

CMPS 6610/4610 – Fall 2016

Graphs

Carola Wenk

Slides courtesy of Charles Leiserson with changes and additions
by Carola Wenk

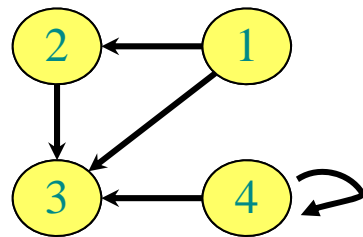
Graphs

Definition. A *directed graph (digraph)* $G = (V, E)$ is an ordered pair consisting of

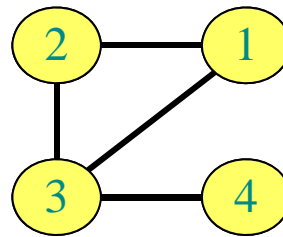
- a set V of *vertices* (singular: *vertex*),
- a set $E \subseteq V \times V$ of *edges*.

In an *undirected graph* $G = (V, E)$, the edge set E consists of *unordered* pairs of vertices.

directed graph



undirected graph



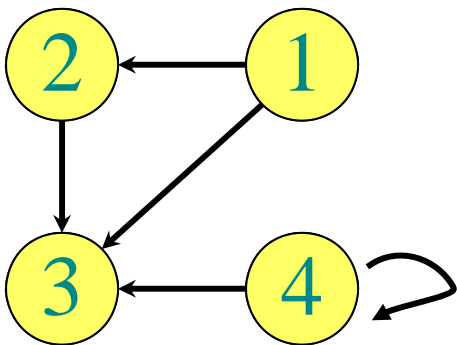
In either case, we have $|E| = O(|V|^2)$.

Moreover, if G is connected, then $|E| \geq |V| - 1$.

Adjacency-matrix representation

The *adjacency matrix* of a graph $G = (V, E)$, where $V = \{1, 2, \dots, n\}$, is the matrix $A[1..n, 1..n]$ given by

$$A[i, j] = \begin{cases} 1 & \text{if } (i, j) \in E, \\ 0 & \text{if } (i, j) \notin E. \end{cases}$$

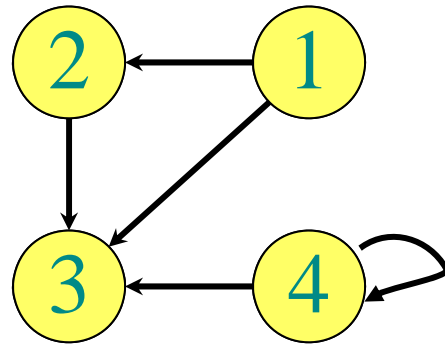


A	1	2	3	4
1	0	1	1	0
2	0	0	1	0
3	0	0	0	0
4	0	0	1	1

$\Theta(|V|^2)$ storage
 \Rightarrow *dense*
representation.

Adjacency-list representation

An *adjacency list* of a vertex $v \in V$ is the list $Adj[v]$ of vertices adjacent to v .



$$Adj[1] = \{2, 3\}$$

$$Adj[2] = \{3\}$$

$$Adj[3] = \{\}$$

$$Adj[4] = \{3, 4\}$$

For undirected graphs, $|Adj[v]| = degree(v)$.

For digraphs, $|Adj[v]| = out-degree(v)$.

Adjacency-list representation

Handshaking Lemma:

Every edge is counted twice

- For undirected graphs:

$$\sum_{v \in V} \text{degree}(v) = 2|E|$$

- For digraphs:

$$\sum_{v \in V} \text{in-degree}(v) = \sum_{v \in V} \text{out-degree}(v) = |E|$$

⇒ adjacency lists use $\Theta(|V| + |E|)$ storage

⇒ a *sparse* representation

⇒ We usually use this representation,
unless stated otherwise

Graph Traversal

Let $G=(V,E)$ be a (directed or undirected) graph, given in adjacency list representation.

$$|V| = n , |E| = m$$

A graph traversal visits every vertex:

- Breadth-first search (BFS)
- Depth-first search (DFS)

Breadth-First Search (BFS)

BFS($G=(V,E)$)

Mark all vertices in G as “unvisited” // $\text{time}=0$

Initialize empty queue Q

for each vertex $v \in V$ **do**

if v is unvisited

 visit v // $\text{time}++$

$Q.\text{enqueue}(v)$

 BFS_iter(G)

BFS_iter(G)

while Q is non-empty **do**

$v = Q.\text{dequeue}()$

for each w adjacent to v **do**

if w is unvisited

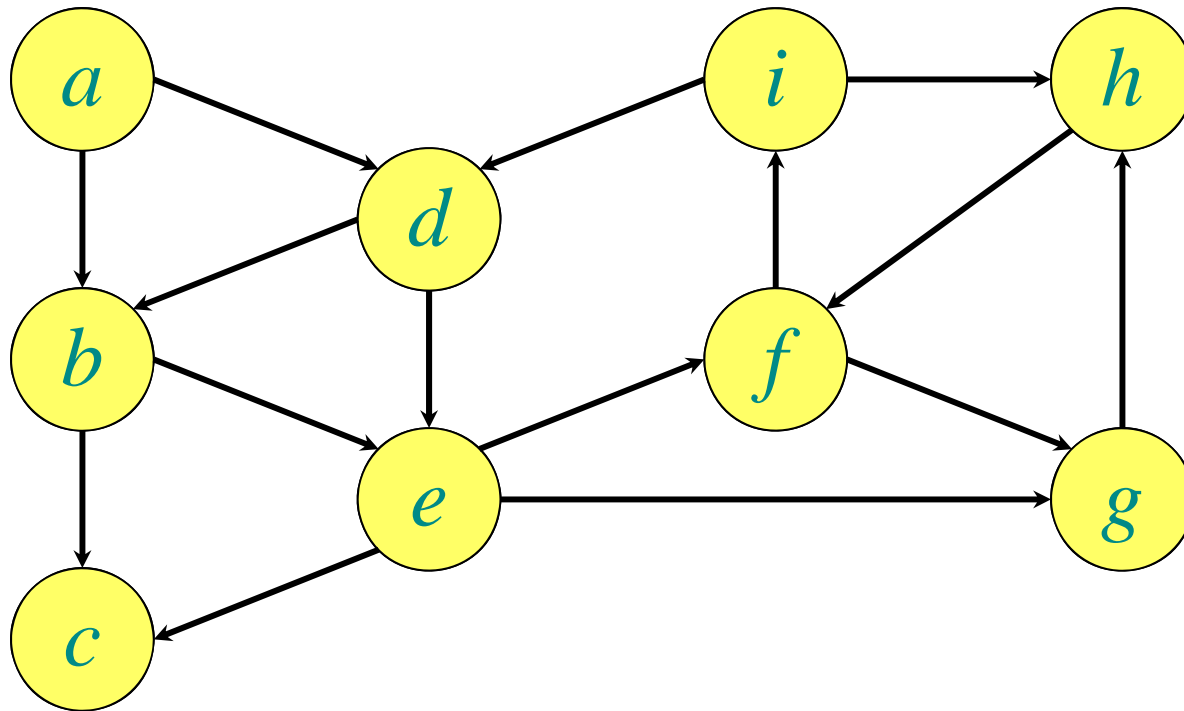
 visit w // $\text{time}++$

 Add edge (v,w) to T

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Example of breadth-first search

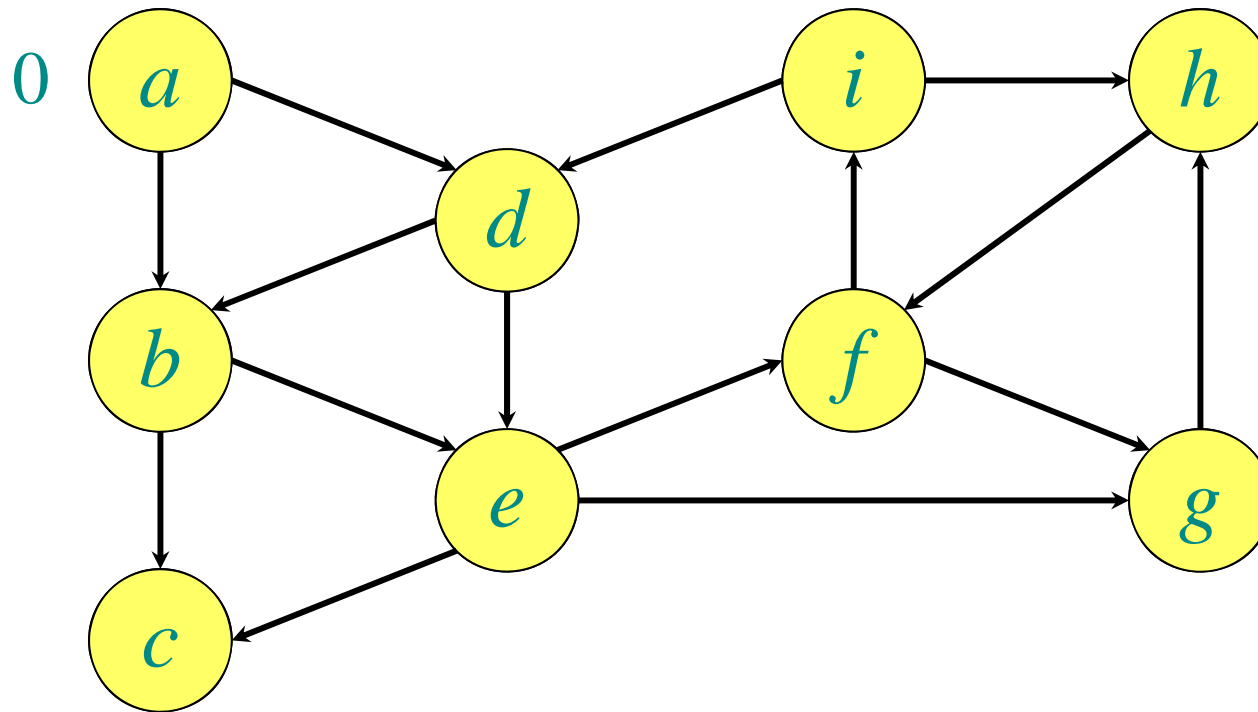
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Q :

