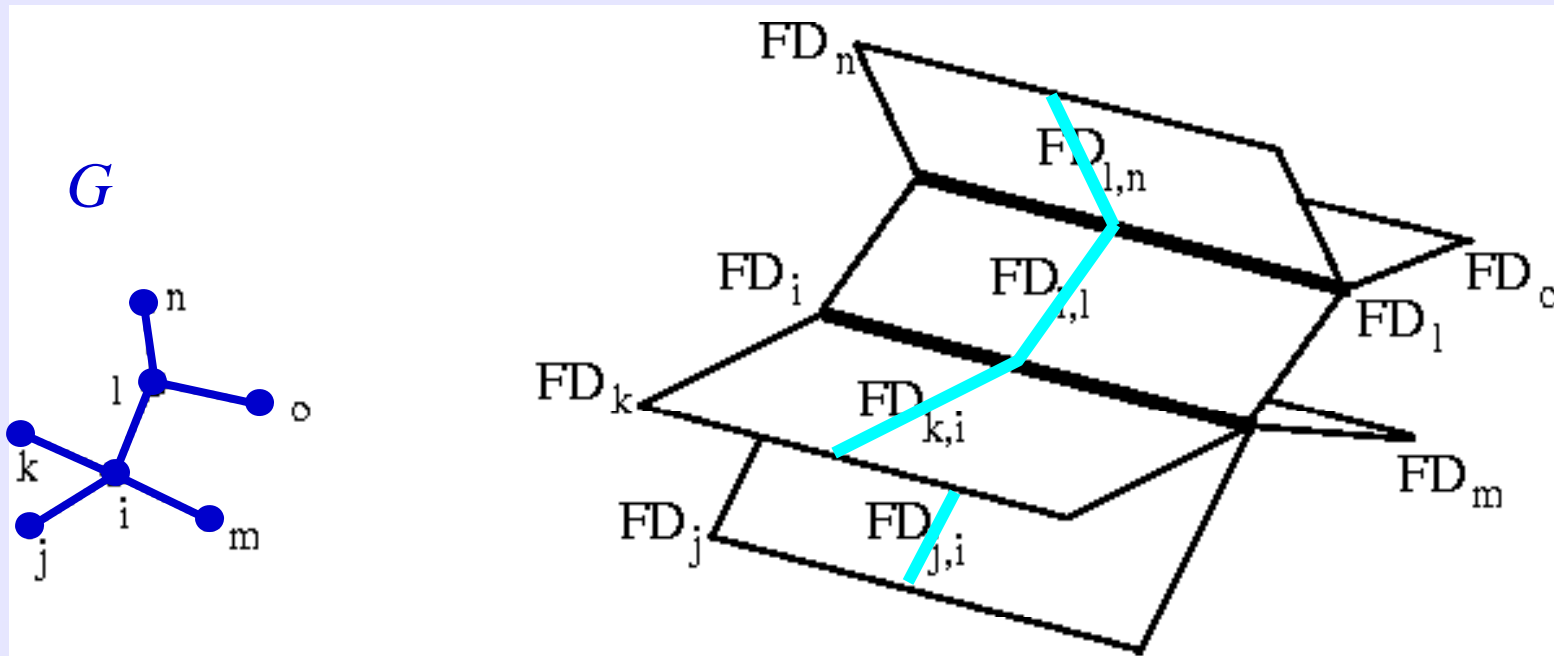
- Sweep all $FD_{i,j}$ at once with a sweepline from left to right

Sweep



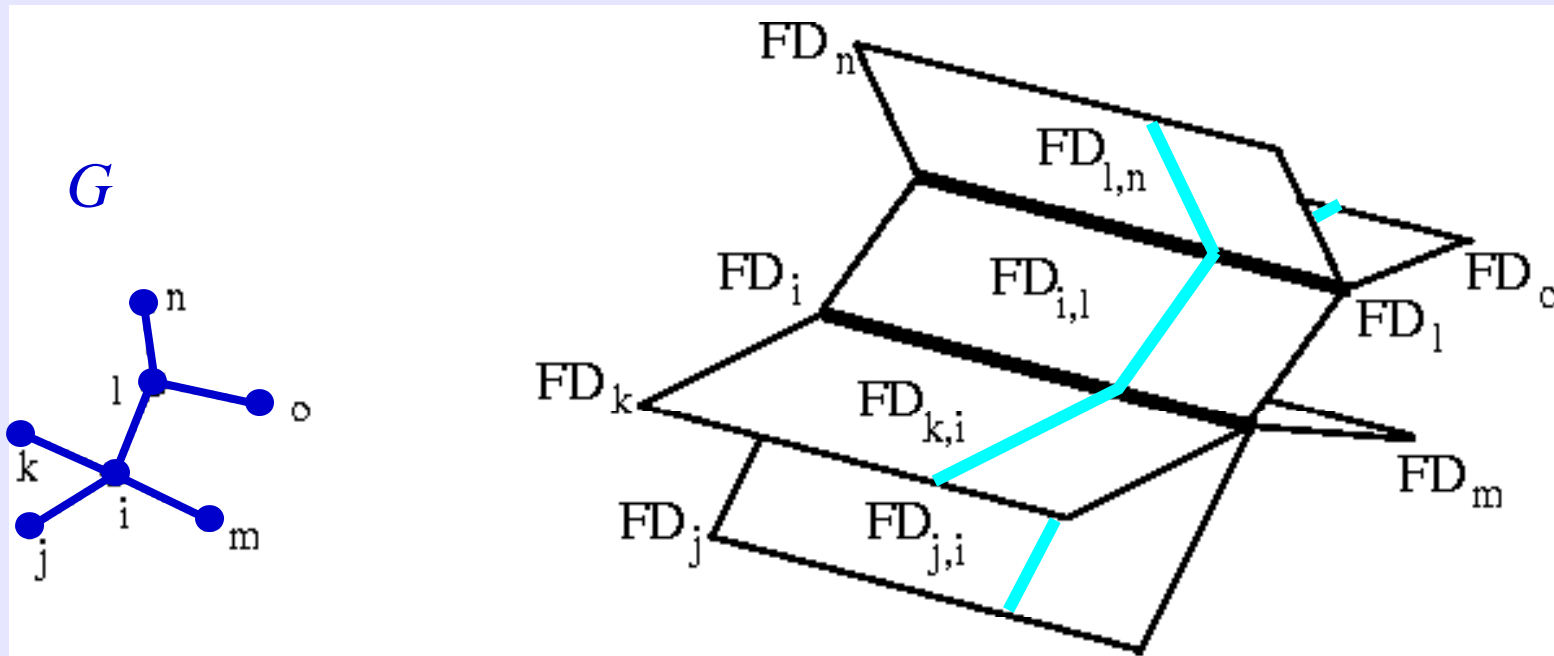
- Sweep all $FD_{i,j}$ at once with a sweepline from left to right

Sweep



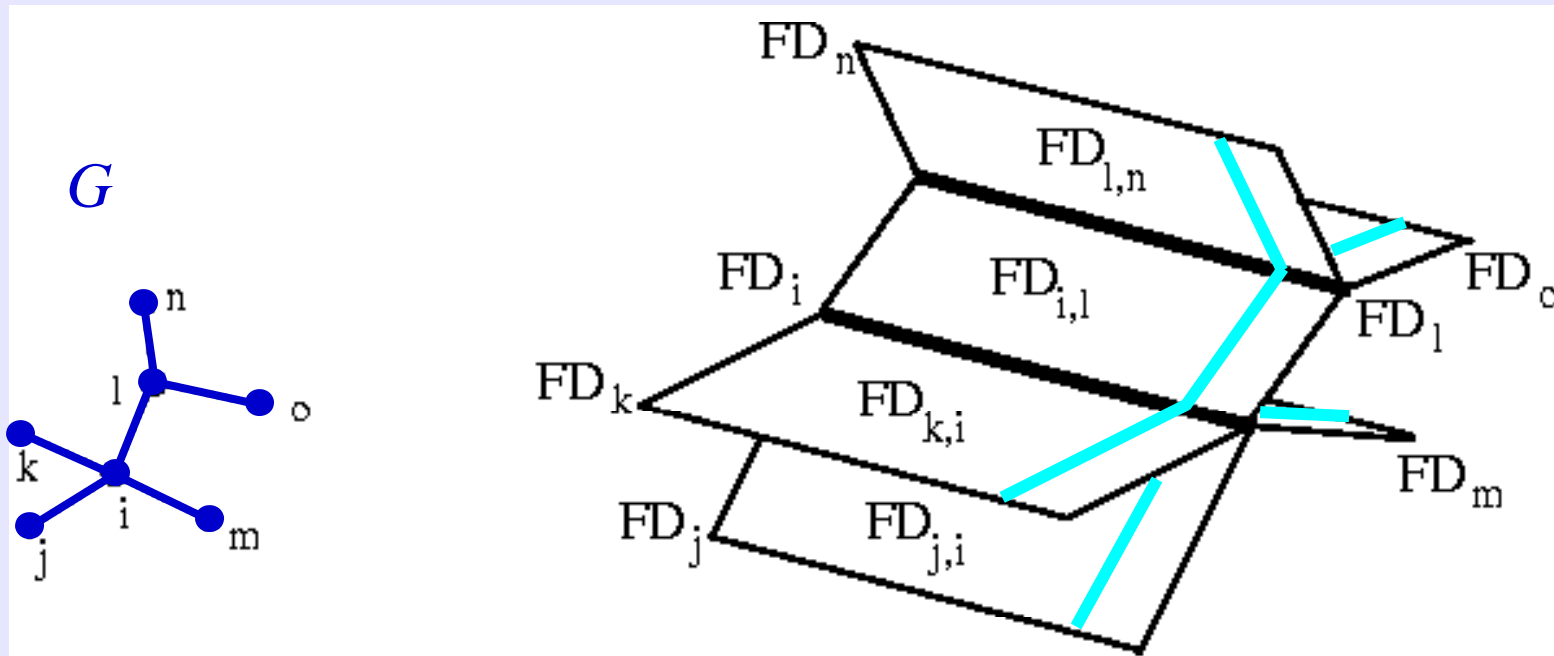
- Sweep all $FD_{i,j}$ at once with a sweepline from left to right

Sweep



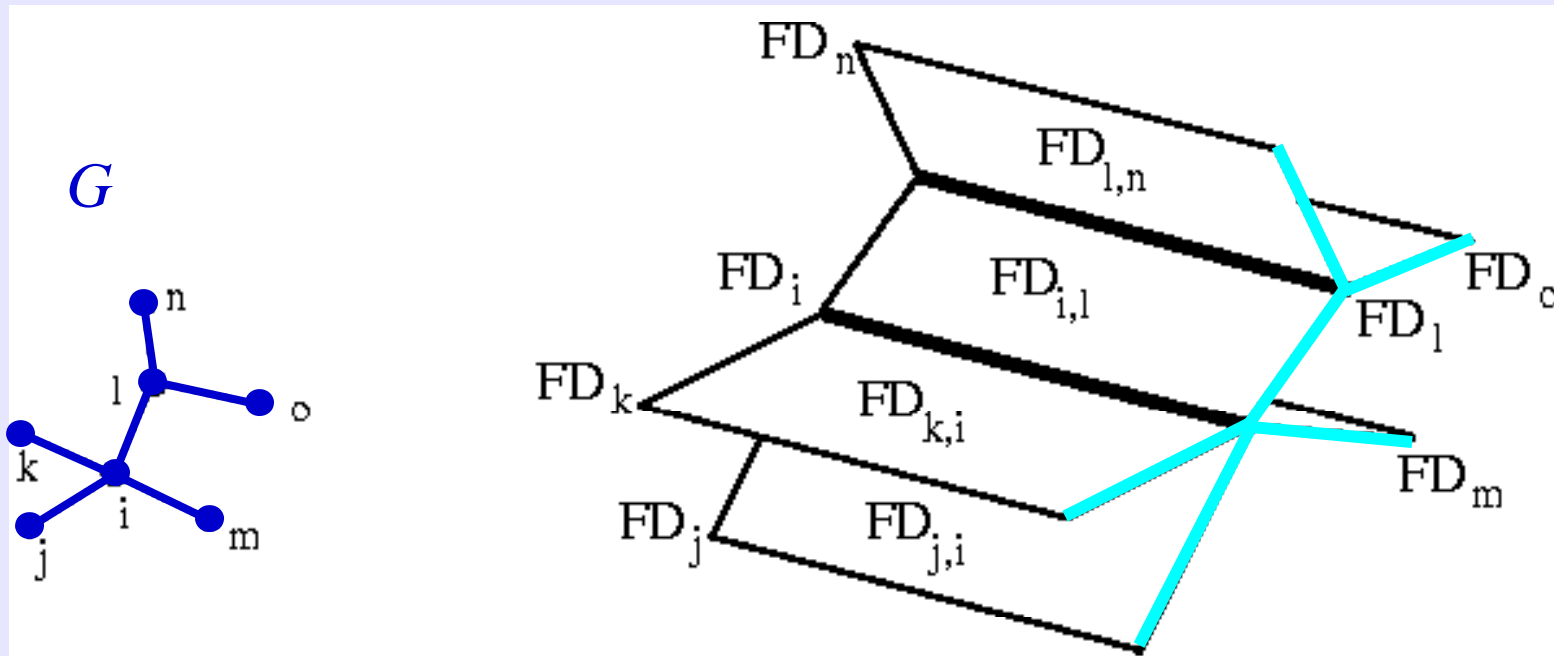
- Sweep all $FD_{i,j}$ at once with a **sweepline** from left to right

