

**CS 5633 -- Spring 2004** 



## Minimum Spanning Trees

#### **Carola Wenk**

### Slides courtesy of Charles Leiserson with small changes by Carola Wenk



### Graphs (review)

**Definition.** A *directed graph* (*digraph*) G = (V, E) is an ordered pair consisting of

- a set *V* of *vertices* (singular: *vertex*),
- a set  $E \subseteq V \times V$  of *edges*.

In an *undirected graph* G = (V, E), the edge set *E* consists of *unordered* pairs of vertices.

In either case, we have  $|E| = O(|V|^2)$ . Moreover, if *G* is connected, then  $|E| \ge |V| - 1$ .

### (Review CLRS, Appendix B.4 and B.5.)



# Adjacency-matrix representation

The *adjacency matrix* of a graph G = (V, E), where  $V = \{1, 2, ..., n\}$ , is the matrix A[1 ... n, 1 ... n] given by

$$A[i,j] = \begin{cases} 1 & \text{if } (i,j) \in \mathcal{E}, \\ 0 & \text{if } (i,j) \notin \mathcal{E}. \end{cases}$$



 $\Theta(|V|^2)$  storage  $\Rightarrow$  *dense* representation.



### Adjacency-list representation

An *adjacency list* of a vertex  $v \in V$  is the list Adj[v] of vertices adjacent to v.



$$Adj[1] = \{2, 3\}$$
  
 $Adj[2] = \{3\}$   
 $Adj[3] = \{\}$   
 $Adj[4] = \{3\}$ 

For undirected graphs, |Adj[v]| = degree(v). For digraphs, |Adj[v]| = out-degree(v).



### Adjacency-list representation

### Handshaking Lemma:

- For undirected graphs:  $\sum_{v \in V} degree(v) = 2|E|$
- For digraphs:

 $\sum_{v \in V} in-degree(v) + \sum_{v \in V} out-degree(v) = 2 \mid E \mid$ 

 $\Rightarrow$  adjacency lists use  $\Theta(|V| + |E|)$  storage  $\Rightarrow$  a *sparse* representation



### Minimum spanning trees

- **Input:** A connected, undirected graph G = (V, E) with weight function  $w : E \to \mathbb{R}$ .
- For simplicity, assume that all edge weights are distinct. (CLRS covers the general case.)

**Output:** A *spanning tree* T — a tree that connects all vertices — of minimum weight:

$$w(T) = \sum_{(u,v)\in T} w(u,v).$$



### **Example of MST**





### Hallmark for "greedy" algorithms

Greedy-choice property A locally optimal choice is globally optimal.

# **Theorem.** Let *T* be the MST of G = (V, E), and let $A \subseteq V$ . Suppose that $(u, v) \in E$ is the least-weight edge connecting *A* to $V \setminus A$ . Then, $(u, v) \in T$ .











Consider the unique simple path from u to v in T.



*Proof.* Suppose  $(u, v) \notin T$ . Cut and paste.

*T*:  $e \in A$   $e \in V - A$  (u, v) = least-weight edge (u, v) = least-weight edge(u, v) = least-weight edge

Consider the unique simple path from u to v in T. Swap (u, v) with the first edge on this path that connects a vertex in A to a vertex in  $V \setminus A$ .



*Proof.* Suppose  $(u, v) \notin T$ . Cut and paste.

T': V = least-weight edge V = V - A

Consider the unique simple path from u to v in T. Swap (u, v) with the first edge on this path that connects a vertex in A to a vertex in V - A. A lighter-weight spanning tree than T results.



### Prim's algorithm

**IDEA:** Maintain  $V \setminus A$  as a priority queue Q. Key each vertex in Q with the weight of the leastweight edge connecting it to a vertex in A.  $Q \leftarrow V$  $kev[v] \leftarrow \infty$  for all  $v \in V$  $key[s] \leftarrow 0$  for some arbitrary  $s \in V$ while  $Q \neq \emptyset$ **do**  $u \leftarrow \text{EXTRACT-MIN}(Q)$ for each  $v \in Adj[u]$ **do if**  $v \in Q$  and w(u, v) < key[v]► DECREASE-KEY then  $key[v] \leftarrow w(u, v)$  $\pi[v] \leftarrow u$ At the end,  $\{(v, \pi[v])\}$  forms the MST. 3/22/04CS 5633 Analysis of Algorithms 14





















9

15



### **Example of Prim's algorithm**





### **Example of Prim's algorithm**











Handshaking Lemma  $\Rightarrow \Theta(|E|)$  implicit DECREASE-KEY's. Time =  $\Theta(|V|) \cdot T_{\text{EXTRACT-MIN}} + \Theta(|E|) \cdot T_{\text{DECREASE-KEY}}$ 



# Analysis of Prim (continued)

Time =  $\Theta(|V|) \cdot T_{\text{EXTRACT-MIN}} + \Theta(|E|) \cdot T_{\text{DECREASE-KEY}}$ 

<i>Q</i>	T <sub>EXTRACT-MIN</sub>	T <sub>DECREASE-KEY</sub>	Total
array	O( V )	<i>O</i> (1)	$O( V ^2)$
binary heap	$O(\log  V )$	$O(\log  V )$	$O( E \log V )$
Fibonacci heap	i O(log  V ) amortized	O(1) O( A amortized	$ V  =  V  \log  V $ worst case



# **MST algorithms**

Kruskal's algorithm (see CLRS):

- Uses the *disjoint-set data structure* (Lecture 20).
- Running time =  $O(|E| \log |V|)$ .

Best to date:

- Karger, Klein, and Tarjan [1993].
- Randomized algorithm.
- O(|V| + |E|) expected time.