



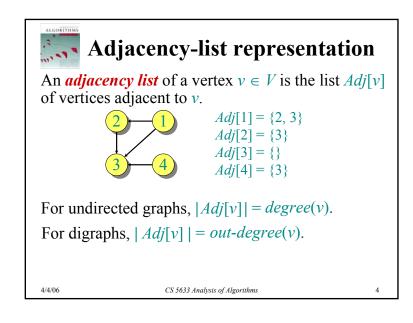
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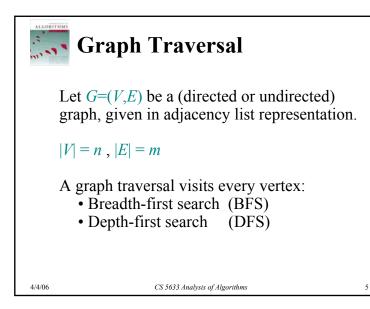
Adjacency-matrix representation

The *adjacency matrix* of a graph G = (V, E), where $V = \{1, 2, ..., n\}$, is the matrix A[1 ... n, 1 ... n]given by $A[i, j] = \begin{cases} 1 & \text{if } (i, j) \in E, \\ 0 & \text{if } (i, j) \notin E. \end{cases}$ $\begin{array}{c} 2 & 1 & \frac{A \mid 1 \ 2 \ 3 \ 4}{1 \ 0 \ 1 \ 1 \ 0} & \Theta(|V|^2) \text{ storage} \\ 2 & 0 \ 0 \ 1 \ 0 & \Rightarrow dense \\ 3 & 0 \ 0 \ 0 \ 1 \ 0 & \end{array}$ representation.

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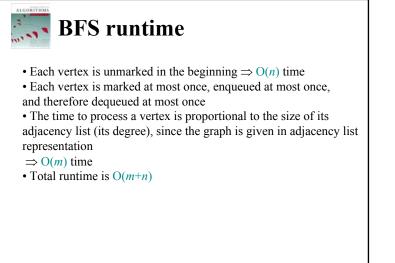


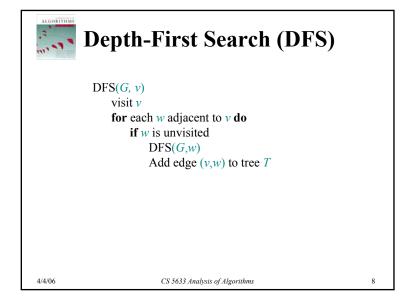




Breadth-First Search (BFS)

BFS(G=(V,E))Unmark all vertices Choose some starting vertex s Mark s queue Q = stree T = swhile *O* is non-empty do v = Q.dequeue visit vfor each unmarked w adjacent to v do Mark w Q.enqueue(w) Add edge (v, w) to T CS 5633 Analysis of Algorithms 4/4/06 6





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