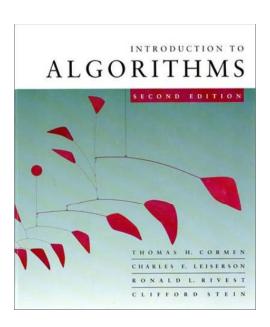


#### **CS** 3343 – Fall 2011



#### More on Shortest Paths

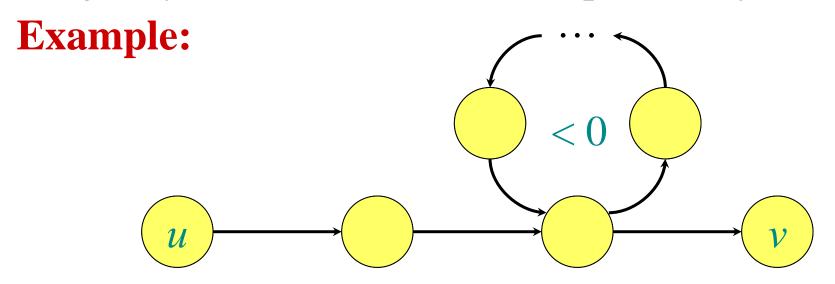
#### Carola Wenk

Slides courtesy of Charles Leiserson with small changes by Carola Wenk

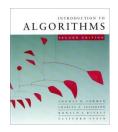


## Negative-weight cycles

**Recall:** If a graph G = (V, E) contains a negative-weight cycle, then some shortest paths may not exist.



**Bellman-Ford algorithm:** Finds all shortest-path weights from a **source**  $s \in V$  to all  $v \in V$  or determines that a negative-weight cycle exists.



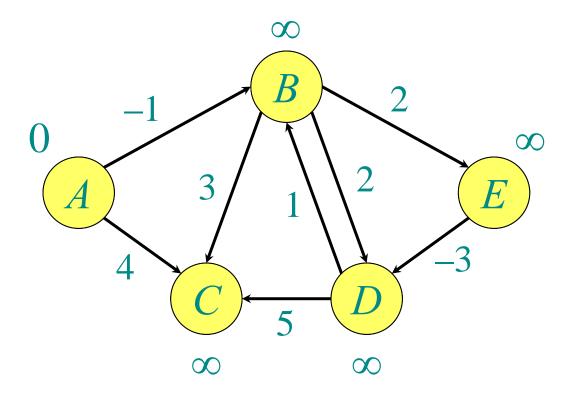
## Bellman-Ford algorithm

```
for i \leftarrow 1 to |V| - 1 do
  for each edge (u, v) \in E do
    if d[v] > d[u] + w(u, v) then d[v] \leftarrow d[u] + w(u, v) step \pi[v] \leftarrow u
for each edge (u, v) \in E
   do if d[v] > d[u] + w(u, v)
          then report that a negative-weight cycle exists
```

At the end,  $d[v] = \delta(s, v)$ . Time = O(|V||E|).

