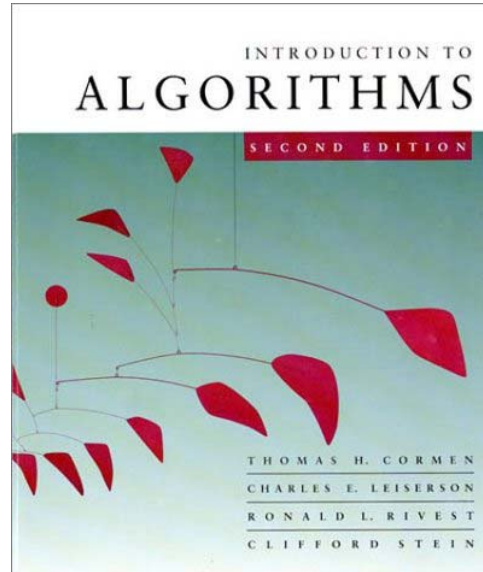


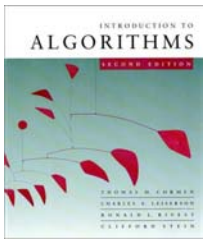


CS 33433 – Fall 2007



Topological Sort

Carola Wenk



Paths, Cycles, Connectivity

Let $G=(V,E)$ be a directed (or undirected) graph

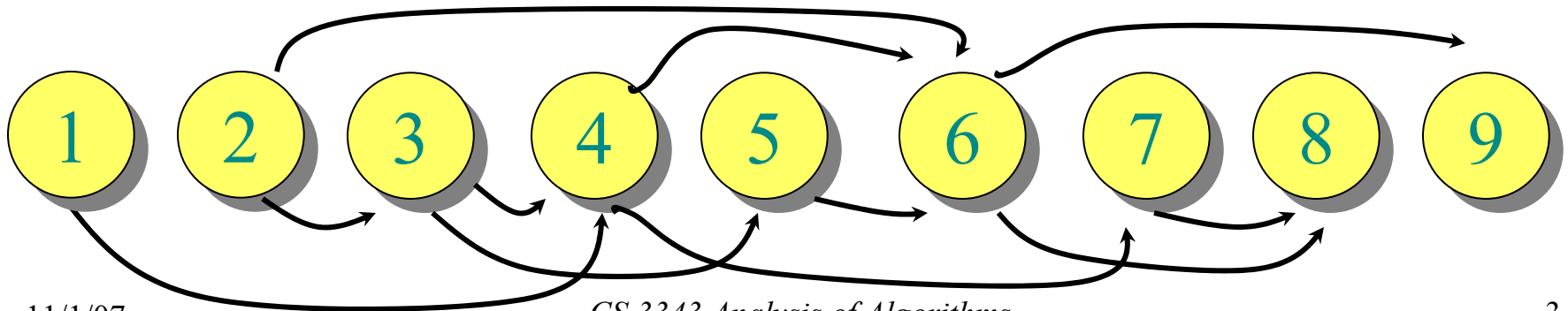
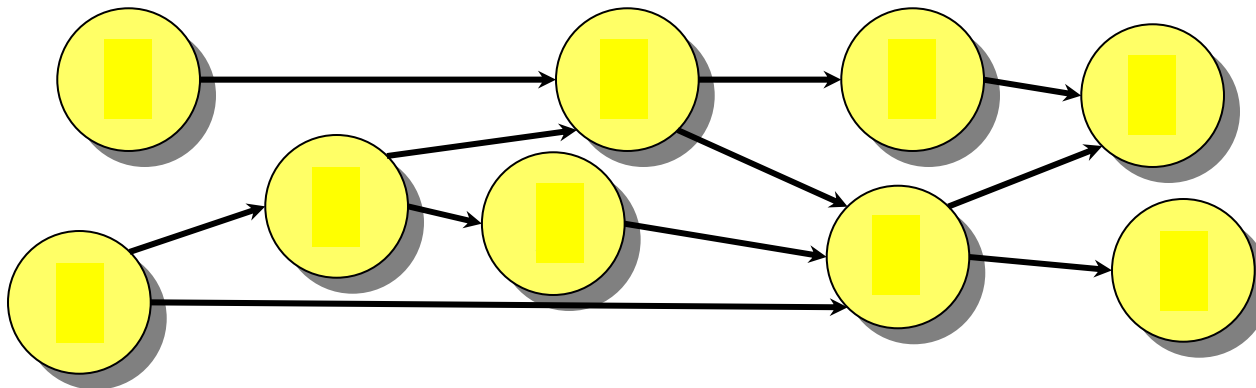
- A **path** from v_1 to v_k in G is a sequence of vertices v_1, v_2, \dots, v_k such that $(v_i, v_{i+1}) \in E$ (or $\{v_i, v_{i+1}\} \in E$ if G is undirected) for all $i \in \{1, \dots, k-1\}$.
- A path is **simple** if all vertices in the path are distinct.
- A path v_1, v_2, \dots, v_k forms a **cycle** if $v_1 = v_k$ and $k \geq 2$.
- A graph with no cycles is **acyclic**.
 - An undirected acyclic graph is called a **tree**. (Trees do not have to have a root vertex specified.)
 - A directed acyclic graph is a **DAG**. (A DAG can have undirected cycles if the direction of the edges is not considered.)
- An undirected graph is **connected** if every pair of vertices is connected by a path. A directed graph is **strongly connected** if for every pair $u, v \in V$ there is a path from u to v and there is a path from v to u .
- The **(strongly) connected components** of a graph are the equivalence classes of vertices under this reachability relation.