Sweep



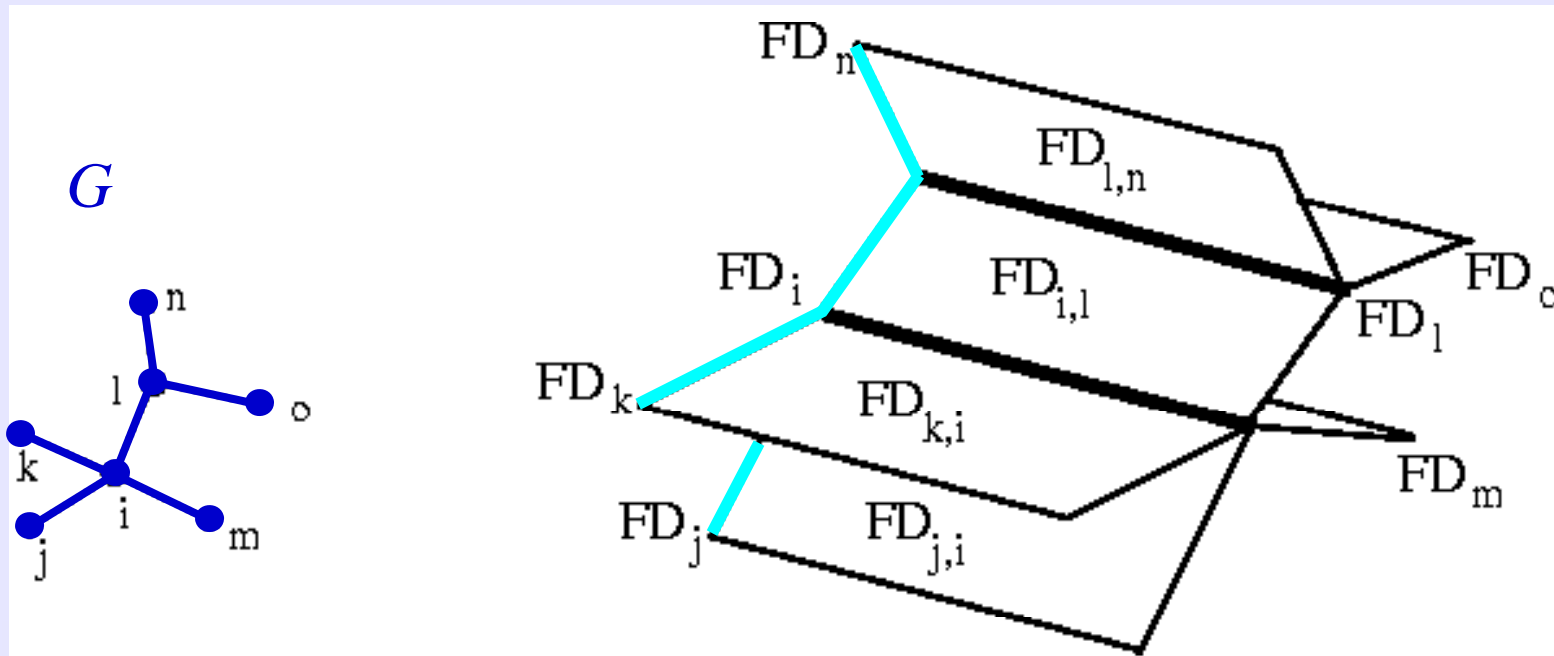
- Sweep all $FD_{i,j}$ at once with a sweepline from left to right

Sweep



- Sweep all $FD_{i,j}$ at once with a **sweepline** from left to right

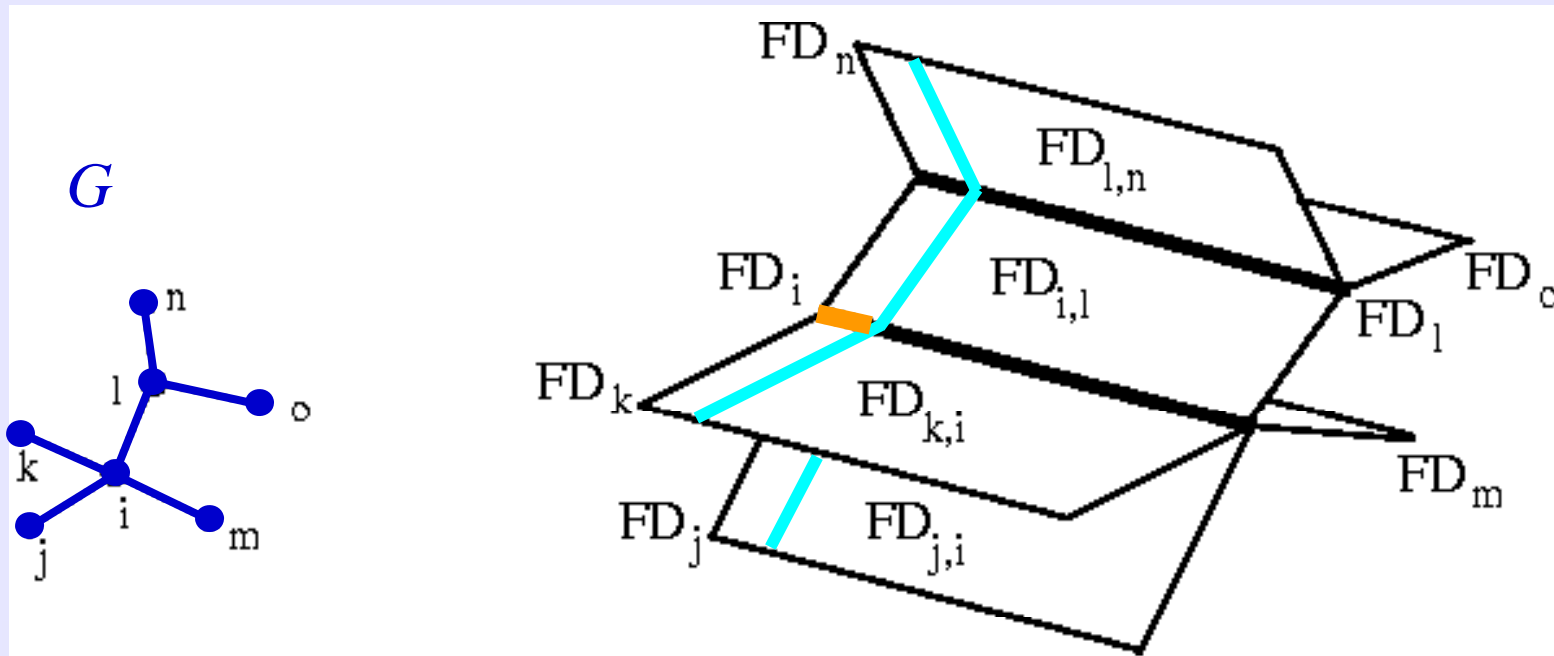
Maintaining reachable points



- During sweep:

Maintain **points** on free space surface, up to the sweepline, that can be reached by some monotone path from some lower left corner

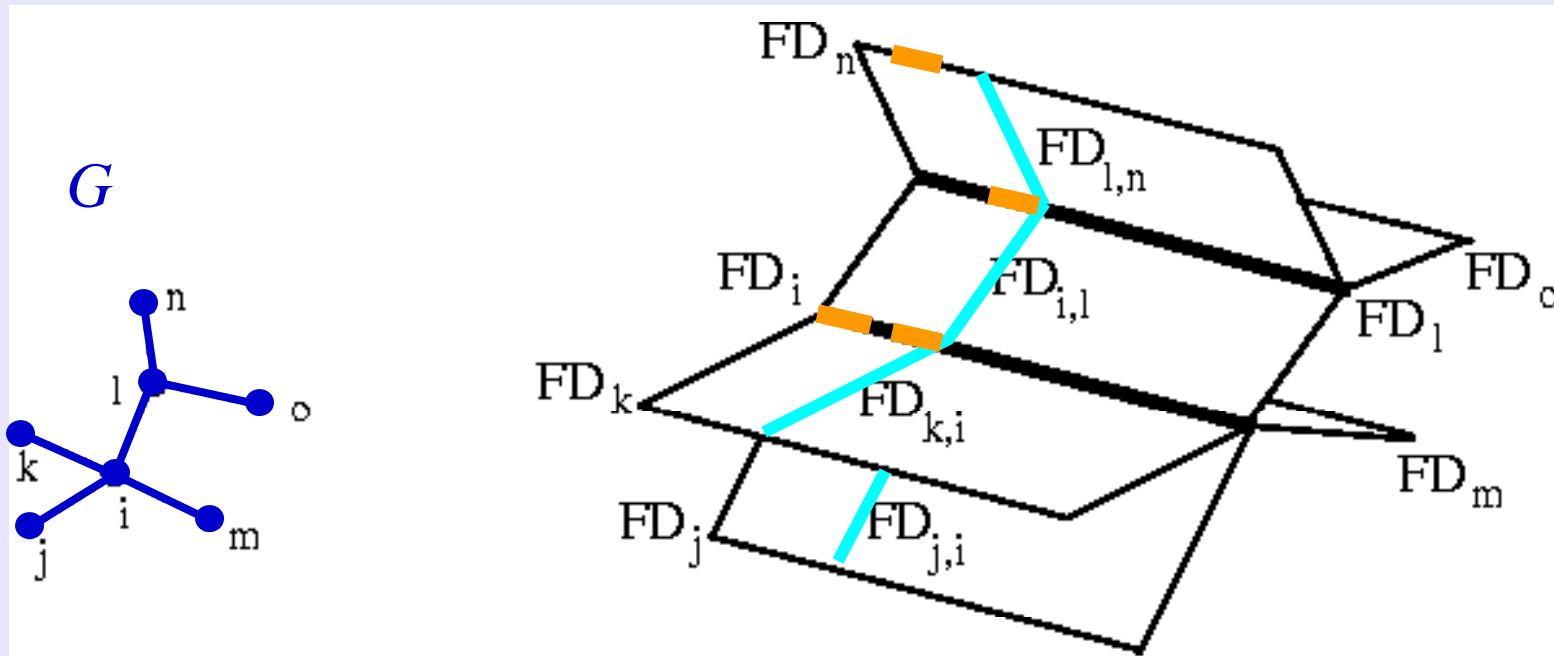
Maintaining reachable points



- During sweep:

Maintain **points** on free space surface, up to the sweep line, that can be reached by some monotone path from some lower left corner