Example of breadth-first search

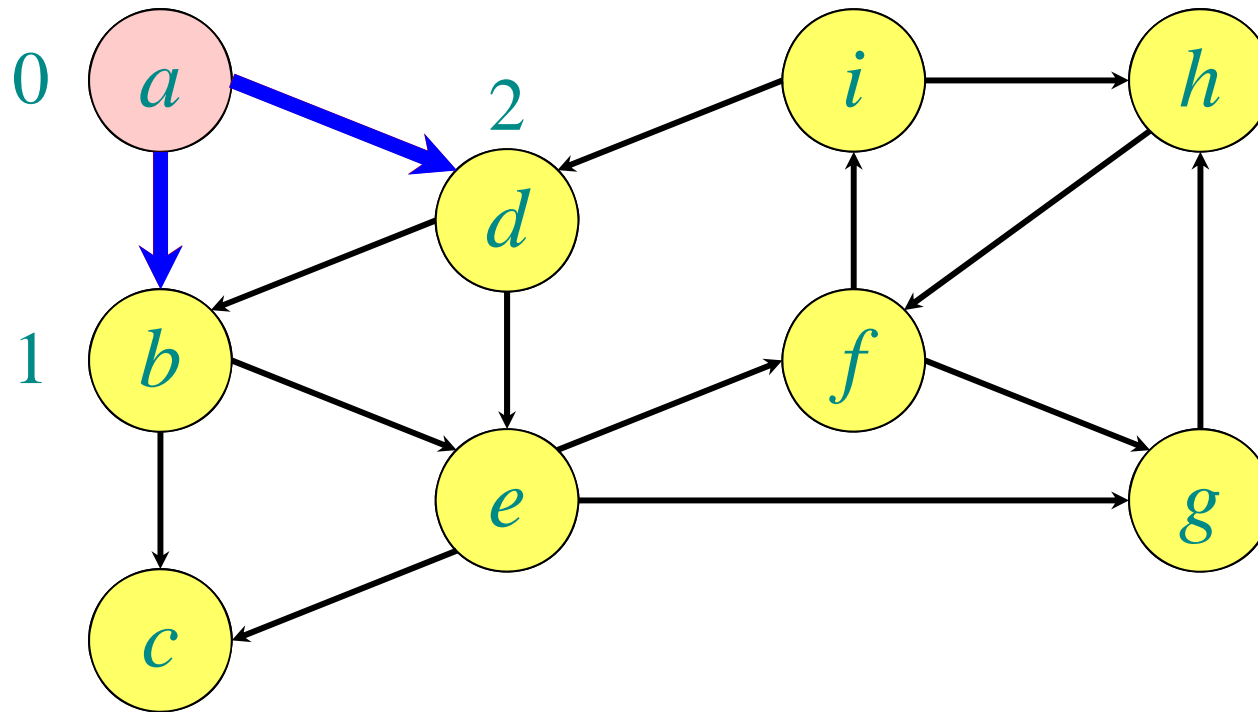
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0
 $Q: a$

Example of breadth-first search

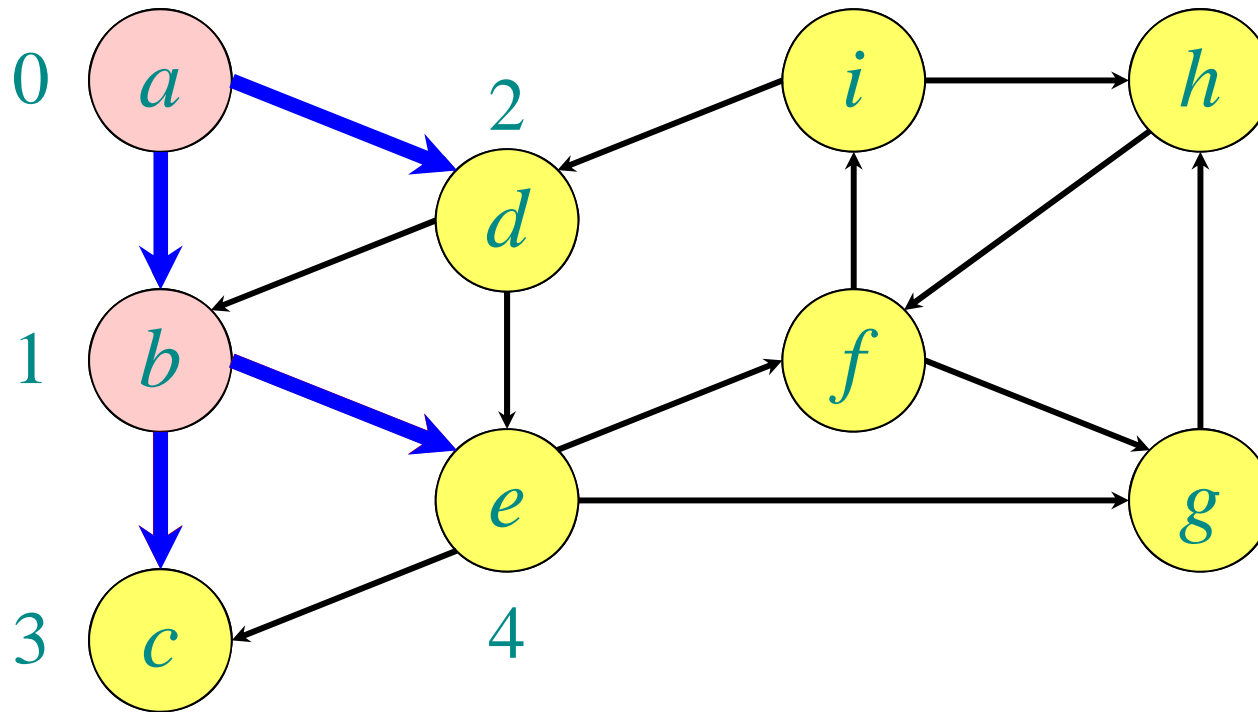
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1 2
 $Q: a b d$