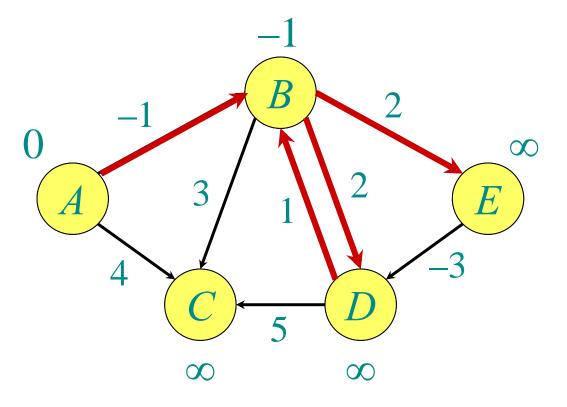
CS 3343 Analysis of Algorithms





A	B	$\boldsymbol{C}$	D	$\boldsymbol{E}$
0	$\infty$	$\infty$	$\infty$	$\infty$

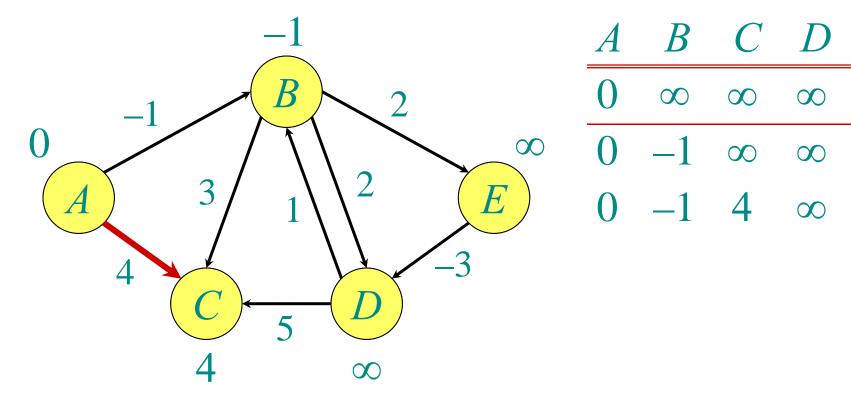




A	B	$\boldsymbol{C}$	D	$\boldsymbol{E}$
0	$\infty$	$\infty$	$\infty$	$\infty$
0	-1	$\infty$	$\infty$	$\infty$



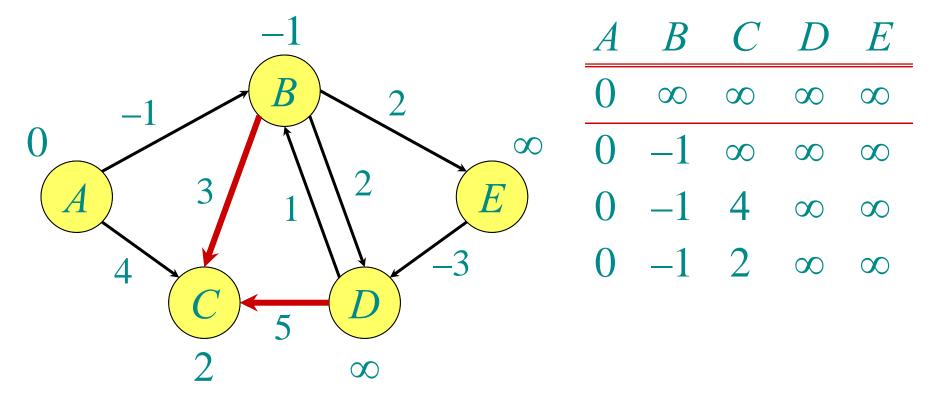
Order of edges: (B,E), (D,B), (B,D), (A,B), (A,C), (D,C), (B,C), (E,D)



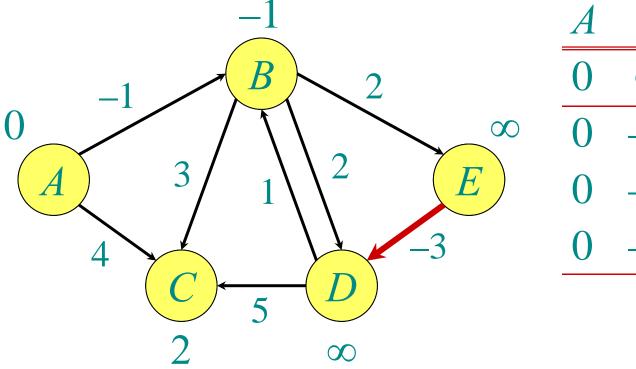
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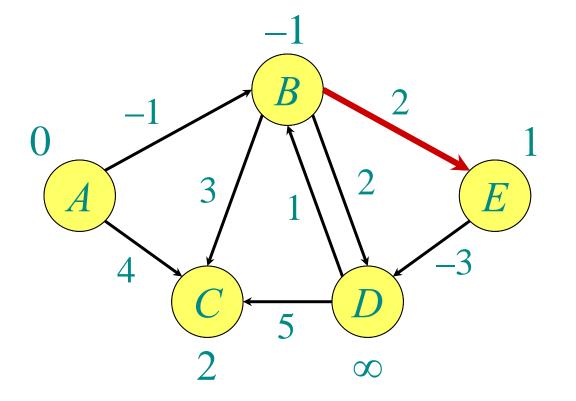