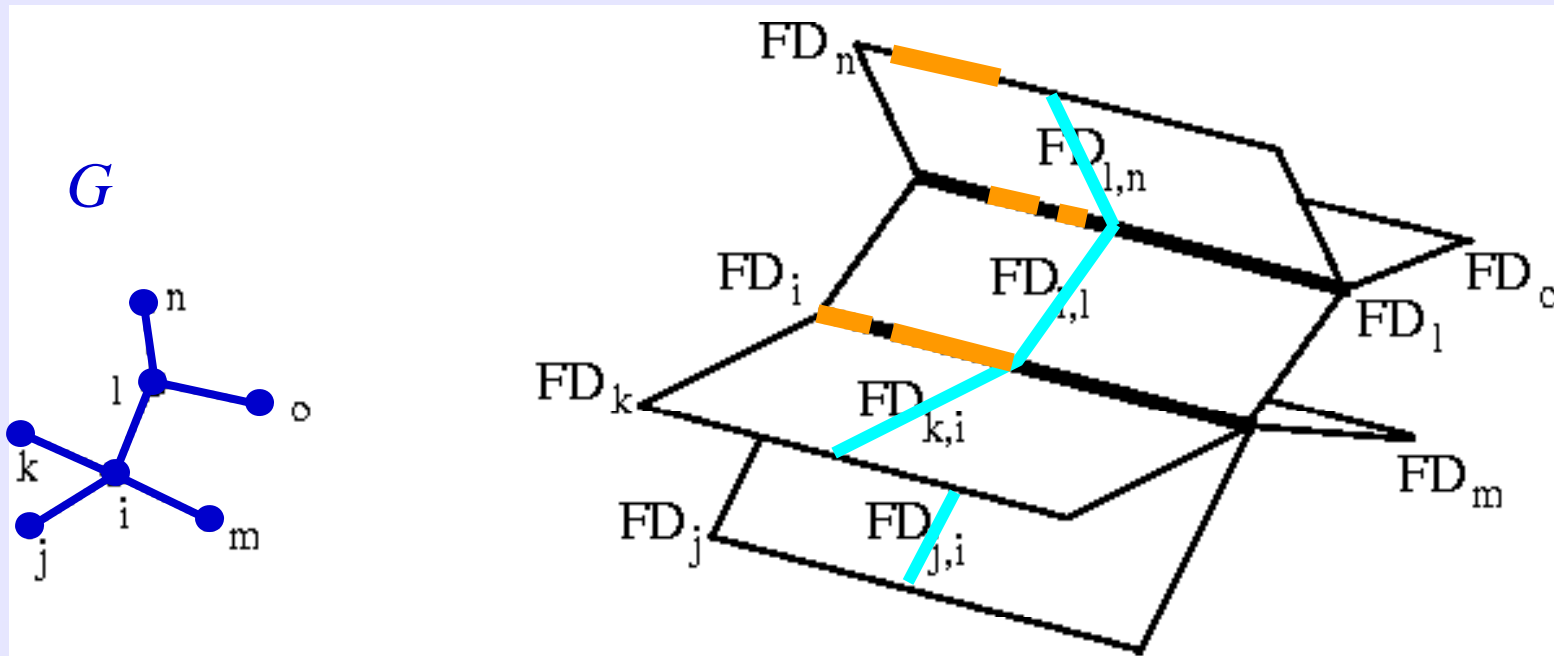
Maintaining reachable points



- During sweep:

Maintain **points** on free space surface, up to the sweepline, that can be reached by some monotone path from some lower left corner

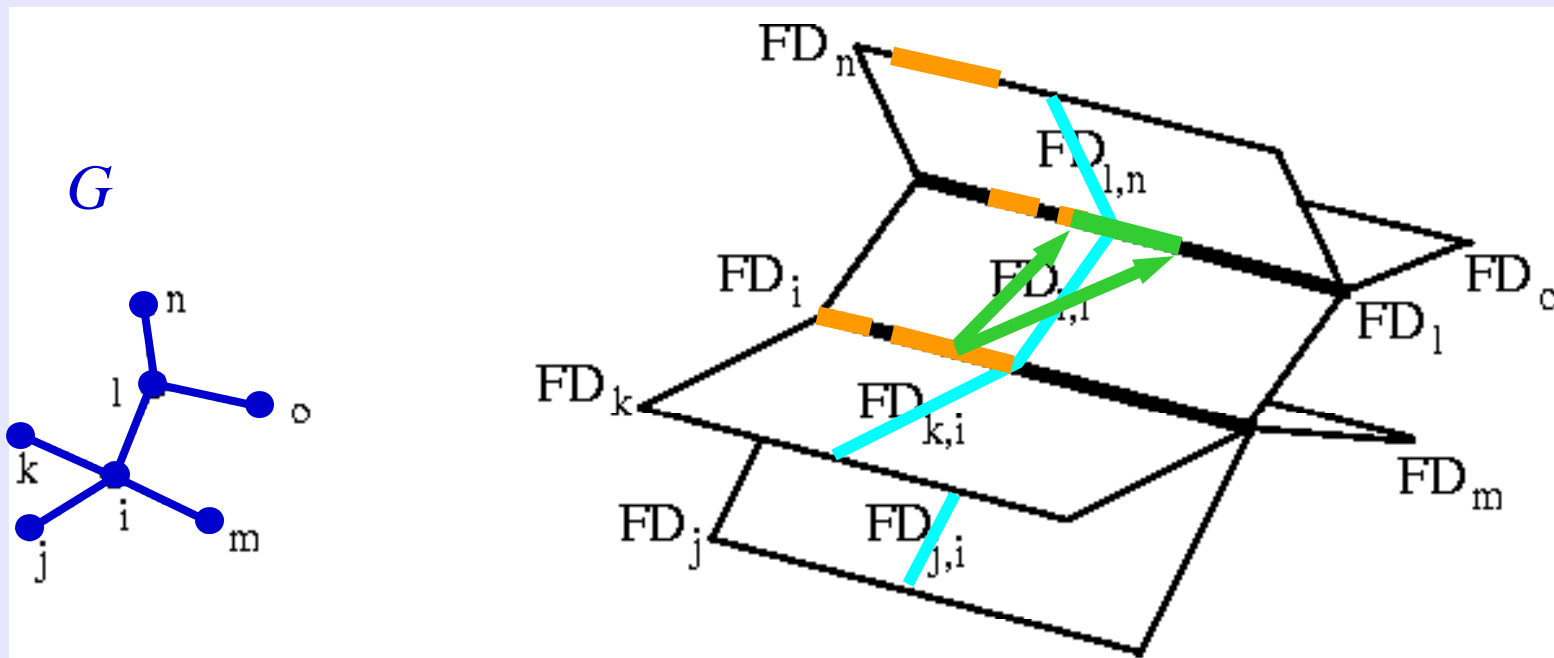
Maintaining reachable points



- During sweep:

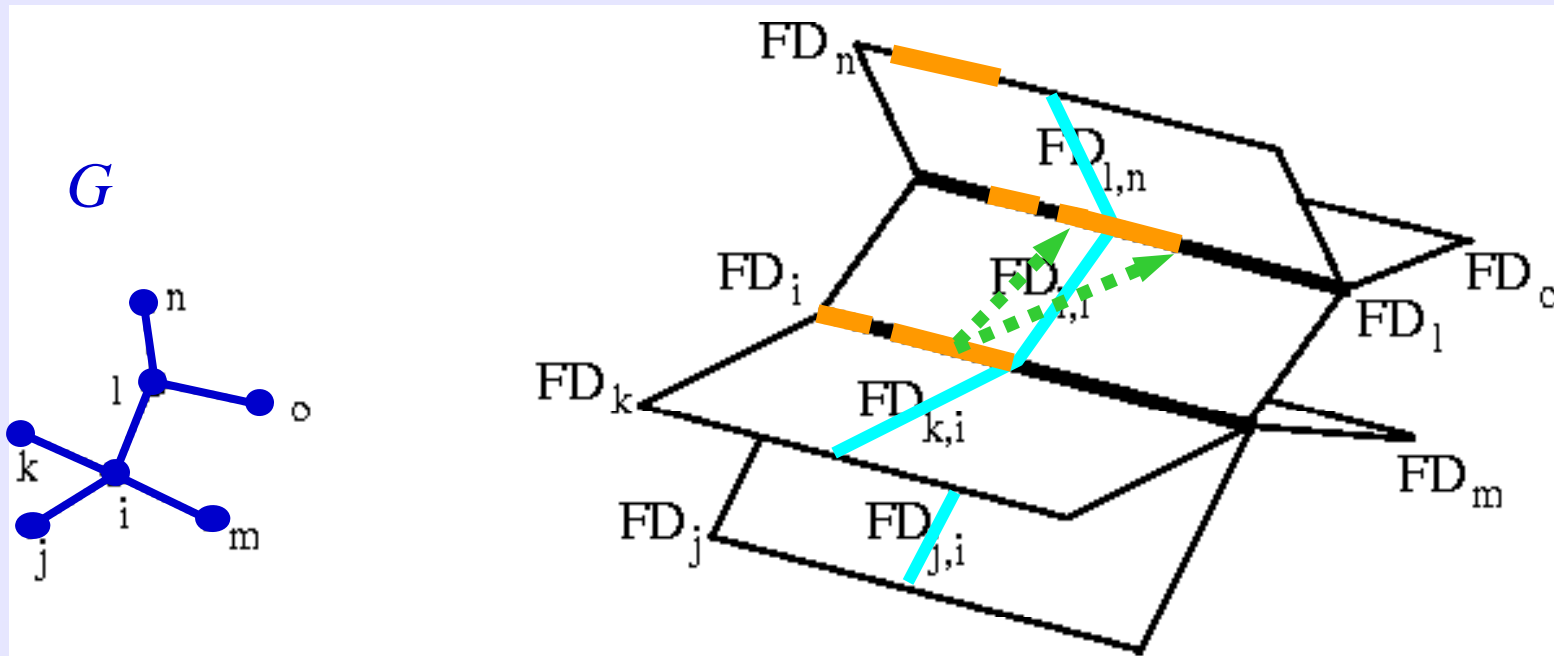
Maintain **points** on free space surface, up to the sweepline, that can be reached by some monotone path from some lower left corner

Update Dijkstra Style



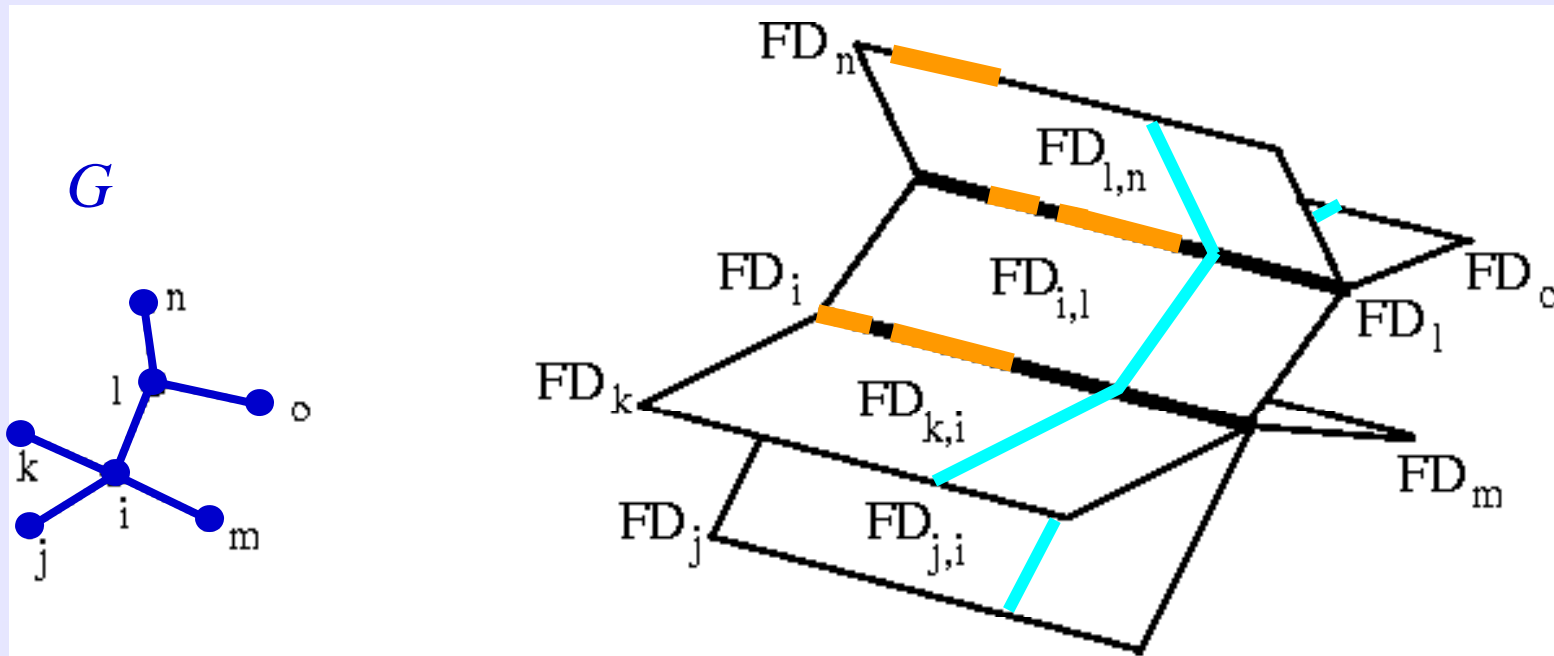
- During sweep:
 - Update reachable points Dijkstra style
 - Use data structure which supports reachability queries on the free space surface

