

## Dynamic Programming

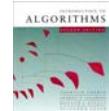
Carola Wenk

Slides courtesy of Charles Leiserson with small changes by Carola Wenk

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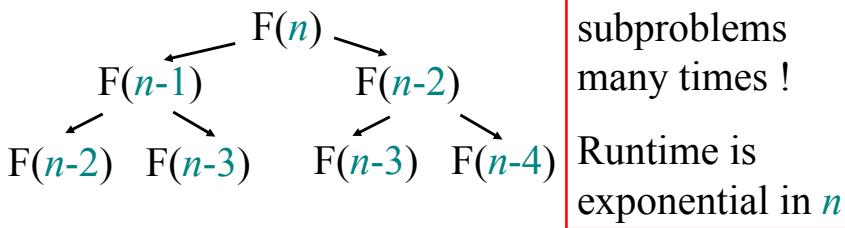
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## Example: Fibonacci numbers

- $F(0)=0; F(1)=1; F(n)=F(n-1)+F(n-2)$  for  $n \geq 2$

- Implement this recursion naively:



Solve same subproblems many times!  
Runtime is exponential in  $n$ .

- Store 1D DP-table and fill bottom-up in  $O(n)$  time:

F:	0	1	1	2	3	5	8				
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## Dynamic programming

- Algorithm design technique (like divide and conquer)
- Is a technique for solving problems that have
  - overlapping subproblems
  - and, when used for optimization, have an optimal substructure property
- **Idea:** Do not repeatedly solve the same subproblems, but solve them only once and store the solutions in a **dynamic programming table**

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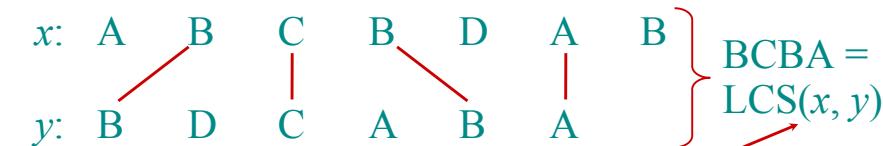


## Longest Common Subsequence

### Example: Longest Common Subsequence (LCS)

- Given two sequences  $x[1 \dots m]$  and  $y[1 \dots n]$ , find a longest subsequence common to them both.

“a” not “the”



functional notation,  
but not a function



# Brute-force LCS algorithm

Check every subsequence of  $x[1 \dots m]$  to see if it is also a subsequence of  $y[1 \dots n]$ .

## Analysis

- $2^m$  subsequences of  $x$  (each bit-vector of length  $m$  determines a distinct subsequence of  $x$ ).
- Hence, the runtime would be exponential !

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# Towards a better algorithm

## Simplification:

1. Look at the *length* of a longest-common subsequence.
2. Extend the algorithm to find the LCS itself.

**Notation:** Denote the length of a sequence  $s$  by  $|s|$ .

**Strategy:** Consider *prefixes* of  $x$  and  $y$ .

- Define  $c[i, j] = |\text{LCS}(x[1 \dots i], y[1 \dots j])|$ .
- Then,  $c[m, n] = |\text{LCS}(x, y)|$ .

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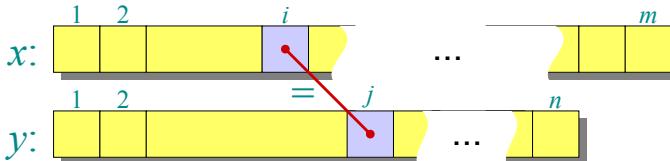


# Recursive formulation

## Theorem.

$$c[i, j] = \begin{cases} c[i-1, j-1] + 1 & \text{if } x[i] = y[j], \\ \max \{c[i-1, j], c[i, j-1]\} & \text{otherwise.} \end{cases}$$

**Proof.** Case  $x[i] = y[j]$ :



Let  $z[1 \dots k] = \text{LCS}(x[1 \dots i], y[1 \dots j])$ , where  $c[i, j] = k$ . Then,  $z[k] = x[i]$ , or else  $z$  could be extended. Thus,  $z[1 \dots k-1]$  is CS of  $x[1 \dots i-1]$  and  $y[1 \dots j-1]$ .



# Proof (continued)

**Claim:**  $z[1 \dots k-1] = \text{LCS}(x[1 \dots i-1], y[1 \dots j-1])$ .

Suppose  $w$  is a longer CS of  $x[1 \dots i-1]$  and  $y[1 \dots j-1]$ , that is,  $|w| > k-1$ . Then, **cut and paste**:  $w \parallel z[k]$  ( $w$  concatenated with  $z[k]$ ) is a common subsequence of  $x[1 \dots i]$  and  $y[1 \dots j]$  with  $|w \parallel z[k]| > k$ . Contradiction, proving the claim.