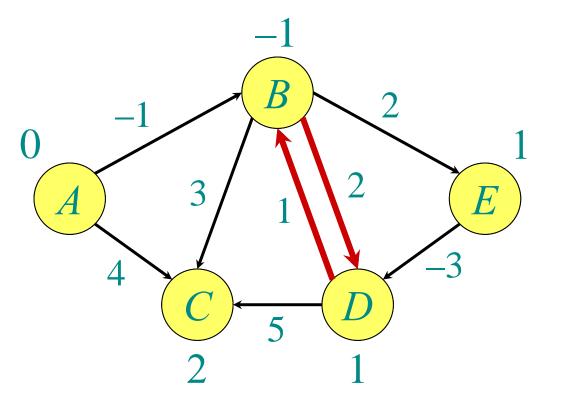
A	B	$\boldsymbol{C}$	D	$\boldsymbol{E}$
0	$\infty$	$\infty$	$\infty$	$\infty$
0	-1	$\infty$	$\infty$	$\infty$
0	-1	4	$\infty$	$\infty$
0	-1	2	$\infty$	$\infty$





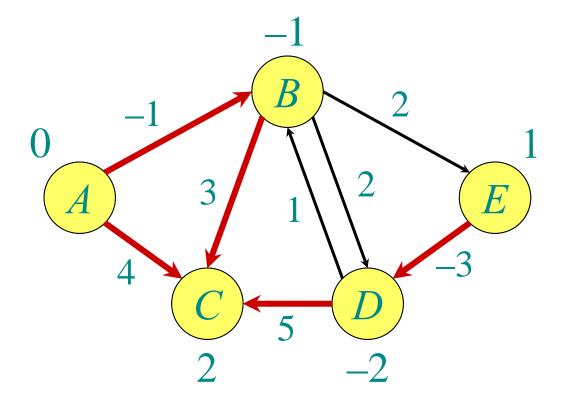
A	B	$\boldsymbol{C}$	D	$\boldsymbol{E}$
0	$\infty$	$\infty$	$\infty$	$\infty$
0	-1	$\infty$	$\infty$	$\infty$
0	<b>-1</b>	4	$\infty$	$\infty$
0	-1	2	$\infty$	$\infty$
0	-1	2	$\infty$	1





A	B	$\boldsymbol{C}$	D	E
0	$\infty$	$\infty$	$\infty$	$\infty$
0	-1	$\infty$	$\infty$	$\infty$
0	-1	4	$\infty$	$\infty$
0	-1	2	$\infty$	$\infty$
0	-1	2	$\infty$	1
0	-1	2	1	1

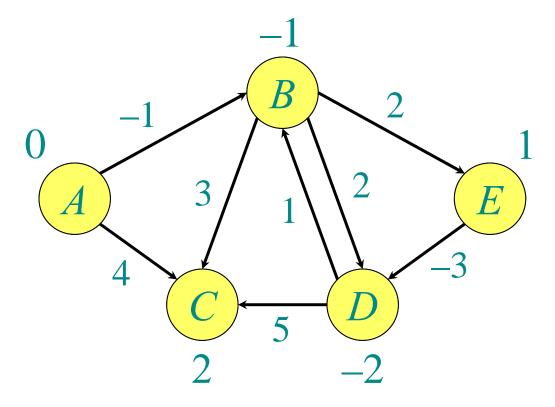




$\boldsymbol{A}$	B	$\boldsymbol{C}$	D	E
0	$\infty$	$\infty$	$\infty$	$\infty$
0	-1	$\infty$	$\infty$	$\infty$
0	-1	4	$\infty$	$\infty$
0	-1	2	$\infty$	$\infty$
0	-1	2	$\infty$	1
0	-1	2	1	1
0	-1	2	-2	1