Update Dijkstra Style



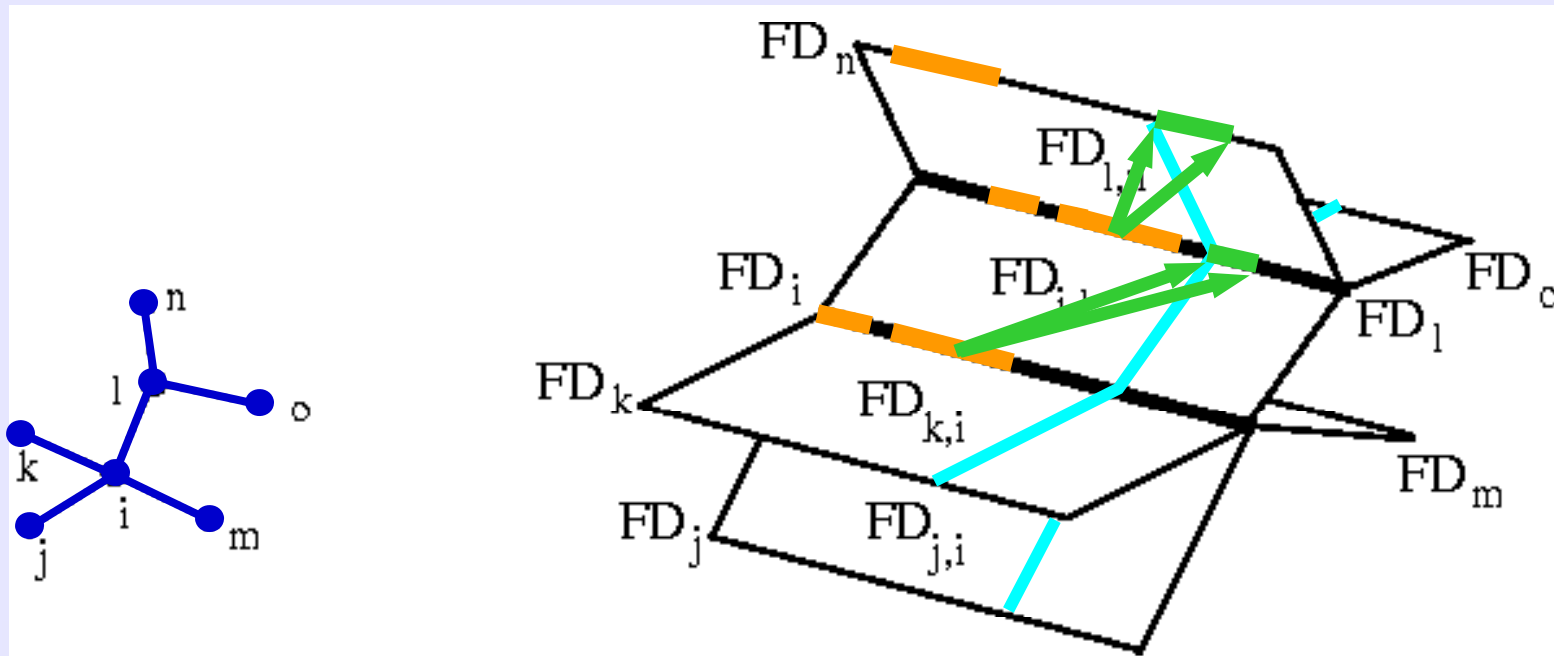
- During sweep:
 - Update reachable points Dijkstra style
 - Use data structure which supports reachability queries on the free space surface

Update Dijkstra Style



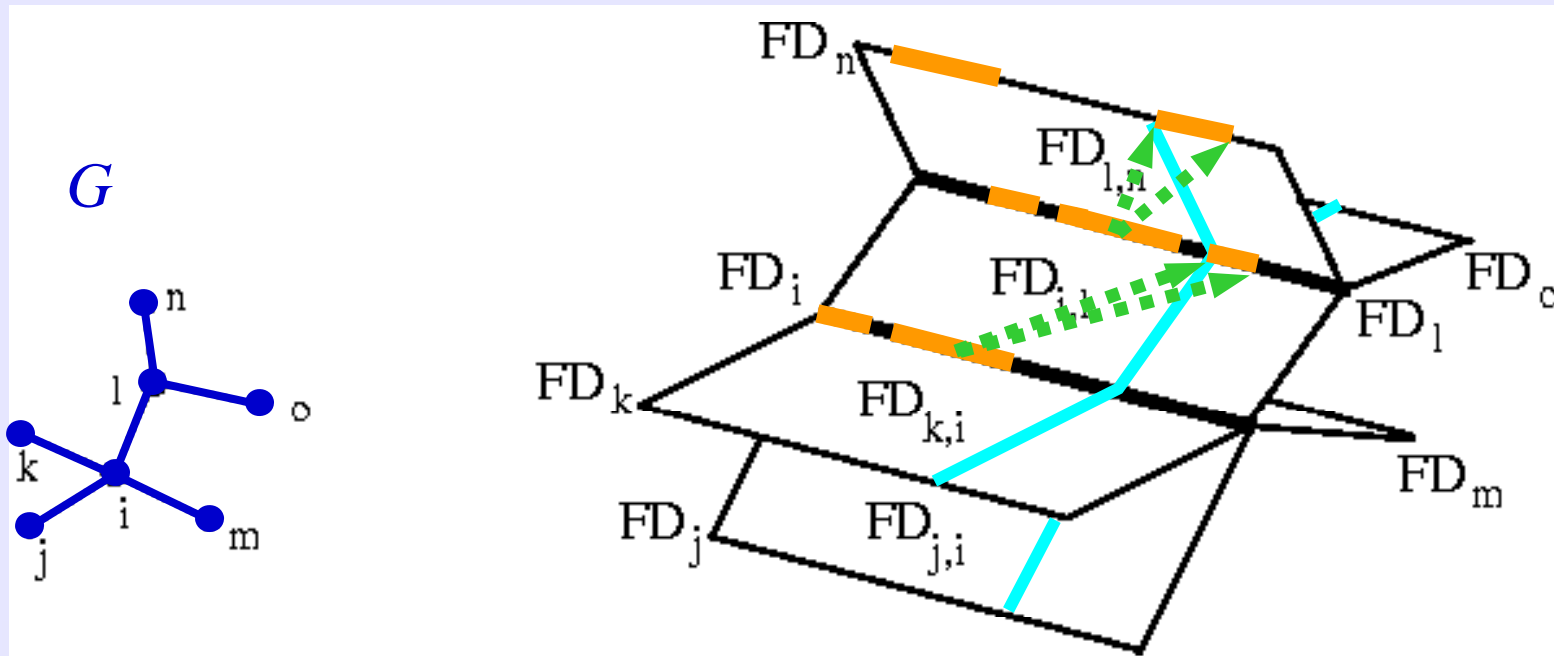
- During sweep:
 - Update reachable points Dijkstra style
 - Use data structure which supports reachability queries on the free space surface

Update Dijkstra Style



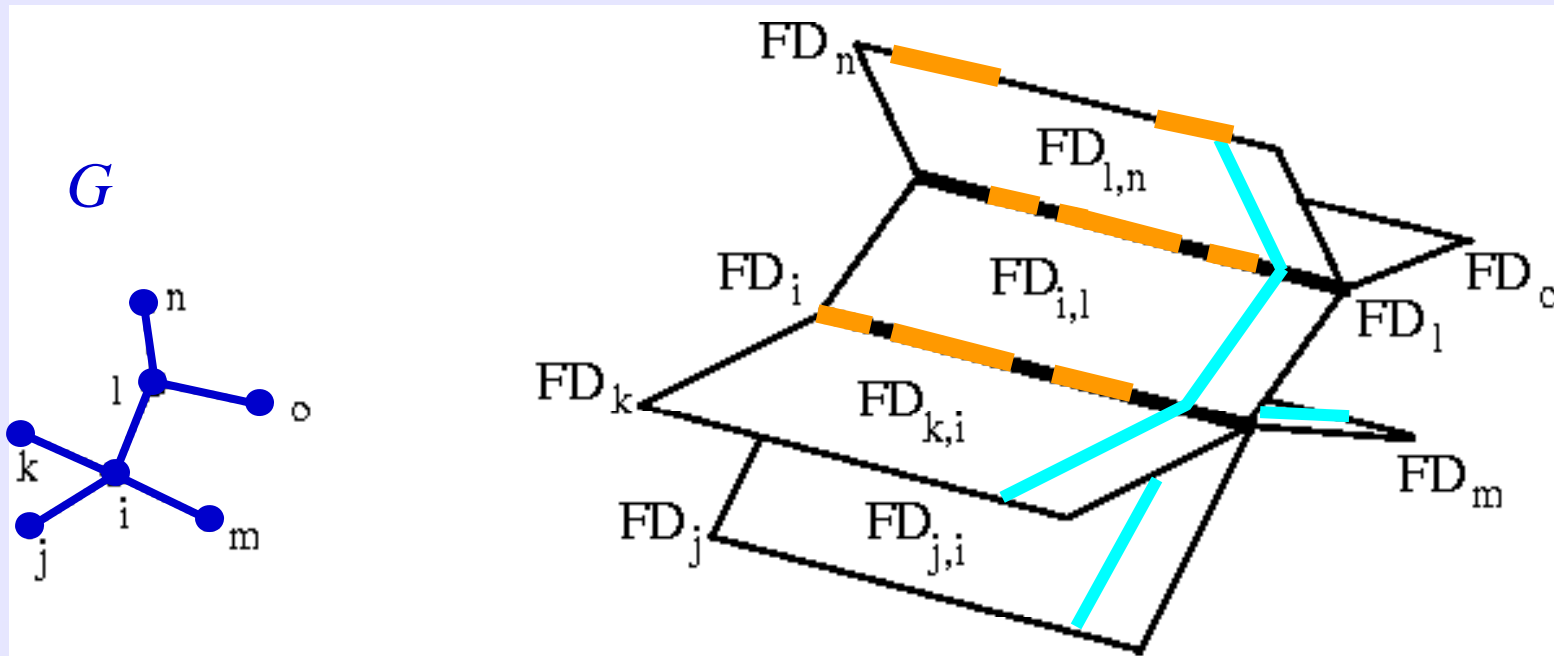
- During sweep:
 - Update reachable points Dijkstra style
 - Use data structure which supports reachability queries on the free space surface