Topological Sort

Topologically sort the vertices of a *directed acyclic graph (DAG)*:

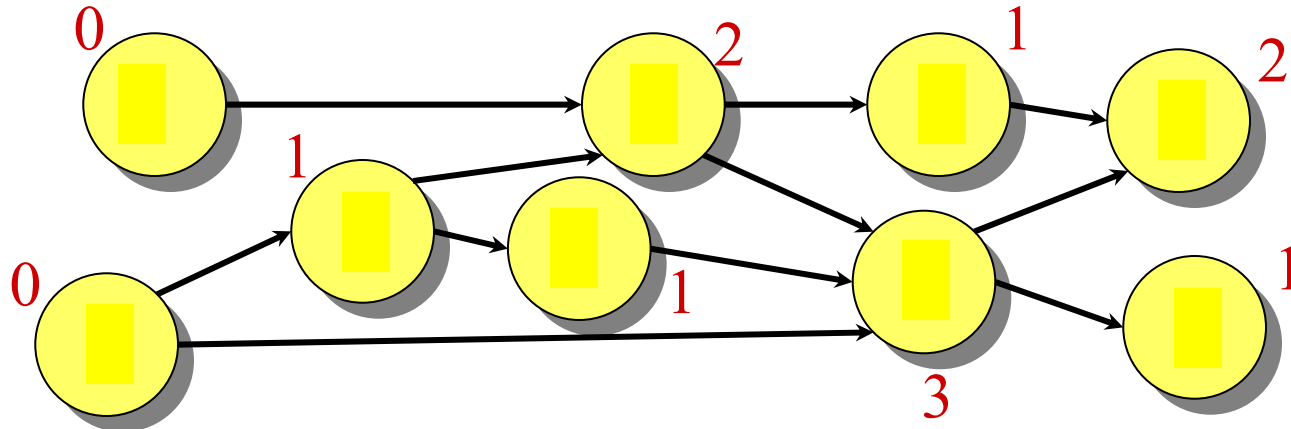
- Determine $f: V \rightarrow \{1, 2, \dots, |V|\}$ such that $(u, v) \in E \Rightarrow f(u) < f(v)$.