Example of breadth-first search

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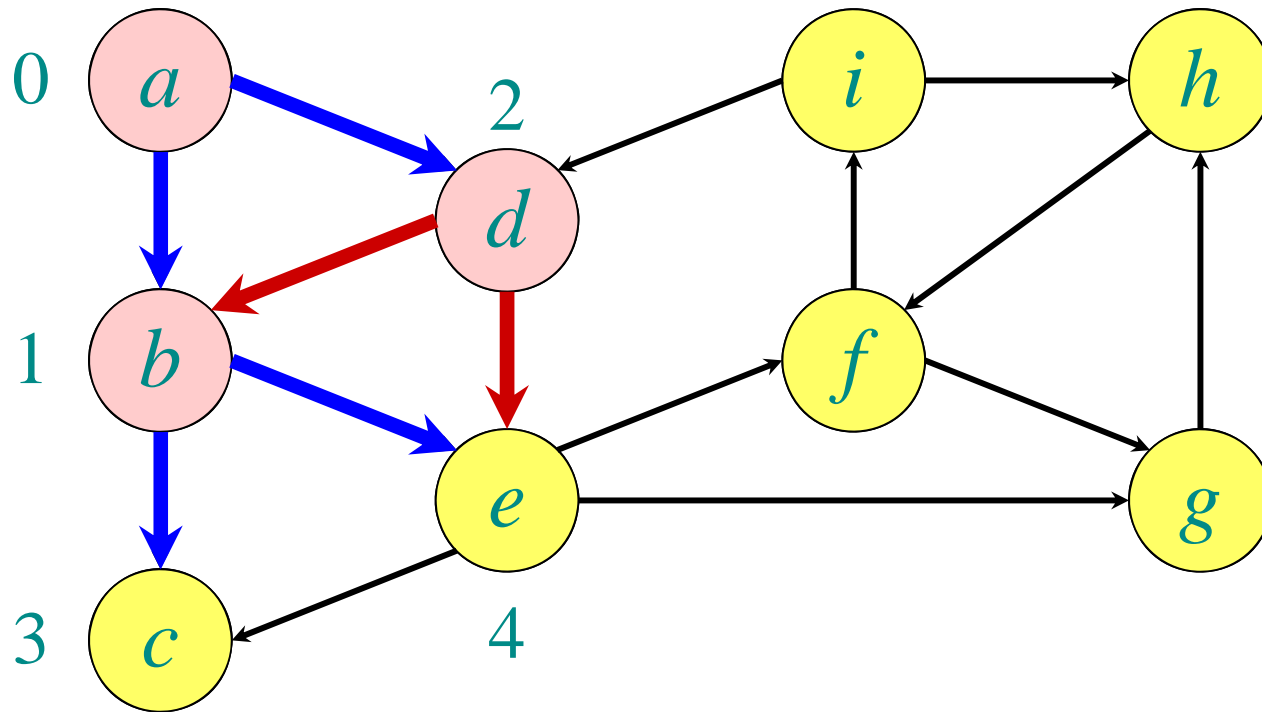