Update Dijkstra Style



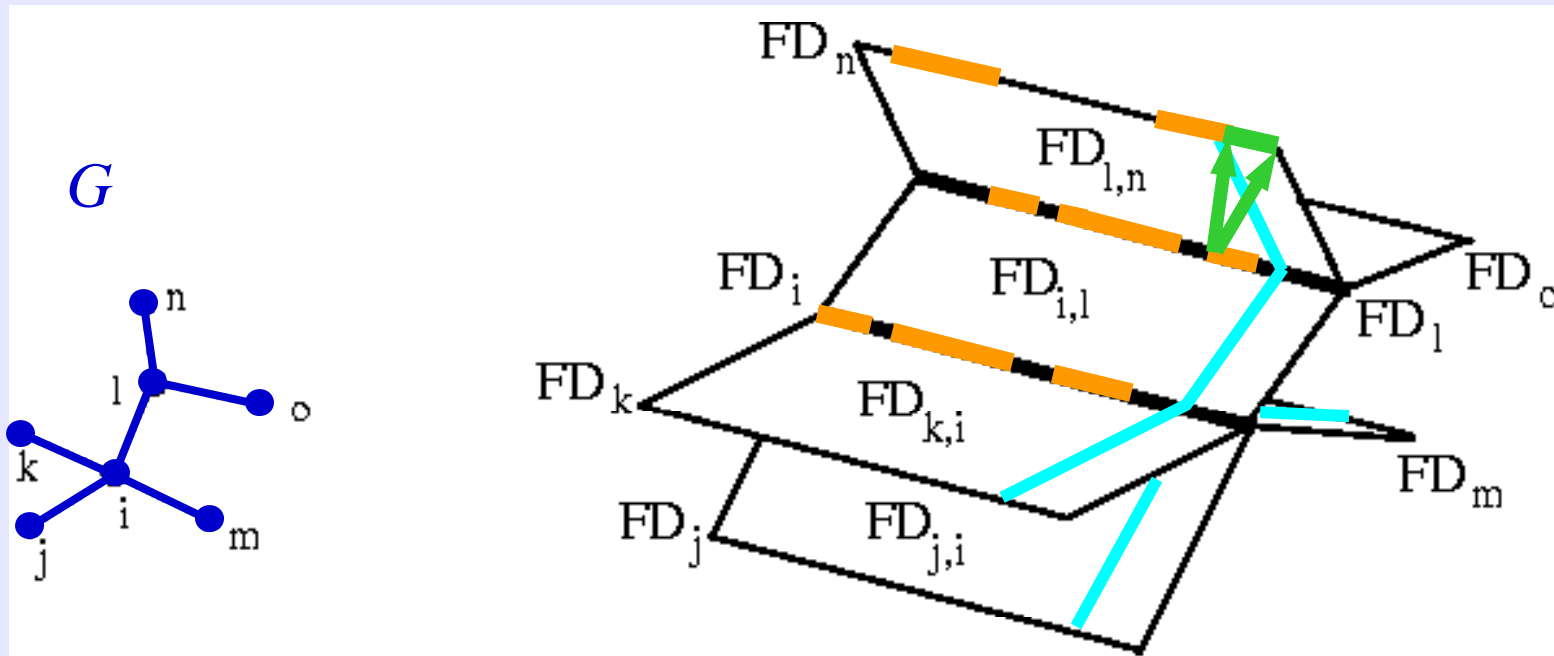
- During sweep:
 - Update reachable points Dijkstra style
 - Use data structure which supports reachability queries on the free space surface

Update Dijkstra Style



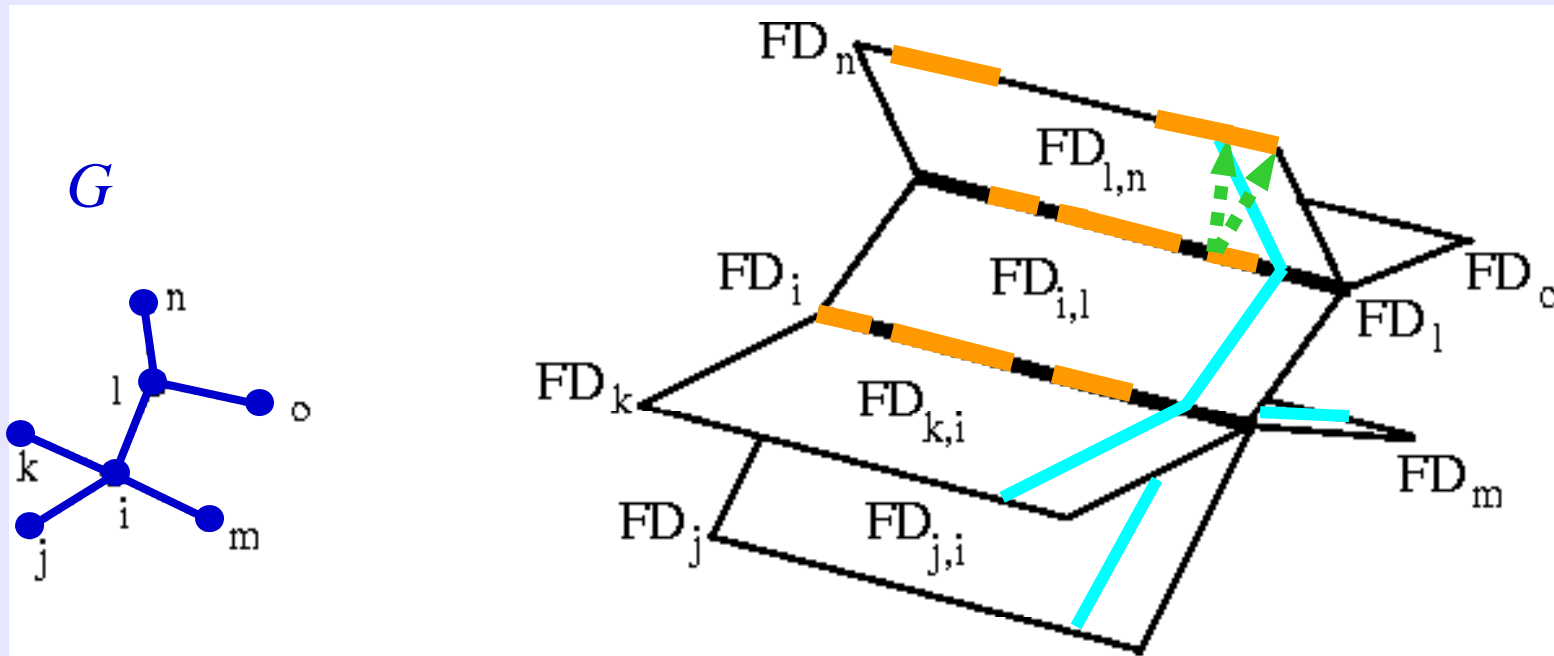
- During sweep:
 - Update reachable points Dijkstra style
 - Use data structure which supports reachability queries on the free space surface

Update Dijkstra Style



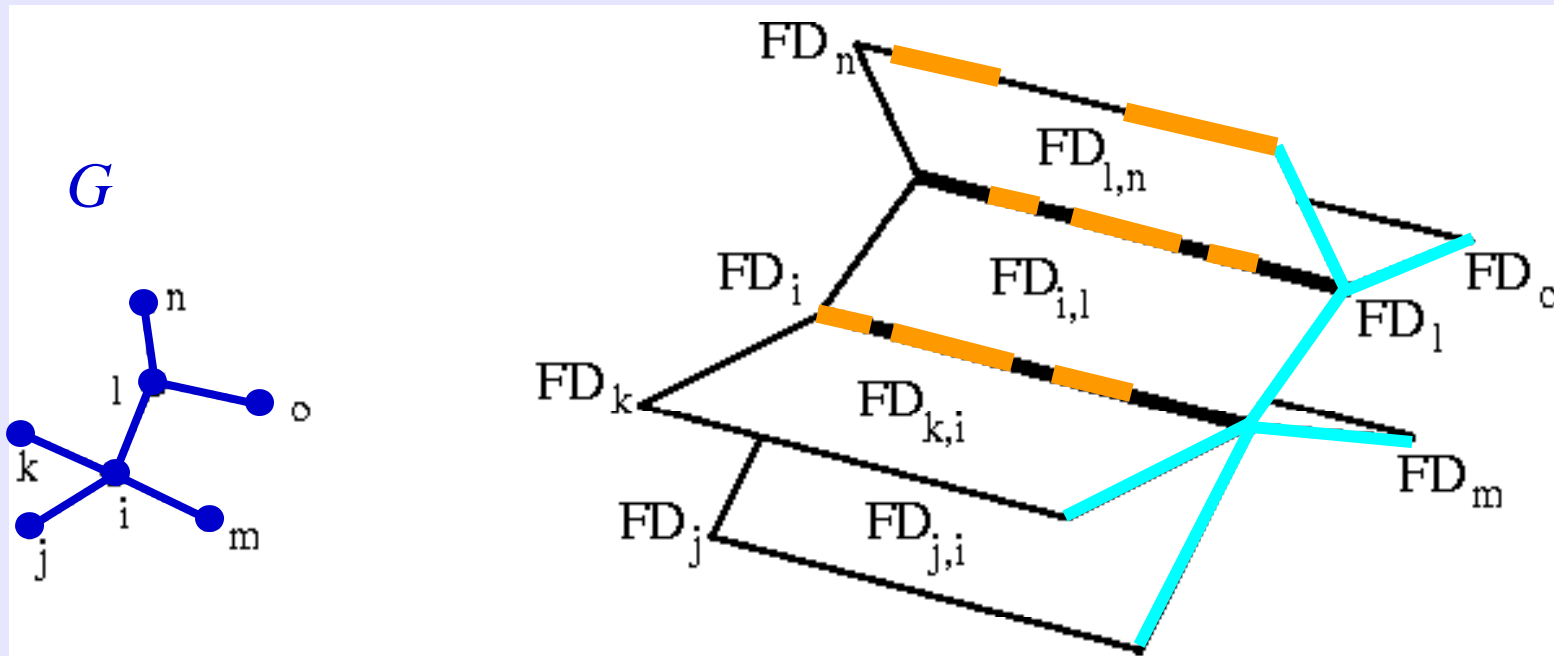
- During sweep:
 - Update reachable points Dijkstra style
 - Use data structure which supports reachability queries on the free space surface