Order of edges: (B,E), (D,B), (B,D), (A,B), (A,C), (D,C), (B,C), (E,D)



**Note:** Values decrease monotonically.

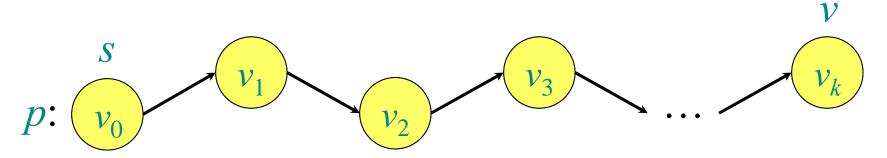
$$A \ B \ C \ D \ E$$
 $0 \ \infty \ \infty \ \infty$ 
 $0 \ -1 \ \infty \ \infty \ \infty$ 
 $0 \ -1 \ 4 \ \infty \ \infty$ 
 $0 \ -1 \ 2 \ \infty \ 1$ 
 $0 \ -1 \ 2 \ 1 \ 1$ 
 $0 \ -1 \ 2 \ -2 \ 1$ 
... and 2 more iterations



### **Correctness**

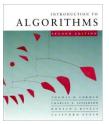
**Theorem.** If G = (V, E) contains no negative-weight cycles, then after the Bellman-Ford algorithm executes,  $d[v] = \delta(s, v)$  for all  $v \in V$ .

**Proof.** Let  $v \in V$  be any vertex, and consider a shortest path p from s to v with the minimum number of edges.

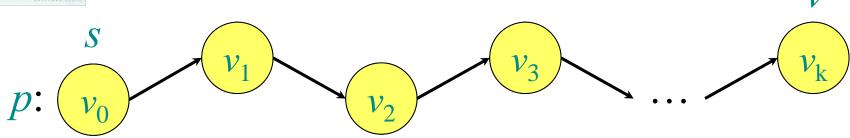


Since p is a shortest path, we have

$$\delta(s, v_i) = \delta(s, v_{i-1}) + w(v_{i-1}, v_i).$$



## **Correctness (continued)**



Initially,  $d[v_0] = 0 = \delta(s, v_0)$ , and d[s] is unchanged by subsequent relaxations.

- After 1 pass through E, we have  $d[v_1] = \delta(s, v_1)$ .
- After 2 passes through E, we have  $d[v_2] = \delta(s, v_2)$ .

• • •

• After *k* passes through *E*, we have  $d[v_k] = \delta(s, v_k)$ .

Since *G* contains no negative-weight cycles, *p* is simple. Longest simple path has  $\leq |V| - 1$  edges.



# Detection of negative-weight cycles

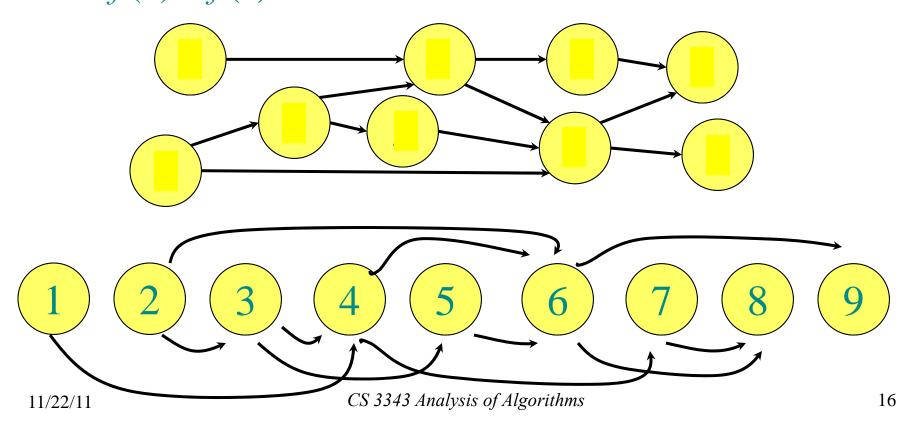
**Corollary.** If a value d[v] fails to converge after |V| - 1 passes, there exists a negative-weight cycle in G reachable from s.