2 3 4
 $Q: a b d c e$

Example of breadth-first search

```

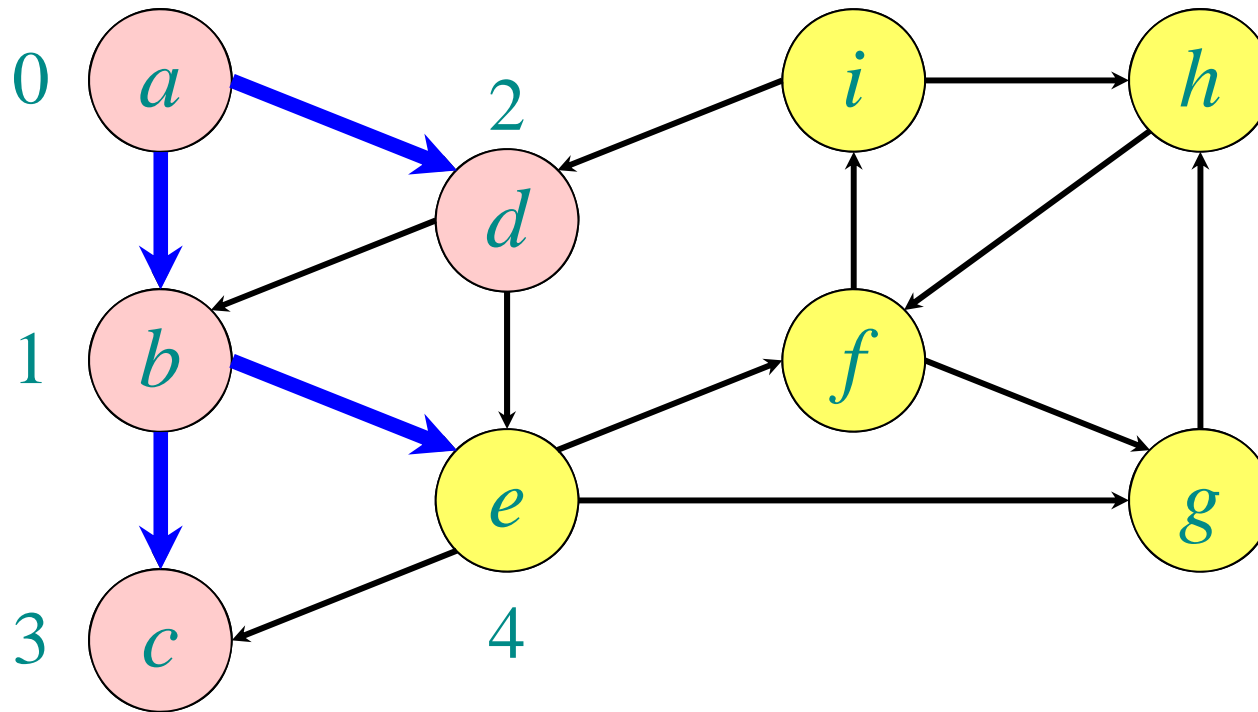
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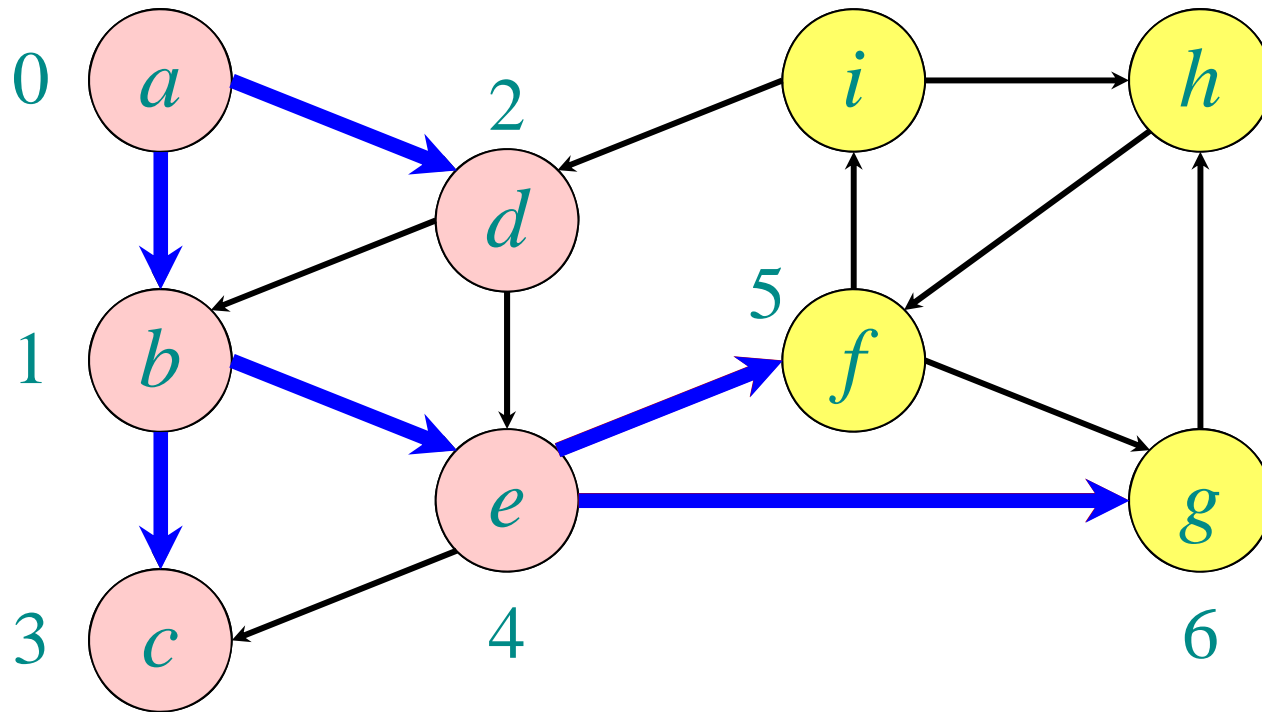
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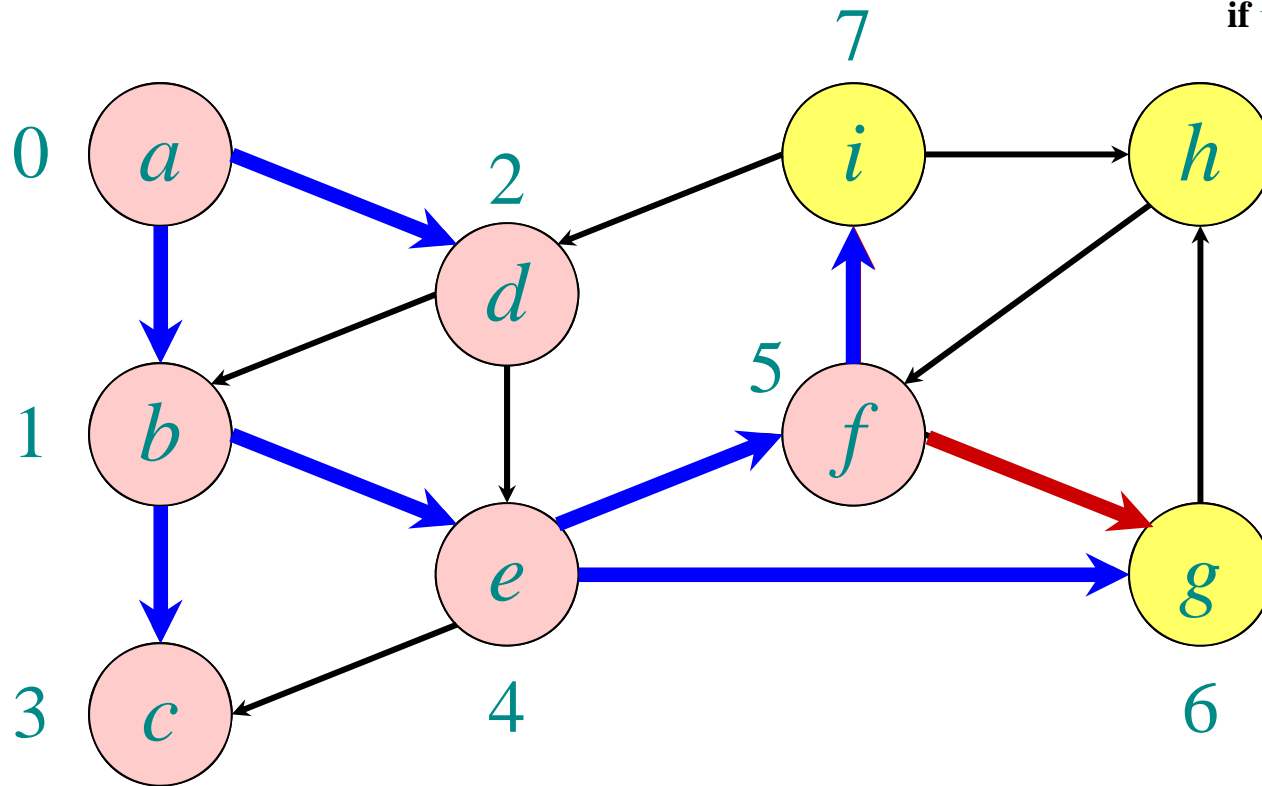


5 6
 $Q: a b d c e f g$

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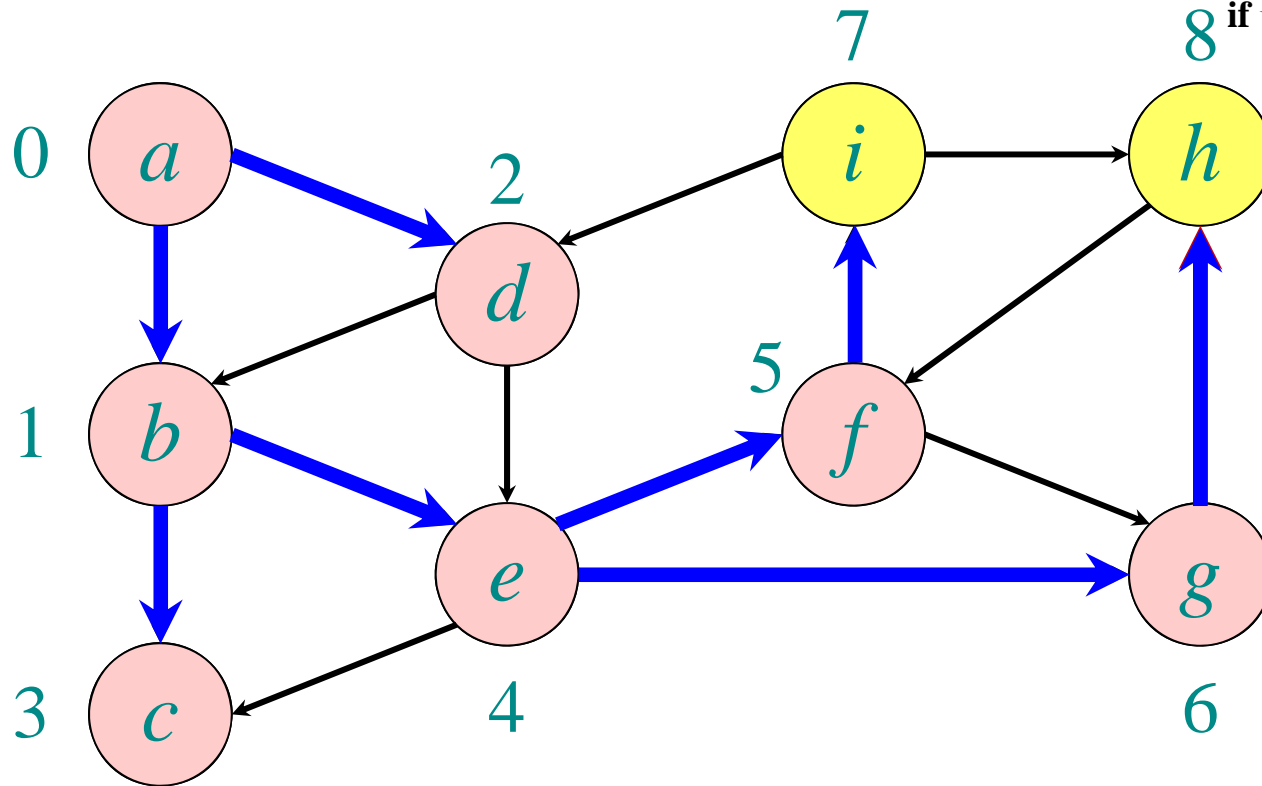


$Q: a\ b\ d\ c\ e\ f\ g\ i$

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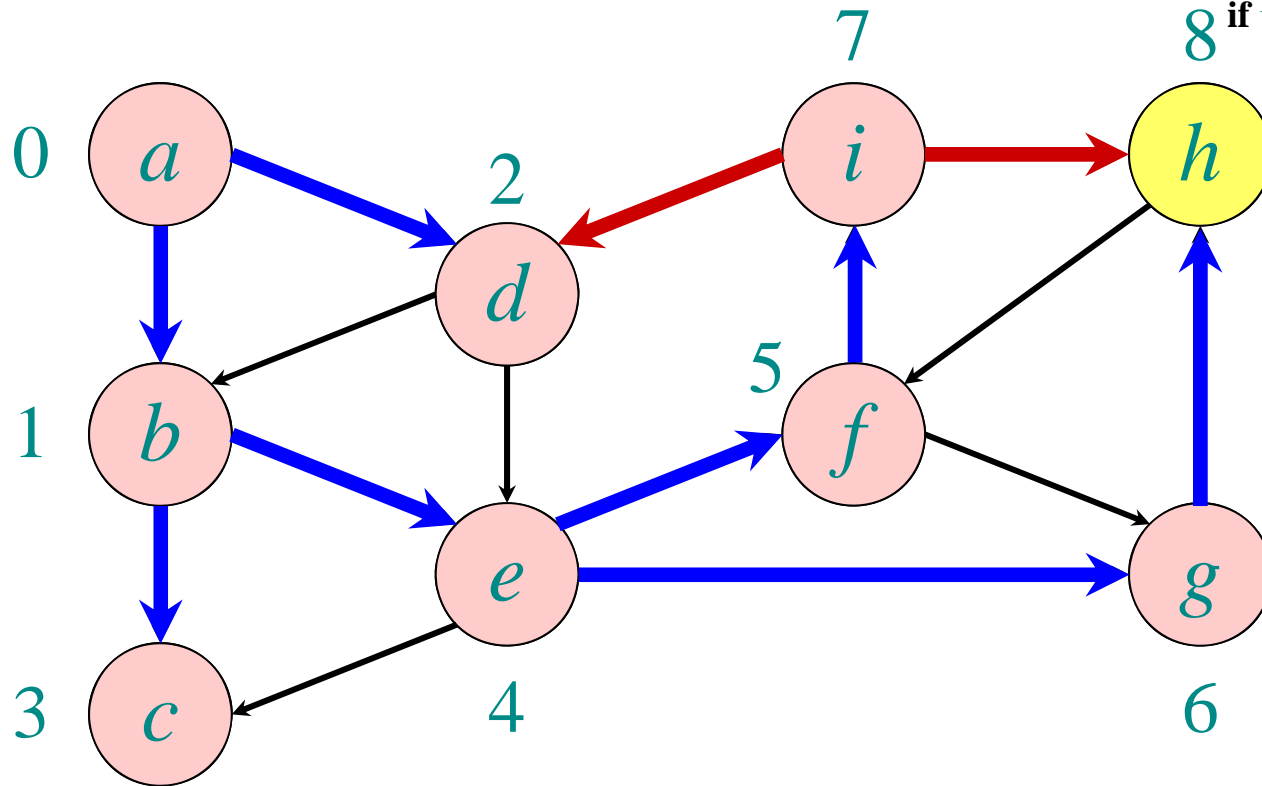


7 8
 $Q: a b d c e f g i h$

Example of breadth-first search