Update Dijkstra Style



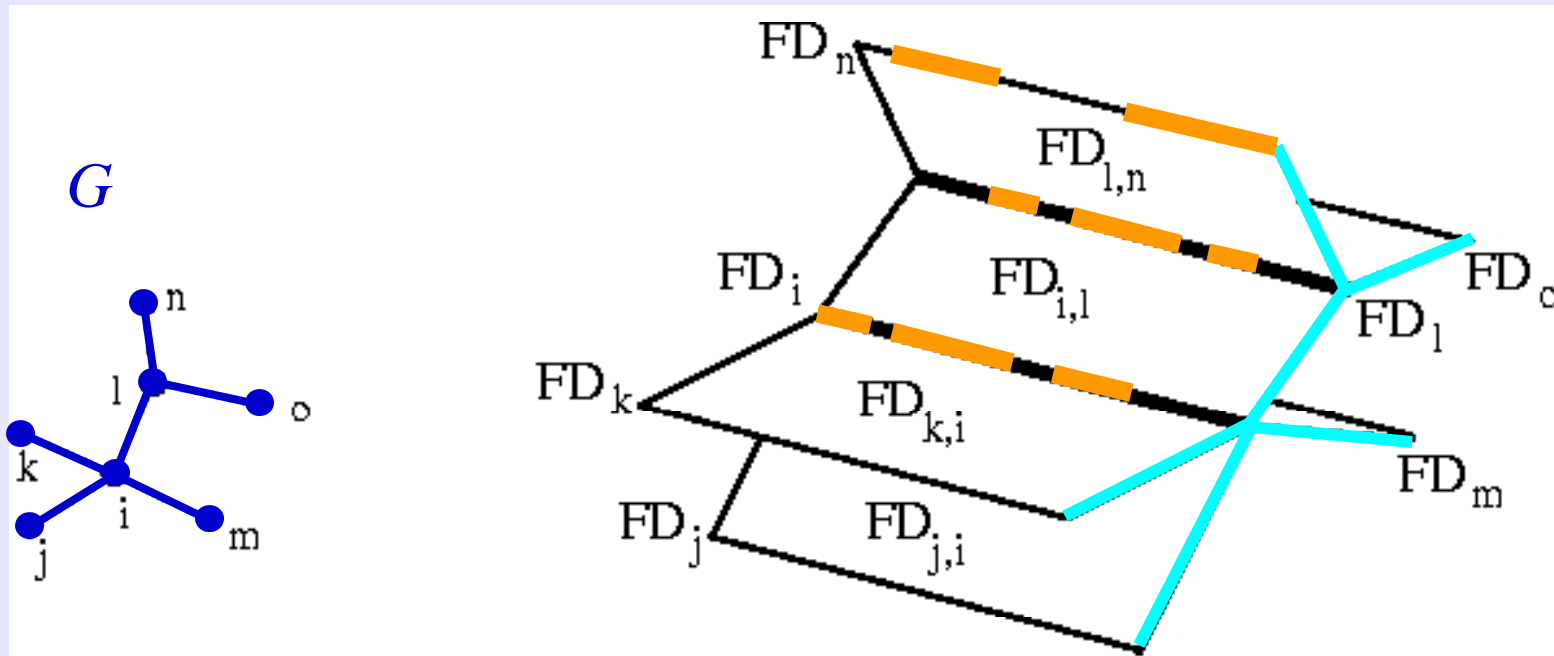
- During sweep:
 - Update reachable points Dijkstra style
 - Use data structure which supports reachability queries on the free space surface

Update Dijkstra Style



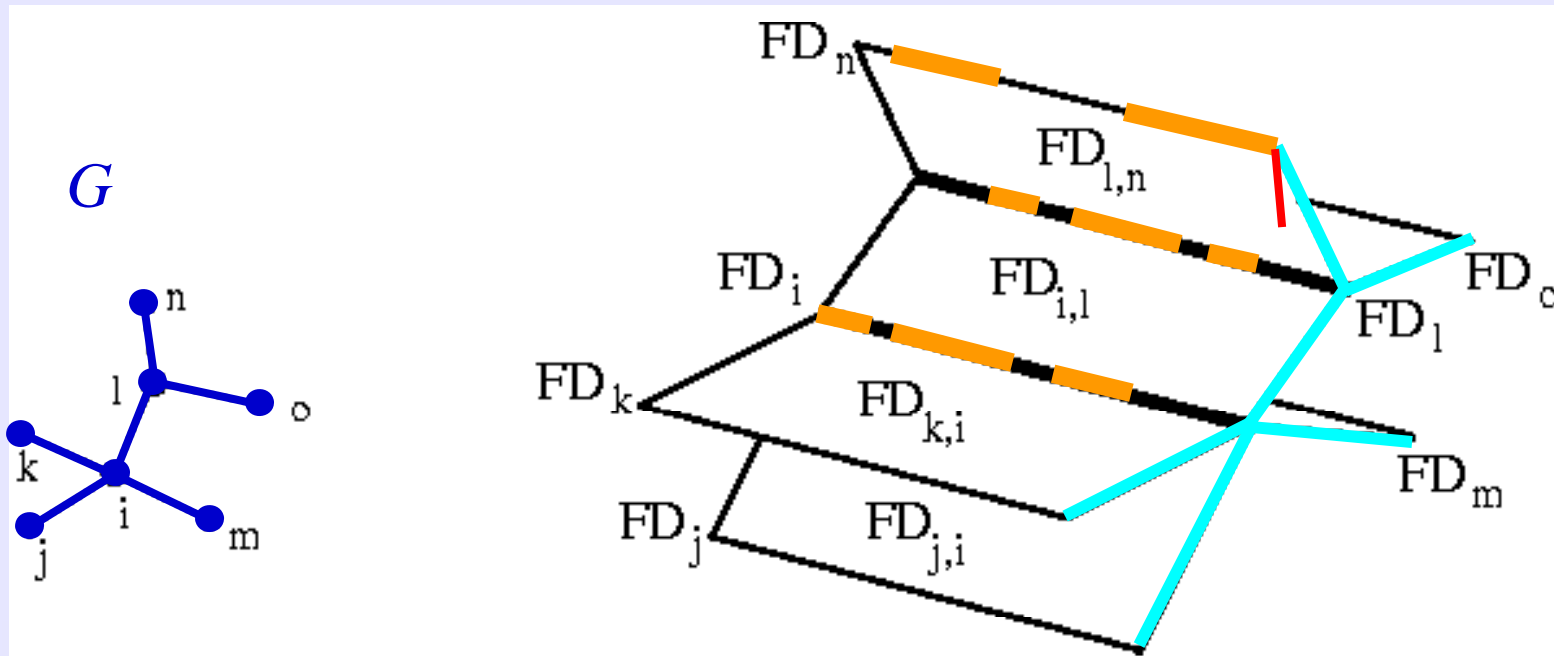
- During sweep:
 - Update reachable points Dijkstra style
 - Use data structure which supports reachability queries on the free space surface

Backtracking



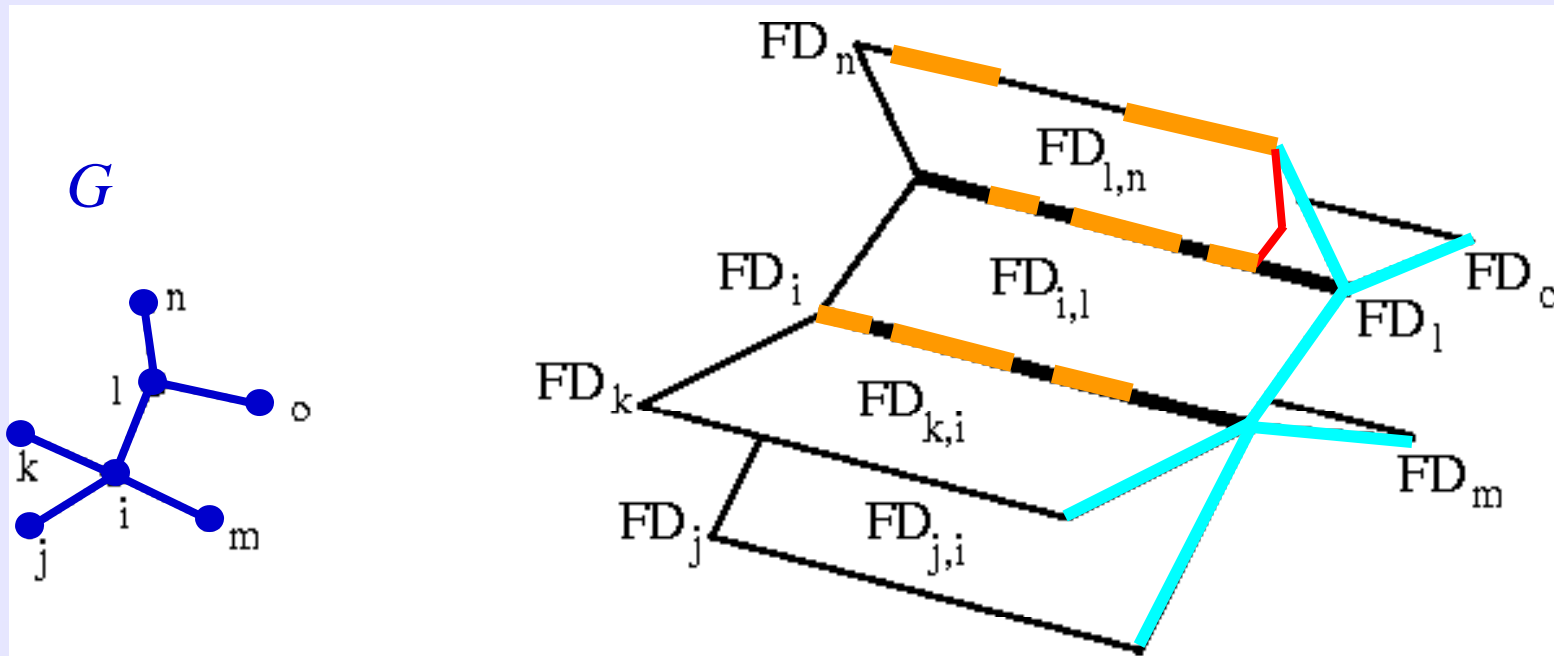
- After sweep:
 - Construct a **monotone path** by backtracking

Backtracking



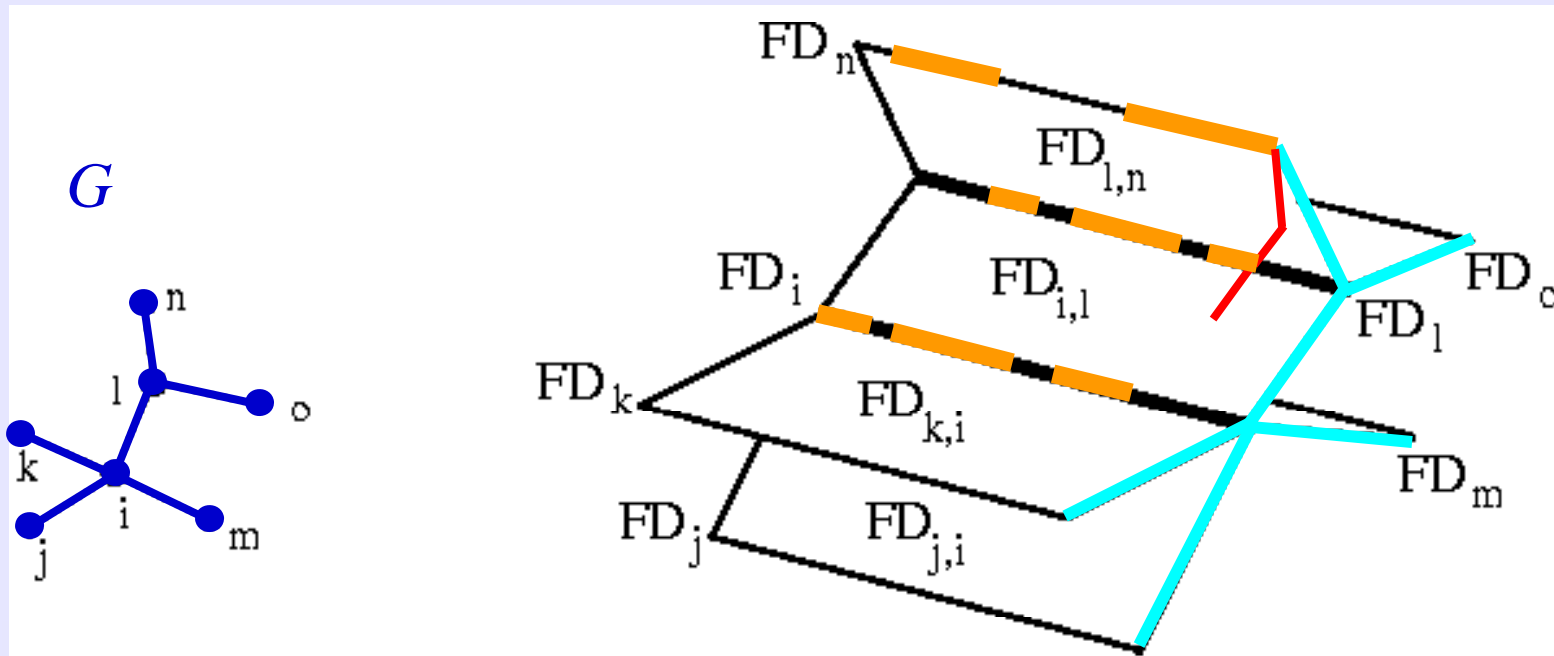
- After sweep:
 - Construct a **monotone path** by backtracking

