





Augmenting Data Structures Carola Wenk

Slides courtesy of Charles Leiserson with small changes by Carola Wenk

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Dictionaries and Dynamic Sets

Abstract Data Type (ADT) Dictionary :

- Insert (x, D): inserts x into D
- Delete (x, D): deletes x from D

D is a dynamic set

Find (x, D): finds x in D

Popular implementation uses any balanced search tree (not necessarily binary). This way each operation takes $O(\log n)$ time.



Dynamic order statistics

- OS-SELECT(i, S): returns the *i*th smallest element in the dynamic set *S*.
- OS-RANK(x, S): returns the rank of $x \in S$ in the sorted order of S's elements.

IDEA: Use a red-black tree for the set *S*, but keep subtree sizes in the nodes.

Notation for nodes:





size[x] = size[left[x]] + size[right[x]] + 1

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Selection

Implementation trick: Use a *sentinel* (dummy record) for NIL such that *size*[NIL] = 0.

- OS-SELECT(x, i) $\triangleright i$ th smallest element in the subtree rooted at x
 - $k \leftarrow size[left[x]] + 1 \quad \triangleright k = rank(x)$
 - if i = k then return x
 - if i < k

then return OS-SELECT(*left*[*x*], *i*) **else return** OS-SELECT(*right*[*x*], *i* – *k*)

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(OS-RANK is in the textbook.)
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Example

OS-SELECT(*root*, 5)

OS-SELECT(x, i) > ith smallest element in the subtree rooted at x $k \leftarrow size[left[x]] + 1 > k = rank(x)$ if i = k then return xif i < kthen return OS-SELECT(left[x], i)

else return OS-SELECT(right[x], i-k) i = 5 $\bigcirc M$ k = 6 $\bigcirc 9$ i = 5 $\bigcirc M$ k = 6 $\bigcirc 9$ i = 3 k = 2 A i = 3 k = 2 A i = 1 k = 1 i = 1 k = 1 i = 3k = 1

Running time = $O(h) = O(\log n)$ for red-black trees.

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Data structure maintenance

Q. Why not keep the ranks themselves in the nodes instead of subtree sizes?

A. They are hard to maintain when the red-black tree is modified. $k \leftarrow size[left[x]] + 1 \qquad \triangleright k = rank(x)$

Modifying operations: INSERT and DELETE. Strategy: Update subtree sizes when inserting or deleting.



Example of insertion





Handling rebalancing

Don't forget that RB-INSERT and RB-DELETE may also need to modify the red-black tree in order to maintain balance.

- *Recolorings*: no effect on subtree sizes.
- *Rotations*: fix up subtree sizes in O(1) time.



 \therefore RB-INSERT and RB-DELETE still run in $O(\log n)$ time.



Data-structure augmentation

Methodology: (e.g., order-statistics trees)

- 1. Choose an underlying data structure (*red-black tree*).
- 2. Determine additional information to be stored in the data structure (*subtree sizes*).
- Verify that this information can be maintained for modifying operations (RB-INSERT, RB-DELETE — *don't forget rotations*).
- 4. Develop new dynamic-set operations that use the information (OS-SELECT *and* OS-RANK).

These steps are guidelines, not rigid rules.



Interval trees

Goal: To maintain a dynamic set of intervals, such as time intervals.



Query: For a given query interval *i*, find an interval in the set that overlaps *i*.



Following the methodology

- Choose an underlying data structure.
 Red-black tree keyed on low (left) endpoint.
- 2. Determine additional information to be stored in the data structure.
 - Store in each node x the interval int[x] corresponding to the key, as well as the largest value m[x] of all right interval endpoints stored in the subtree rooted at x.







Modifying operations

3. Verify that this information can be maintained for modifying operations.

- INSERT: Fix *m*'s on the way down.
- Rotations Fixup = O(1) time per rotation:



Total INSERT time = $O(\log n)$; DELETE similar.

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New operations

4. Develop new dynamic-set operations that use the information.

INTERVAL-SEARCH(*i*) $x \leftarrow root$ while $x \neq NIL$ and (low[i] > high[int[x]] $or \ low[int[x]] > high[i])$ do $\succ i$ and int[x] don't overlap if $left[x] \neq NIL$ and $low[i] \leq m[left[x]]$ then $x \leftarrow left[x]$ $else \ x \leftarrow right[x]$

return x

Example 1: INTERVAL-SEARCH([14,16]) $x \underbrace{17,19}_{4 \longrightarrow 8} \xrightarrow{low[i] = 7 \longrightarrow 10 = high[i]}_{15 \longrightarrow 18 \ 22 \longrightarrow 23}$

23

5,11



 $14 \le 18 \Longrightarrow x \leftarrow left[x]$

4,8

8

14 - 16





Example 2: Interval-Search([12,14])





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Example 2: INTERVAL-SEARCH([12,14])







Analysis

Time = $O(h) = O(\log n)$, since INTERVAL-SEARCH does constant work at each level as it follows a simple path down the tree.

List *all* overlapping intervals:

- Search, list, delete, repeat.
- Insert them all again at the end. Time = $O(k \log n)$, where k is the total number of overlapping intervals.
- This is an *output-sensitive* bound.

Best algorithm to date: $O(k + \log n)$.



Correctness

Theorem. Let *L* be the set of intervals in the left subtree of node *x*, and let *R* be the set of intervals in x's right subtree.

• If the search goes right, then

{ $i' \in L : i'$ overlaps i } = \emptyset .

• If the search goes left, then

 $\{i' \in L : i' \text{ overlaps } i\} = \emptyset$ $\Rightarrow \{i' \in R : i' \text{ overlaps } i\} = \emptyset.$

In other words, it's always safe to take only 1 of the 2 children: we'll either find something, or nothing was to be found.



Correctness proof

Proof. Suppose first that the search goes right.

- If left[x] = NIL, then we're done, since $L = \emptyset$.
- Otherwise, the code dictates that we must have low[i] > m[left[x]]. The value m[left[x]] corresponds to the right endpoint of some interval j ∈ L, and no other interval in L can have a larger right endpoint than high(j).

$$i$$

$$high(j) = m[left[x]] \xrightarrow{i} low(i)$$

• Therefore, $\{i' \in L : i' \text{ overlaps } i\} = \emptyset$.



Proof (continued)

Suppose that the search goes left, and assume that $\{i' \in L : i' \text{ overlaps } i\} = \emptyset$.

- Then, the code dictates that *low*[*i*] ≤ *m*[*left*[*x*]] = *high*[*j*] for some *j* ∈ *L*.
- Since *j* ∈ *L*, it does not overlap *i*, and hence *high*[*i*] < *low*[*j*].
- But, the binary-search-tree property implies that for all *i*' ∈ *R*, we have *low*[*j*] ≤ *low*[*i*'].
- But then $\{i' \in R : i' \text{ overlaps } i\} = \emptyset$.