```

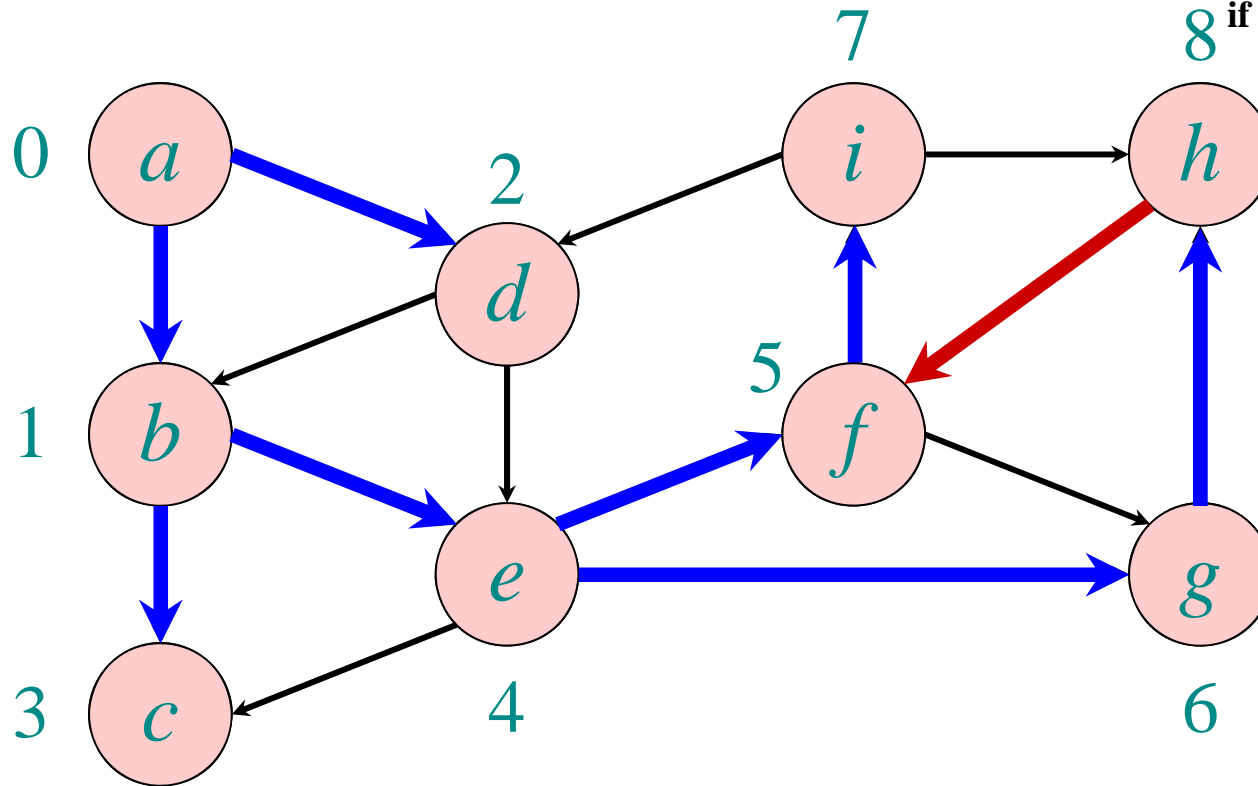
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$Q: a \ b \ d \ c \ e \ f \ g \ i \ h$

Example of breadth-first search

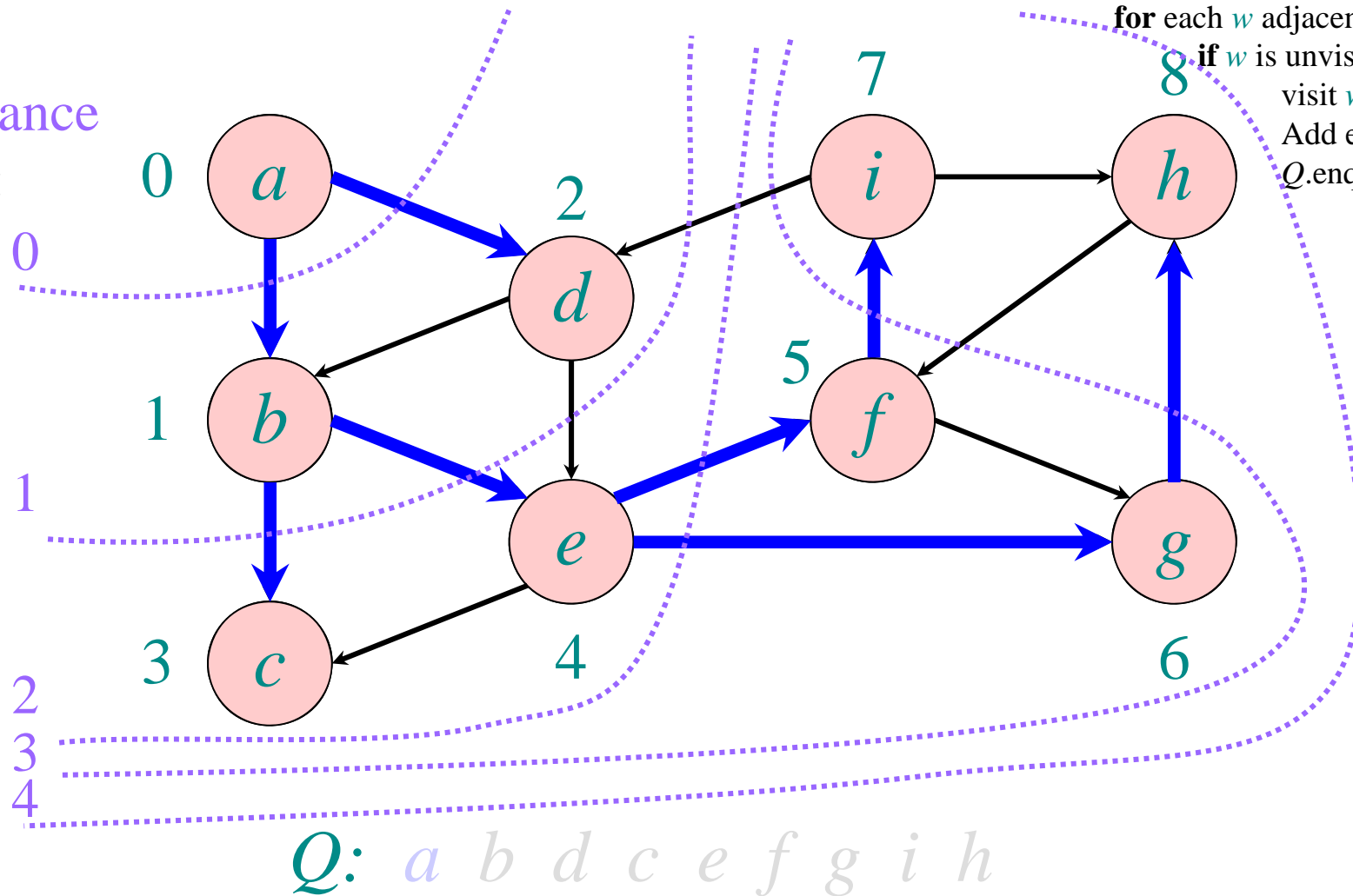
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$Q: a b d c e f g i h$

Example of breadth-first search

Distance
to a :



```

while  $Q$  is non-empty do
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      Add edge  $(v,w)$  to  $T$ 
       $Q.enqueue(w)$ 
  
```

Breadth-First Search (BFS)

BFS($G=(V,E)$)

Mark all vertices in G as “unvisited” // **time=0**

Initialize empty queue Q

for each vertex $v \in V$ **do**

if v is unvisited

 visit v // **time++**

$Q.enqueue(v)$

 BFS_iter(G)

BFS_iter(G)

while Q is non-empty **do**

$v = Q.dequeue()$

for each w adjacent to v **do**

if w is unvisited

 visit w // **time++**

 Add edge (v,w) to T

$Q.enqueue(w)$

$O(n)$

$O(1)$

$O(n)$

without
BFS_iter

$O(m)$

$O(deg(v))$

BFS runtime

- Each vertex is marked as unvisited in the beginning $\Rightarrow O(n)$ time
- Each vertex is marked at most once, enqueued at most once, and therefore dequeued at most once
- The time to process a vertex is proportional to the size of its adjacency list (its degree), since the graph is given in adjacency list representation
 $\Rightarrow O(m)$ time
- Total runtime is $O(n+m) = O(|V| + |E|)$

Depth-First Search (DFS)