Topological Sort Algorithm

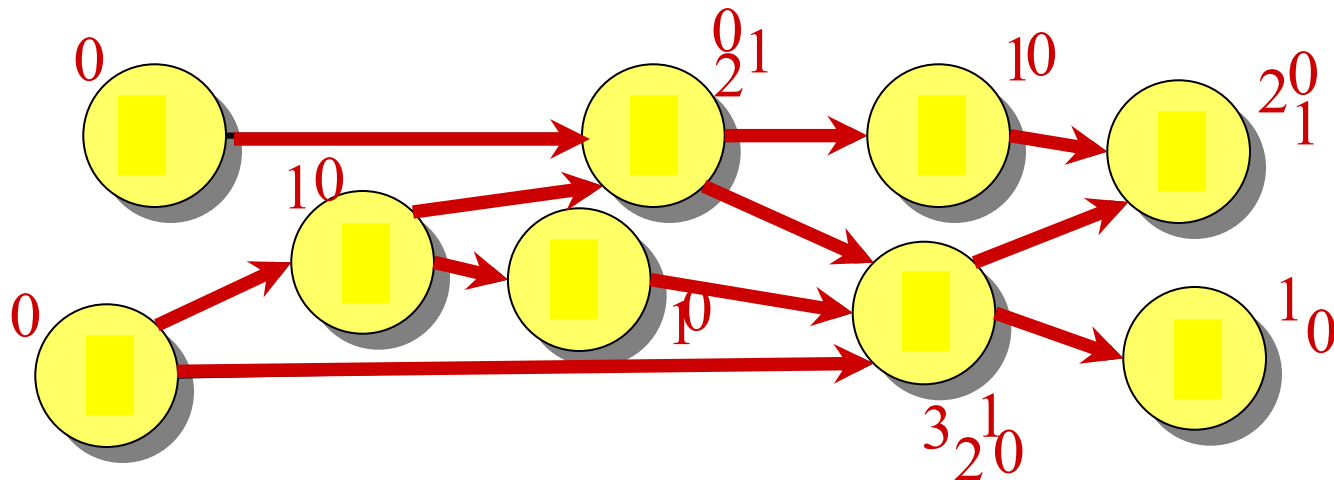
- Store vertices in a priority min-queue, with the **in-degree** of the vertex as the key
- While queue is not empty
 - Extract minimum vertex v , and give it next number
 - Decrease keys of all adjacent vertices by 1





Topological Sort Algorithm

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Topological Sort Runtime

Runtime:

- $O(|V|)$ to build heap + $O(|E|)$ DECREASE-KEY ops
- $\Rightarrow O(|V| + |E| \log |V|)$ with a binary heap
- $\Rightarrow O(|V| + |E|)$ with a Fibonacci heap



Depth-First Search revisited

```
DFS( $G=(V,E)$ )
```

```
  Mark all vertices in  $G$  as “unvisited”
```

```
  time=0;
```

```
  for each vertex  $v \in V$  do
```

```
    if  $v$  is unvisited
```

```
      DFS_rec( $G,v$ )
```

```
DFS_rec( $G, v$ )
```

```
  visit  $v$ ;
```

```
  d[ $v$ ]=++time; //discover time
```

```
  for each  $w$  adjacent to  $v$  do
```

```
    if  $w$  is unvisited
```

```
      Add edge  $(v,w)$  to tree  $T$ 
```

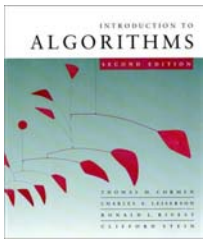
```
      DFS_rec( $G,w$ )
```

```
  f[ $v$ ]=++time; //finish time
```



DFS Edge Classification

- Edge (u, v) in depth-first forest:
 - **Tree edge:** v was discovered by exploring edge (u, v)
- Edge (u, v) not in depth-first forest:
 - Back edge: v is ancestor of u in depth-first forest
 - Forward edge: v is descendant of u in depth-first forest
 - Cross edge: Any other edge