Backtracking



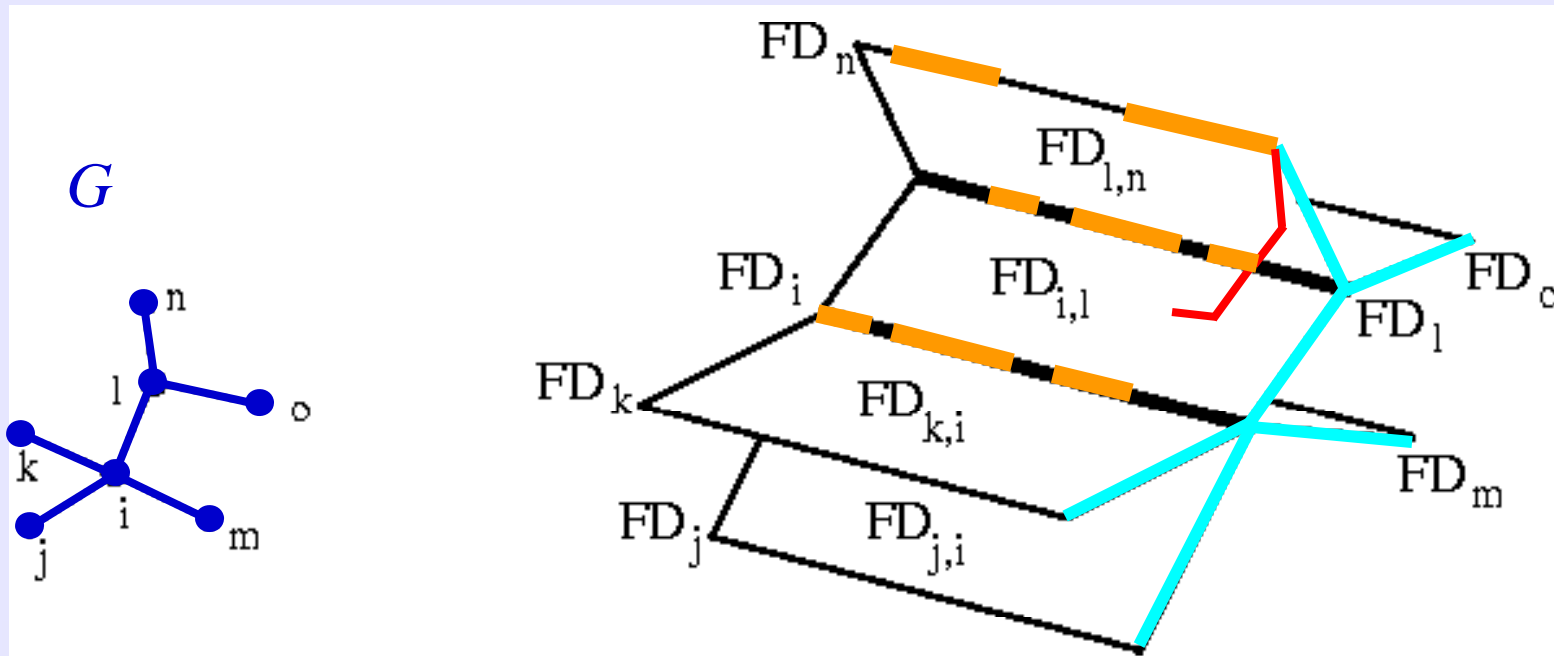
- After sweep:
 - Construct a **monotone path** by backtracking

Backtracking



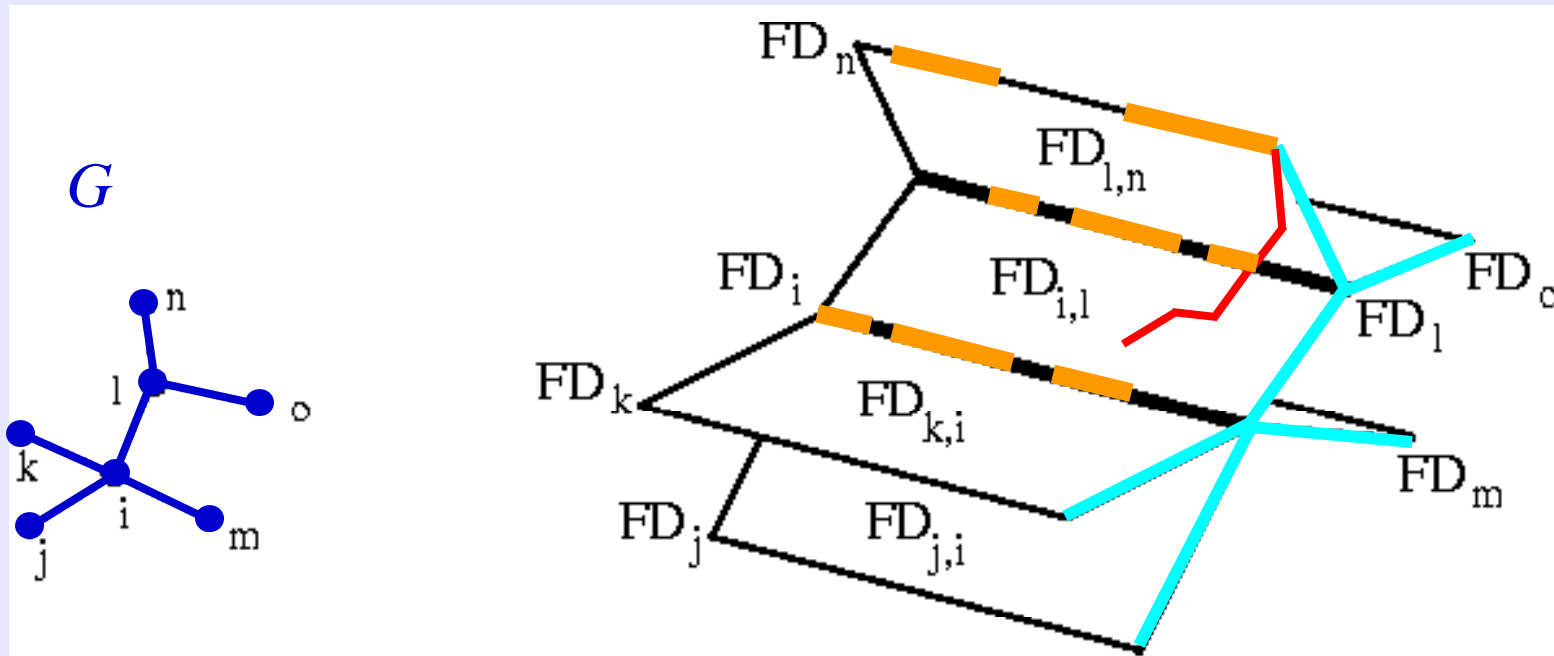
- After sweep:
 - Construct a **monotone path** by backtracking

Backtracking



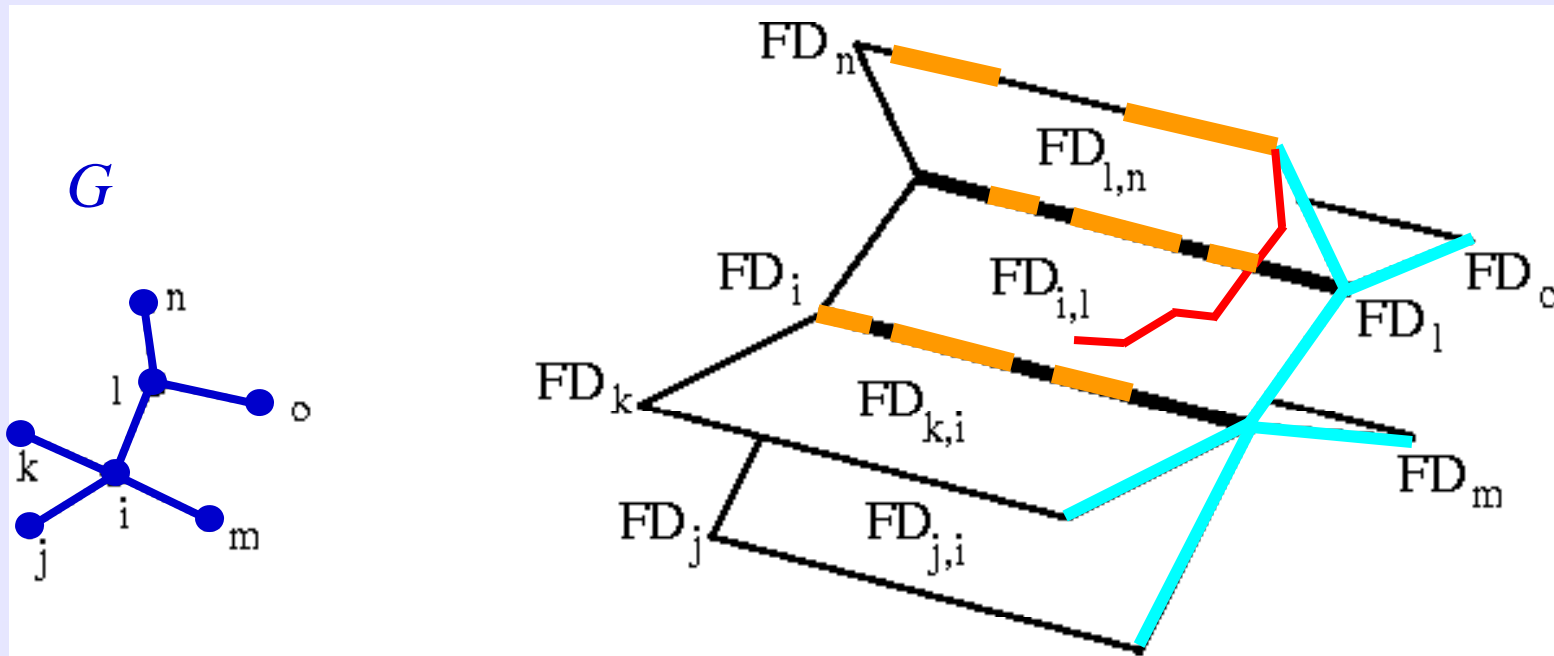
- After sweep:
 - Construct a **monotone path** by backtracking