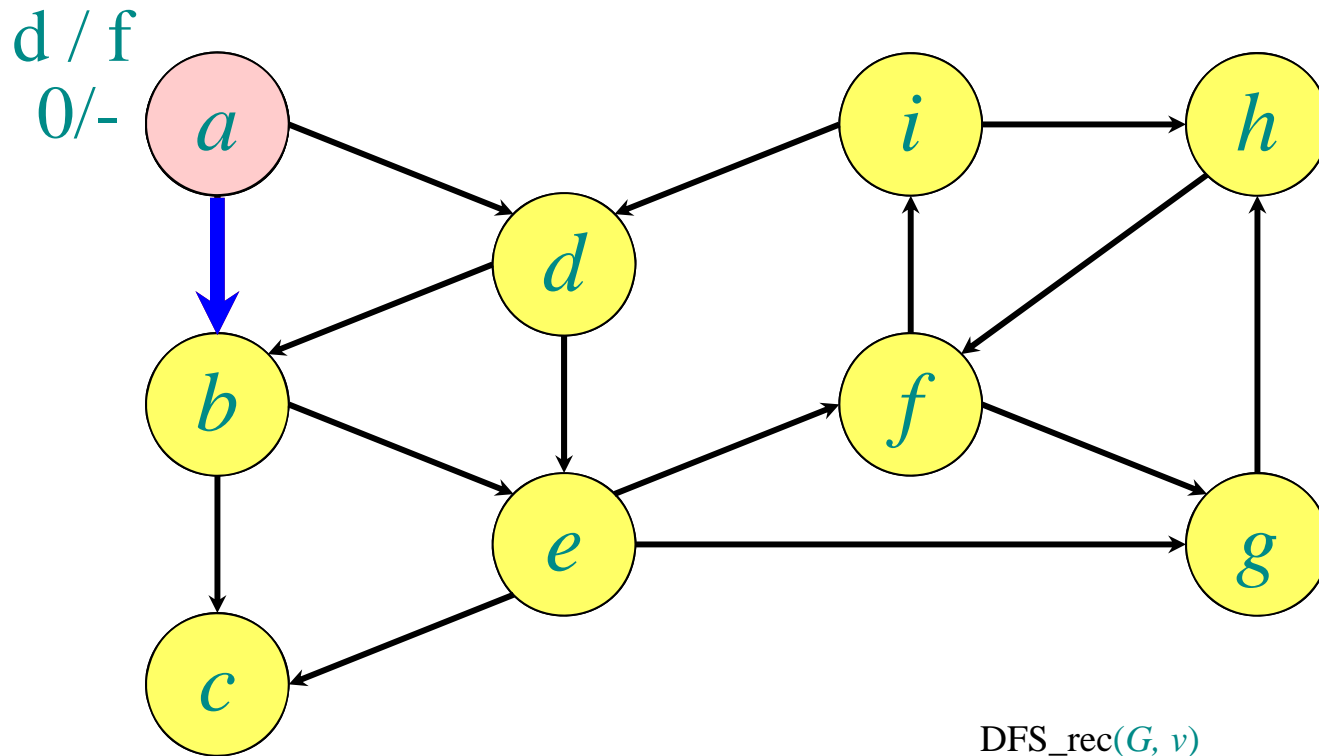
DFS($G=(V,E)$)

Mark all vertices in G as “unvisited” // $\text{time}=0$
for each vertex $v \in V$ **do**
 if v is unvisited
 DFS_rec(G,v)

DFS_rec(G, v)

mark v as “visited” // $d[v]=++\text{time}$
for each w adjacent to v **do**
 if w is unvisited
 Add edge (v,w) to tree T
 DFS_rec(G,w)
mark v as “finished” // $f[v]=++\text{time}$

Example of depth-first search



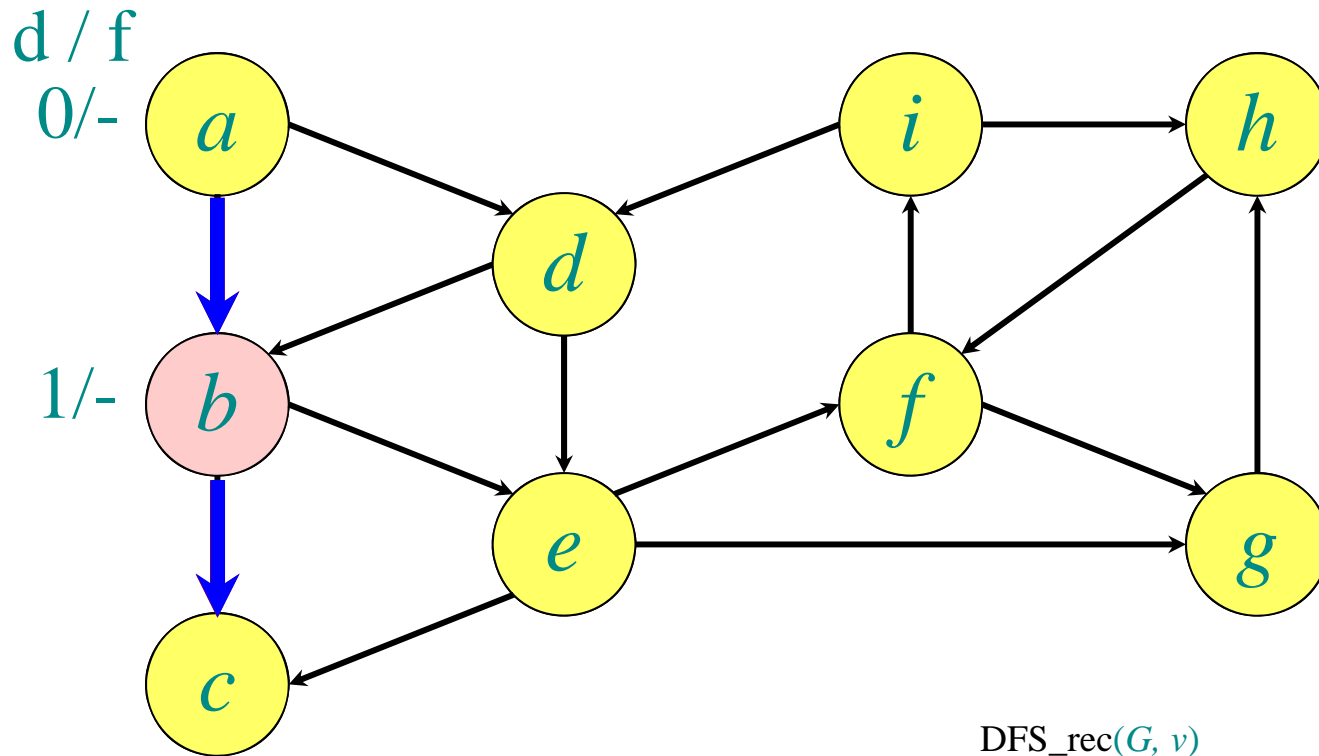
$\pi: \underline{a \ b \ c \ d \ e \ f \ g \ h \ i}$
 - a