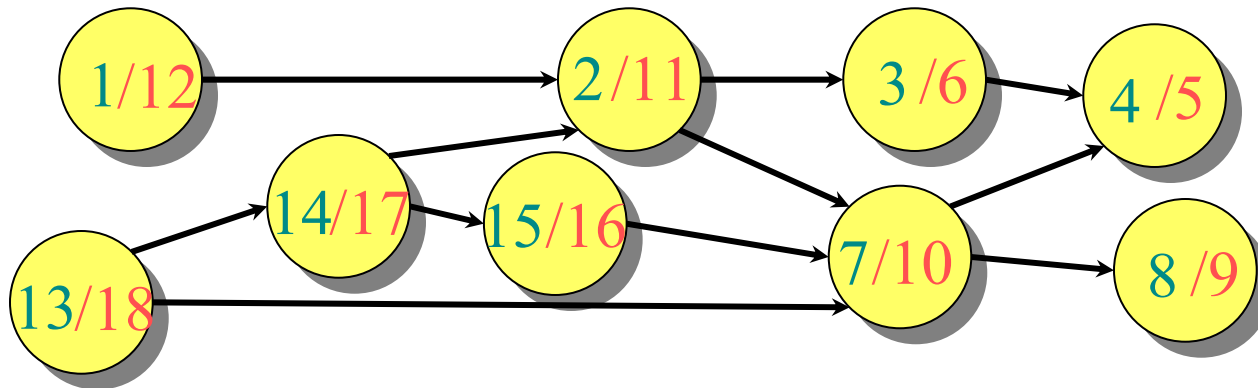
DFS-Based Topological Sort Algorithm

- Call DFS on the directed acyclic graph $G=(V,E)$
 - \Rightarrow Finish time for every vertex
- Reverse the finish times (highest finish time becomes the lowest finish time,...)
 - \Rightarrow Valid function $f: V \rightarrow \{1, 2, \dots, |V|\}$ such that $(u, v) \in E \Rightarrow f(u) < f(v)$.

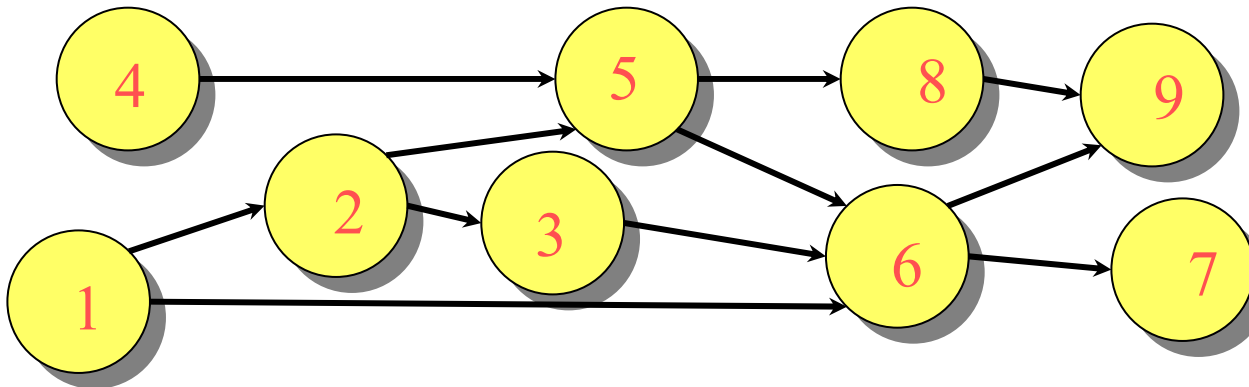
Runtime: $O(|V|+|E|)$

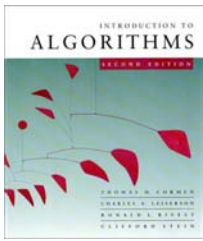
DFS-Based Topological Sort

- Run DFS:



- Reverse finish times:





Topological Sort Runtime

Runtime:

- $O(|V|)$ to build heap + $O(|E|)$ DECREASE-KEY ops
⇒ $O(|V| + |E| \log |V|)$ with a binary heap
⇒ $O(|V| + |E|)$ with a Fibonacci heap
- DFS-based algorithm: $O(|V| + |E|)$