Thus,  $c[i-1, j-1] = k-1$ , which implies that  $c[i, j] = c[i-1, j-1] + 1$ .

Other cases are similar. □



# Dynamic-programming hallmark #1

## Optimal substructure

An optimal solution to a problem (instance) contains optimal solutions to subproblems.

→ Recurrence

If  $z = \text{LCS}(x, y)$ , then any prefix of  $z$  is an LCS of a prefix of  $x$  and a prefix of  $y$ .

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# Recursive algorithm for LCS

$\text{LCS}(x, y, i, j)$

if  $x[i] = y[j]$

then  $c[i, j] \leftarrow \text{LCS}(x, y, i-1, j-1) + 1$

else  $c[i, j] \leftarrow \max \{ \text{LCS}(x, y, i-1, j), \text{LCS}(x, y, i, j-1) \}$

**Worst-case:**  $x[i] \neq y[j]$ , in which case the algorithm evaluates two subproblems, each with only one parameter decremented.

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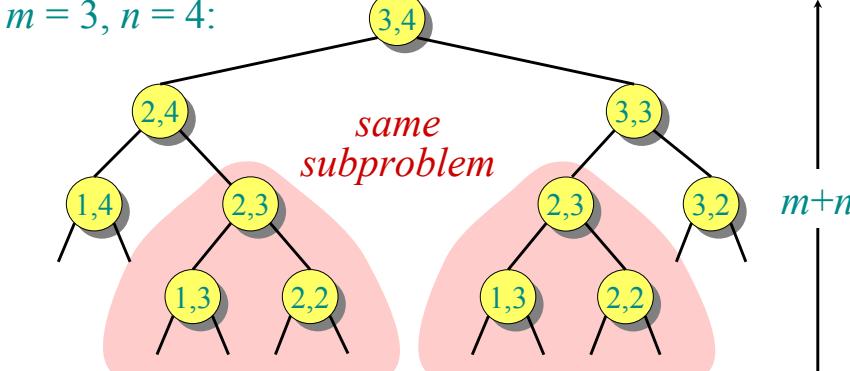
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# Recursion tree



Height =  $m + n \Rightarrow$  work potentially exponential, but we're solving subproblems already solved!



# Dynamic-programming hallmark #2

## Overlapping subproblems

A recursive solution contains a “small” number of distinct subproblems repeated many times.

The number of distinct LCS subproblems for two strings of lengths  $m$  and  $n$  is only  $mn$ .

# Memoization algorithm

**Memoization:** After computing a solution to a subproblem, store it in a table. Subsequent calls check the table to avoid redoing work.

$\text{LCS}(x, y, i, j)$

if  $c[i, j] = \text{NIL}$

then if  $x[i] = y[j]$

then  $c[i, j] \leftarrow \text{LCS}(x, y, i-1, j-1) + 1$  } same  
else  $c[i, j] \leftarrow \max \{ \text{LCS}(x, y, i-1, j),$   
 $\text{LCS}(x, y, i, j-1) \}$  } as before

Time =  $\Theta(mn)$  = constant work per table entry.  
Space =  $\Theta(mn)$ .

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# Memoization

$x: A$	1 B	2 C	3 B	4 D	5 A	6 B	7 B
$y: 0$	0	0	0	0	0	0	0
1 B	0	0	1	1	nil	nil	nil
2 D	0	0	1	nil	nil	2	nil
3 C	0	nil	nil	nil	nil	nil	nil
4 A	0	nil	nil	nil	nil	nil	nil
5 B	0	nil	nil	nil	nil	nil	nil
6 A	0	nil	nil	nil	nil	nil	nil

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# Bottom-up dynamic-programming algorithm

**IDEA:**

Compute the table bottom-up.

Time =  $\Theta(mn)$ .

	A	B	C	B	D	A	B
A	0	0	0	0	0	0	0
B	0	0	1	1	1	1	1
D	0	0	1	1	2	2	2
C	0	0	1	2	2	2	2
A	0	1	1	2	2	3	3
B	0	1	2	2	3	3	4
A	0	1	2	2	3	3	4



# Bottom-up dynamic-programming algorithm

**IDEA:**

Compute the table bottom-up.

Time =  $\Theta(mn)$ .

Reconstruct LCS by back-tracing.

Space =  $\Theta(mn)$ .

Exercise:  
 $O(\min\{m, n\})$ .

	A	B	C	B	D	A	B
B	0	0	0	0	0	0	0
D	0	0	1	1	1	2	2
C	0	0	1	2	2	2	2
A	0	1	1	2	2	3	3
B	0	1	2	2	3	3	4
A	0	1	2	2	3	3	4