Store edges in predecessor array

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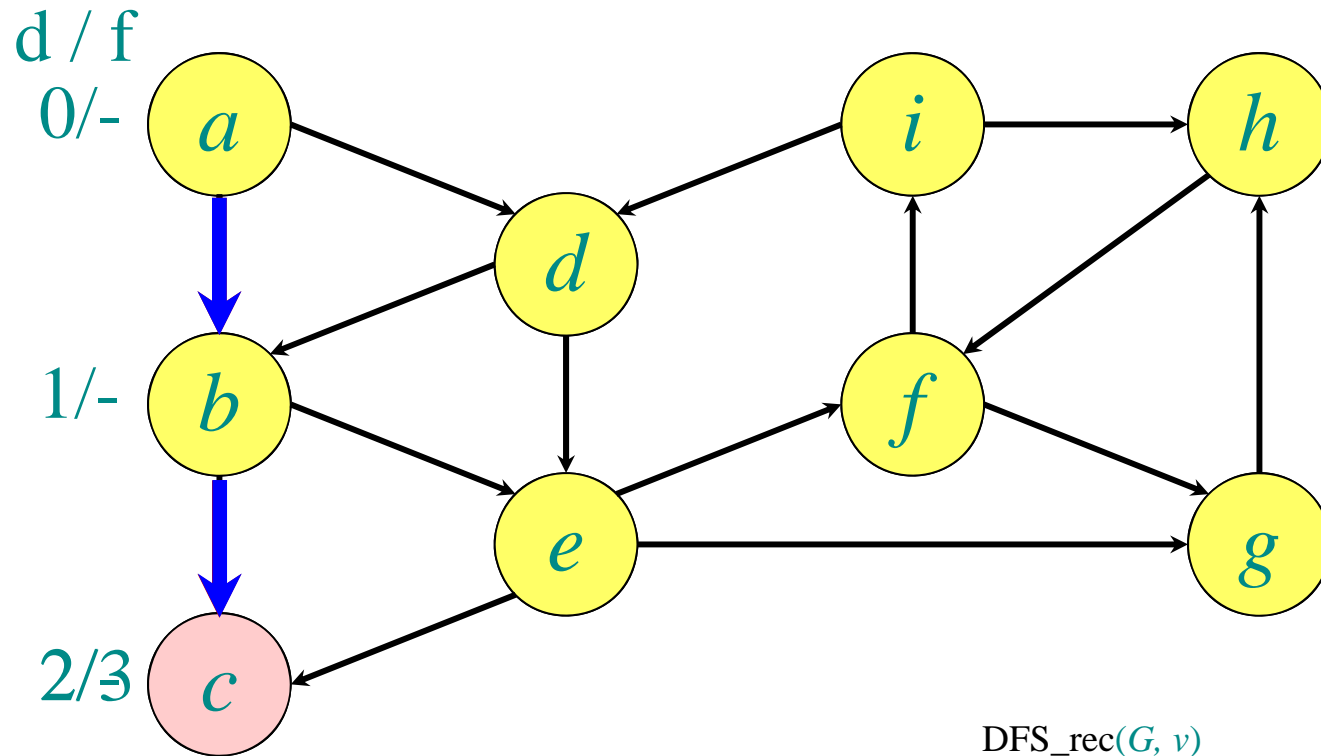
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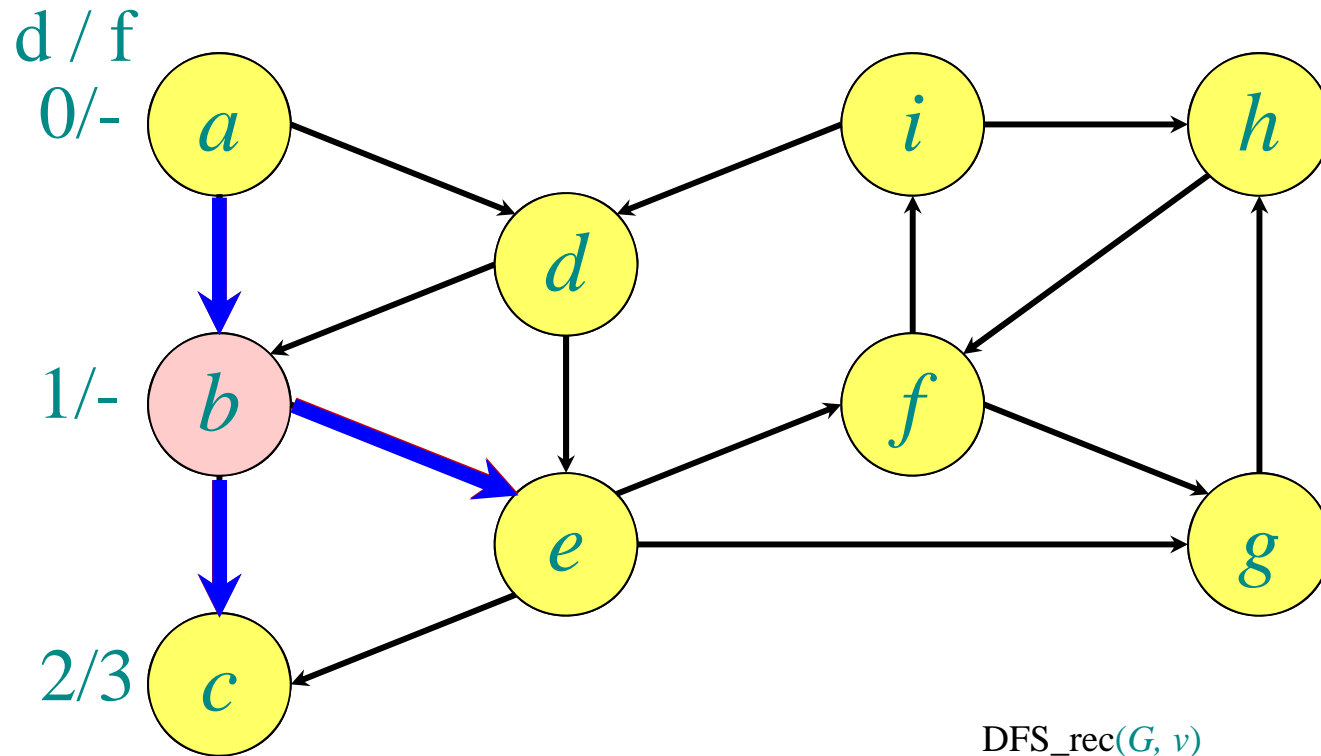
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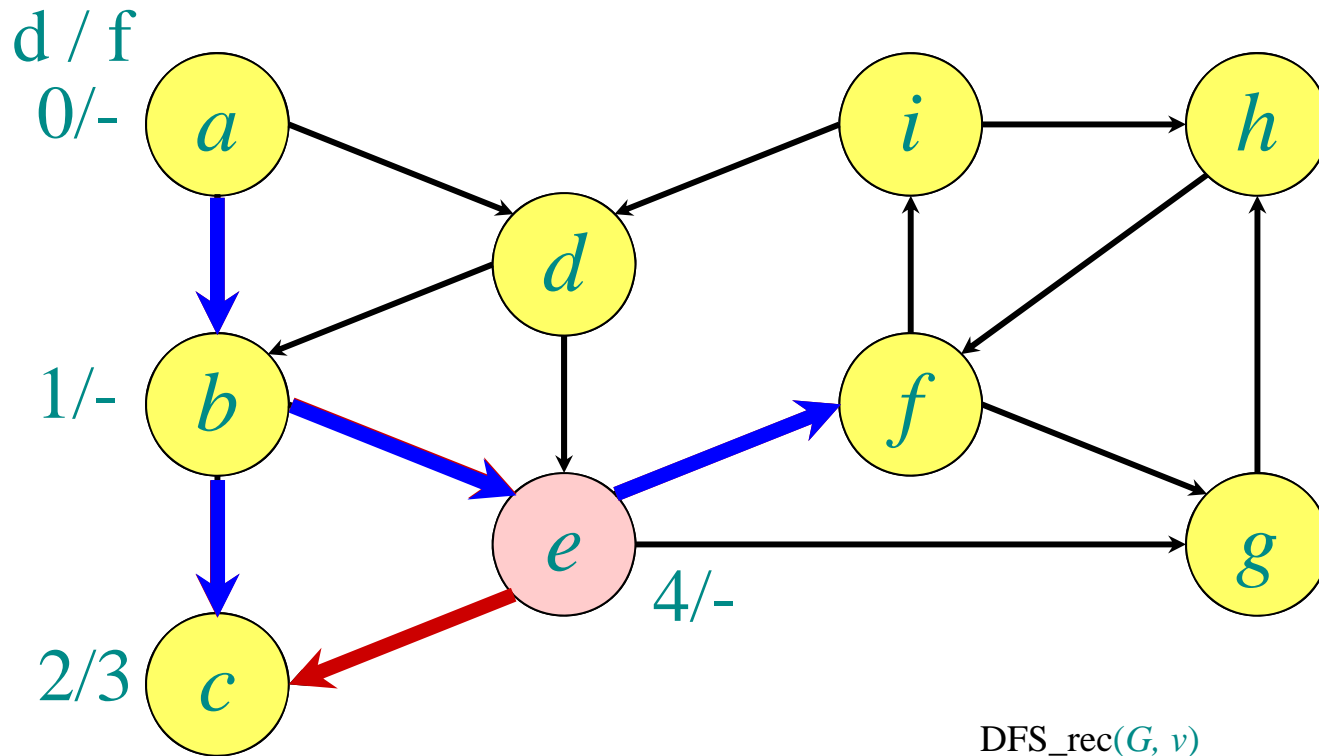
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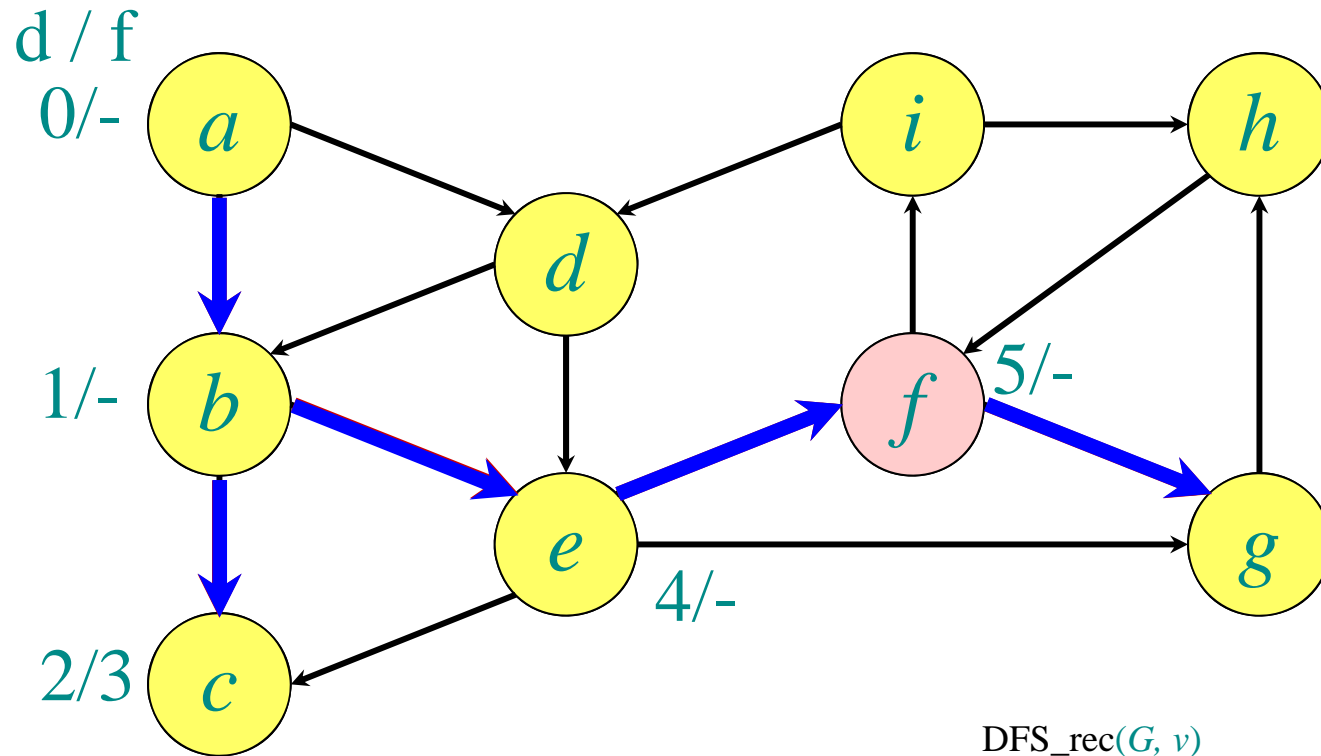
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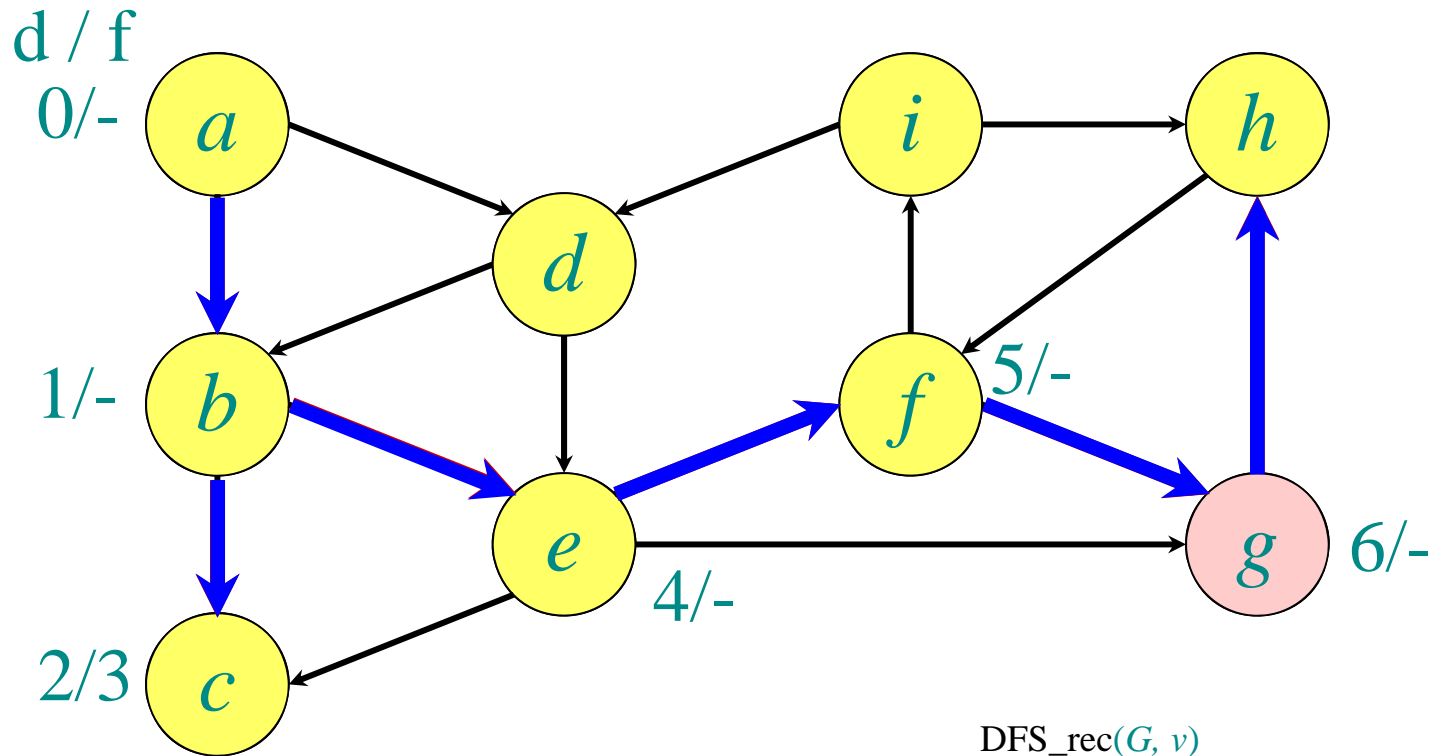