#### DAG shortest paths

If the graph is a *directed acyclic graph* (*DAG*), we first *topologically sort* the vertices.

• Determine  $f: V \to \{1, 2, ..., |V|\}$  such that  $(u, v) \in E$  $\Rightarrow f(u) < f(v)$ .

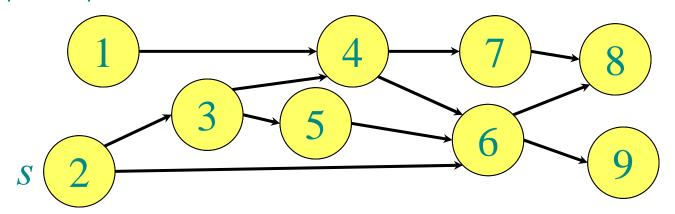




#### DAG shortest paths

If the graph is a *directed acyclic graph* (*DAG*), we first *topologically sort* the vertices.

- Determine  $f: V \to \{1, 2, ..., |V|\}$  such that  $(u, v) \in E$  $\Rightarrow f(u) < f(v)$ .
- O(|V| + |E|) time



• Walk through the vertices  $u \in V$  in this order, relaxing the edges in Adj[u], thereby obtaining the shortest paths from s in a total of O(|V| + |E|) time.



#### Shortest paths

#### **Single-source shortest paths**

- Nonnegative edge weights
  - Dijkstra's algorithm:  $O(|E| \log |V|)$
- General: Bellman-Ford: O(|V||E|)
- DAG: One pass of Bellman-Ford: O(|V| + |E|)

#### **All-pairs shortest paths**

- Nonnegative edge weights
  - Dijkstra's algorithm |V| times:  $O(|V||E|\log |V|)$
- General
  - Bellman-Ford |V| times:  $O(|V|^2|E|)$
  - Floyd-Warshall:  $O(|V|^3)$



## All-pairs shortest paths

**Input:** Digraph G = (V, E), where |V| = n, with edge-weight function  $w : E \to \mathbb{R}$ .

Output:  $n \times n$  matrix of shortest-path lengths  $\delta(i, j)$  for all  $i, j \in V$ .

#### Algorithm #1:

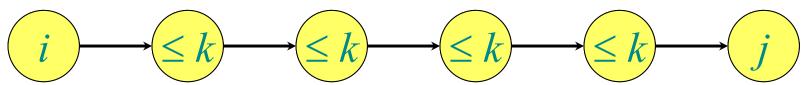
- Run Bellman-Ford once from each vertex.
- Time =  $O(|V|^2|E|)$ .
- But: Dense graph  $\Rightarrow$   $O(|V|^4)$  time.



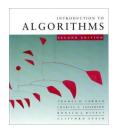
## Floyd-Warshall algorithm

- Dynamic programming algorithm.
- Assume  $V=\{1, 2, ..., n\}$ , and assume G is given in an **adjacency matrix**  $A=(a_{ij})_{1 \le i,j \le n}$  where  $a_{ij}$  is the weight of the edge from i to j.