Backtracking



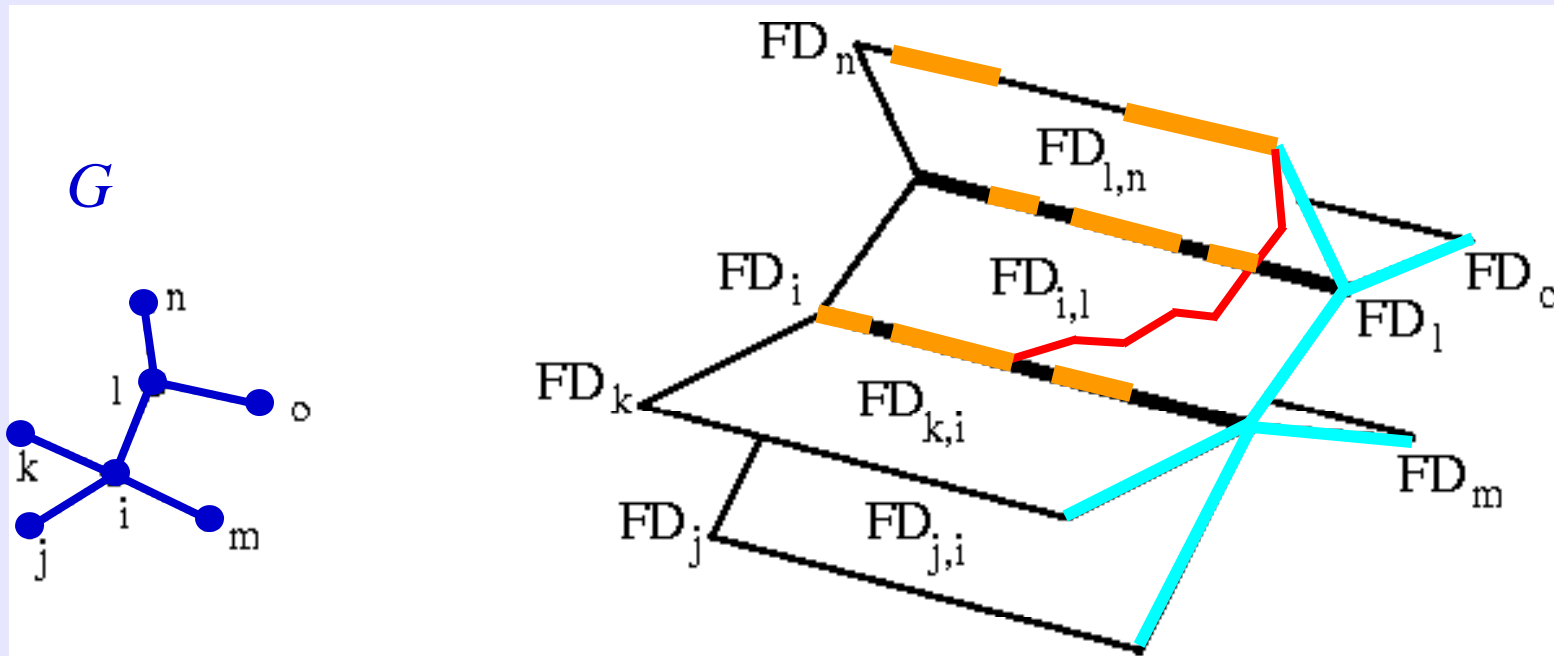
- After sweep:
 - Construct a **monotone path** by backtracking

Backtracking



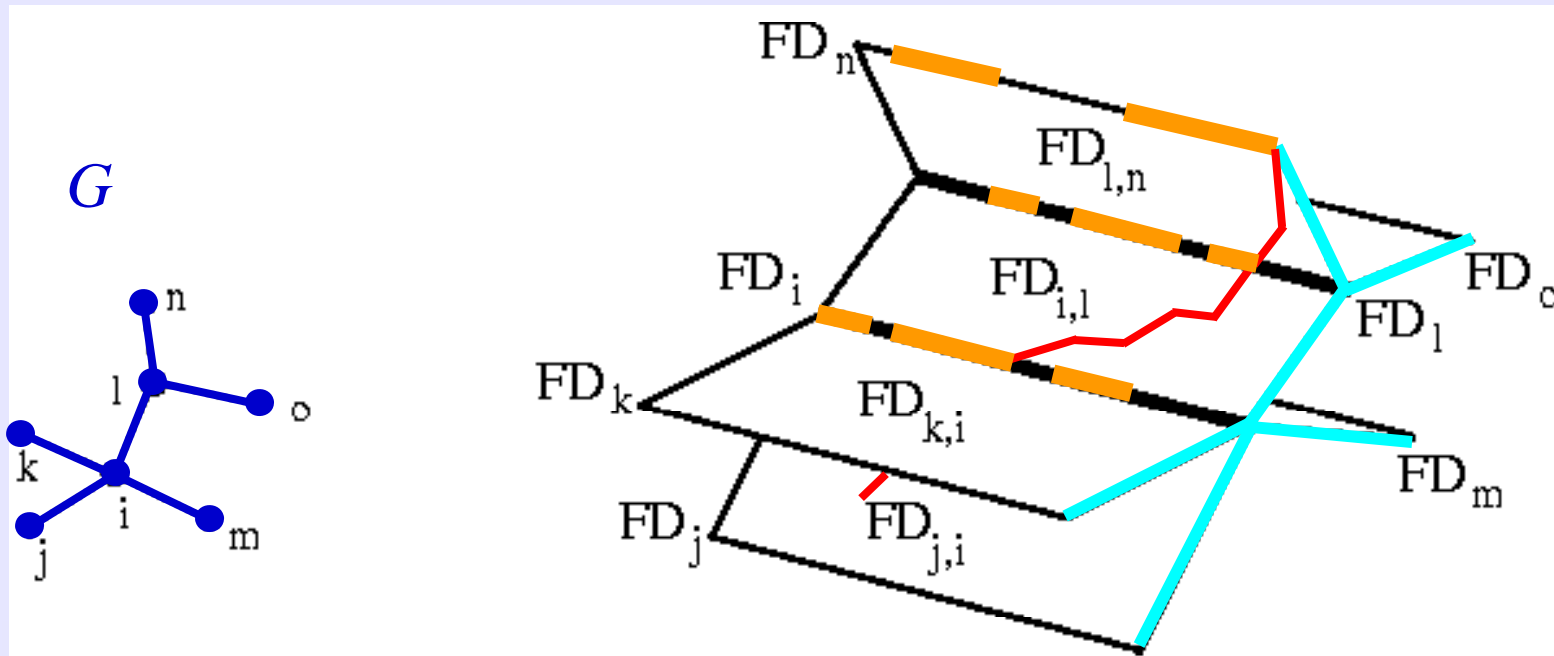
- After sweep:
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Backtracking



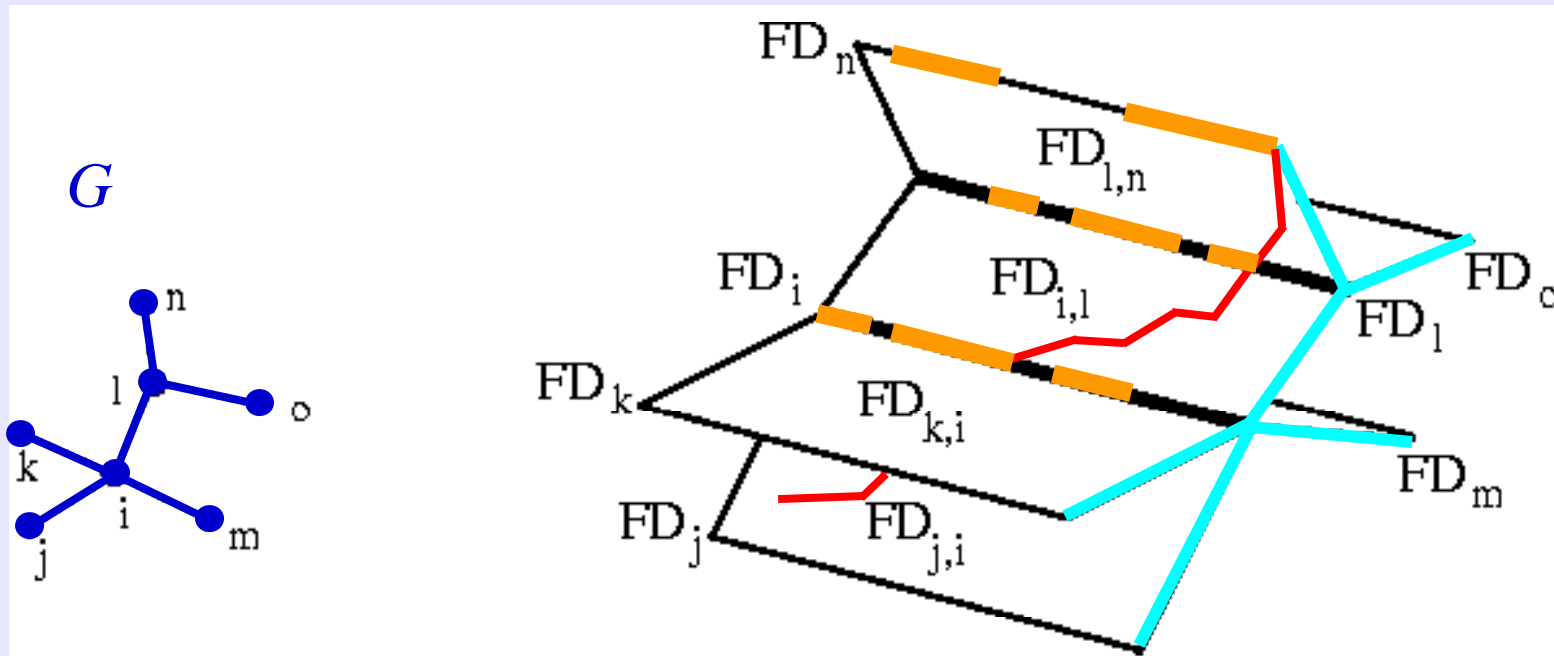
- After sweep:
 - Construct a **monotone path** by backtracking

Backtracking



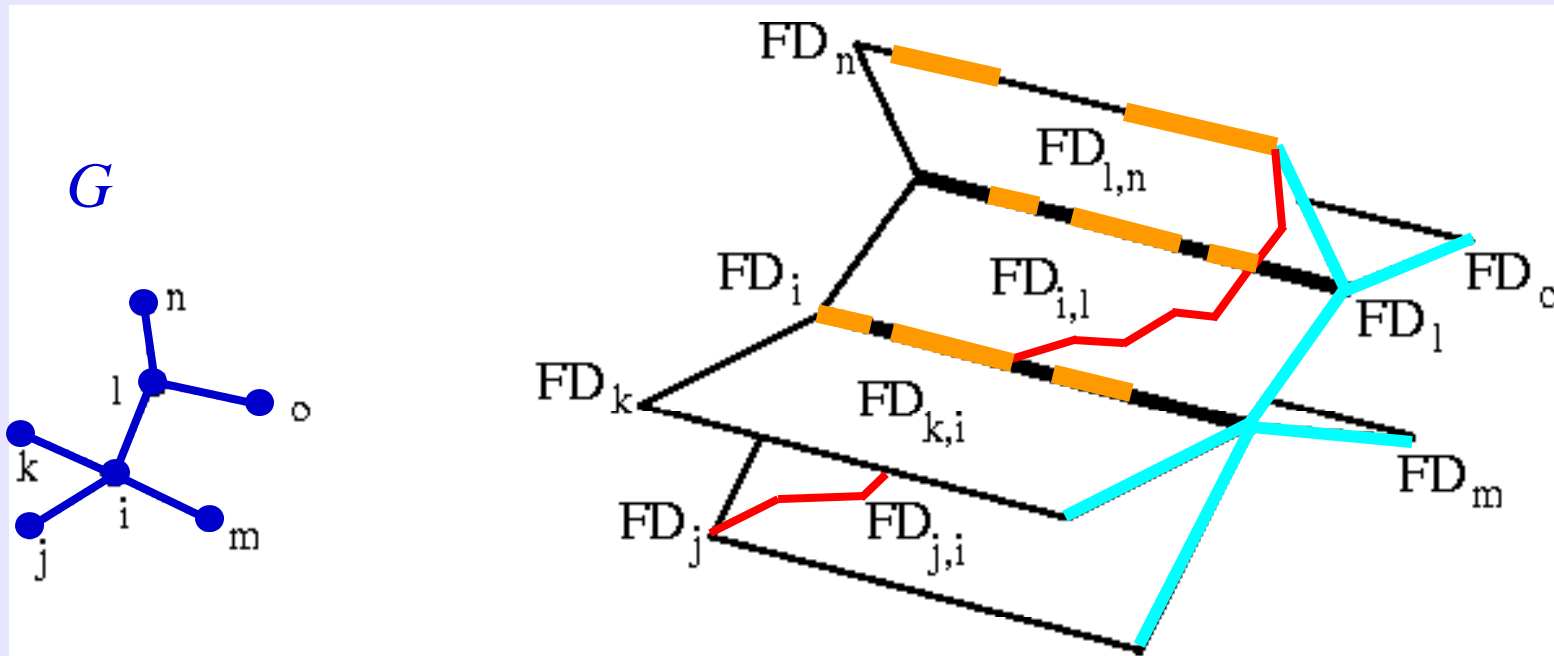
- After sweep:
 - Construct a **monotone path** by backtracking

Backtracking



- After sweep:
 - Construct a **monotone path** by backtracking

Backtracking



- After sweep:
 - Construct a **monotone path** by backtracking