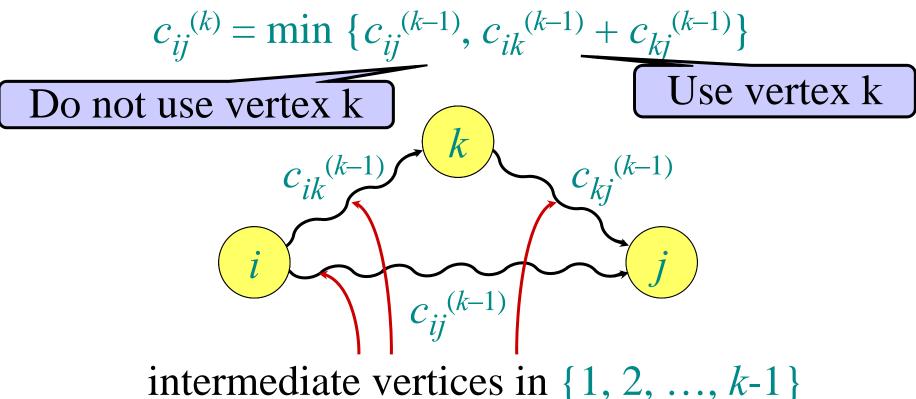
Define  $c_{ij}^{(k)}$  = weight of a shortest path from i to j with intermediate vertices belonging to the set  $\{1, 2, ..., k\}$ .



Thus,  $\delta(i, j) = c_{ij}^{(n)}$ . Also,  $c_{ij}^{(0)} = a_{ij}$ .



## Floyd-Warshall recurrence





## Pseudocode for Floyd-Warshall

```
for k \leftarrow 1 to n do

for i \leftarrow 1 to n do

for j \leftarrow 1 to n do

if c_{ij}^{(k-1)} > c_{ik}^{(k-1)} + c_{kj}^{(k-1)} then

c_{ij}^{(k)} \leftarrow c_{ik}^{(k-1)} + c_{kj}^{(k-1)} else
```

$$c_{ij}^{(k)} \leftarrow c_{ij}^{(k-1)}$$

- Runs in  $\Theta(n^3)$  time and space
- Simple to code.
- Efficient in practice.



#### **Shortest paths**

#### Single-source shortest paths

- Nonnegative edge weights
  - Dijkstra's algorithm:  $O(|E| \log |V|)$
- General: Bellman-Ford: O(|V||E|)
- DAG: One pass of Bellman-Ford: O(|V| + |E|)

#### **All-pairs shortest paths**

- Nonnegative edge weights
  - Dijkstra's algorithm |V| times:  $O(|V||E| \log |V|)$
- General
  - Bellman-Ford |V| times:  $O(|V|^2|E|)$
  - Floyd-Warshall:  $O(|V|^3)$

adj. list

adj. list

adj. matrix

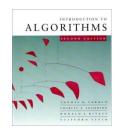


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## Johnson's algorithm

- 1. Compute a weight function  $\hat{w}$  from w such that  $\hat{w}(u, v) \ge 0$  for all  $(u, v) \in E$ . (Or determine that a negative-weight cycle exists, and stop.)
  - Can be done in O(|V||E|) time (details skipped)
- 2. Run Dijkstra's algorithm from each vertex using  $\hat{w}$ .
  - Time =  $O(|V||E|\log |V|)$ .
- 3. Reweight each shortest-path length  $\hat{w}(p)$  to produce the shortest-path lengths w(p) of the original graph.
  - Time =  $O(|V|^2)$  (details skipped)

Total time =  $O(|V||E|\log |V|)$ .



#### Shortest paths

#### **Single-source shortest paths**

- Nonnegative edge weights
  - Dijkstra's algorithm:  $O(|E| \log |V|)$
- General: Bellman-Ford: O(|V||E|)
- DAG: One pass of Bellman-Ford: O(|V| + |E|)

#### **All-pairs shortest paths**

- Nonnegative edge weights
  - Dijkstra's algorithm |V| times:  $O(|V||E| \log |V|)$
- General
  - Bellman-Ford |V| times:  $O(|V|^2|E|)$
  - Floyd-Warshall:  $O(|V|^3)$
  - Johnson's algorithm:  $O(|V| |E| \log |V|)$
- adj. list

adj. list

- adj. matrix
  - adj. list