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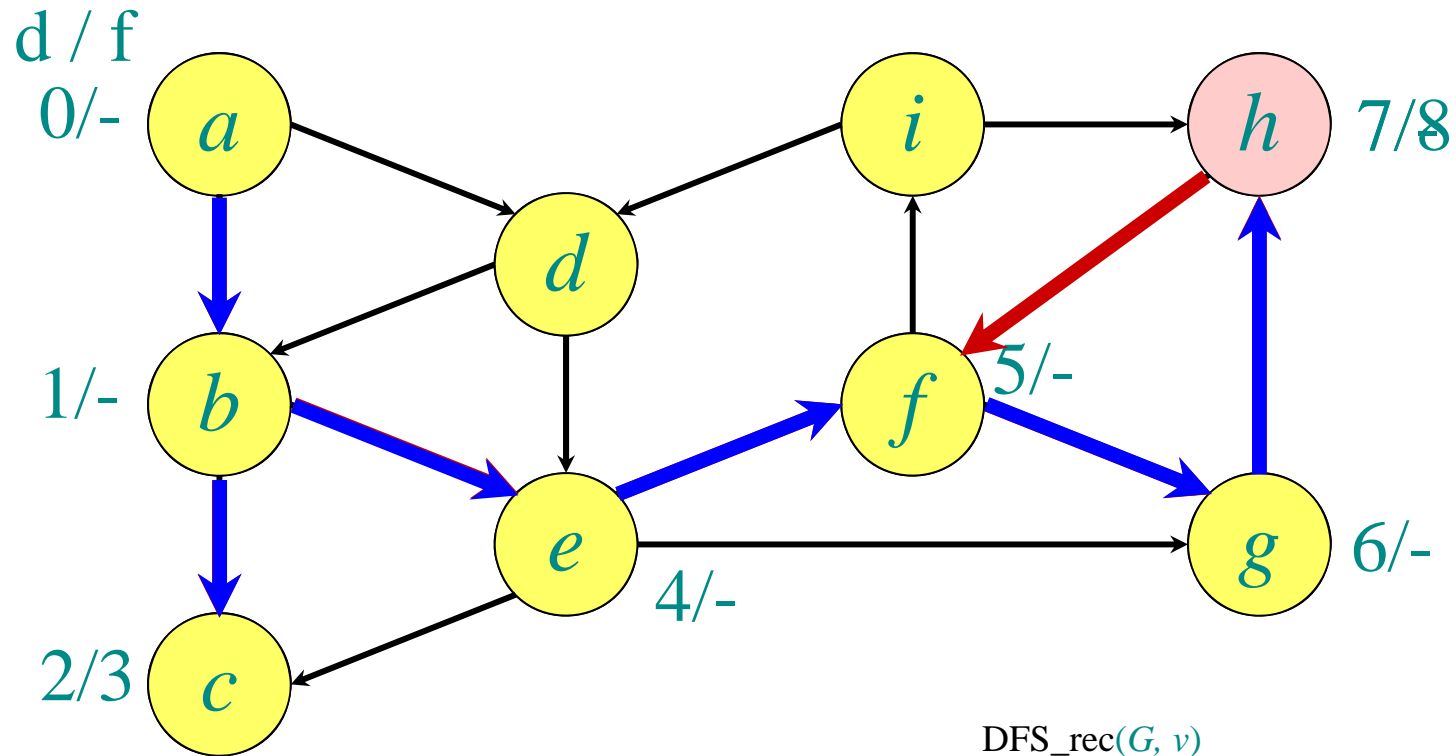
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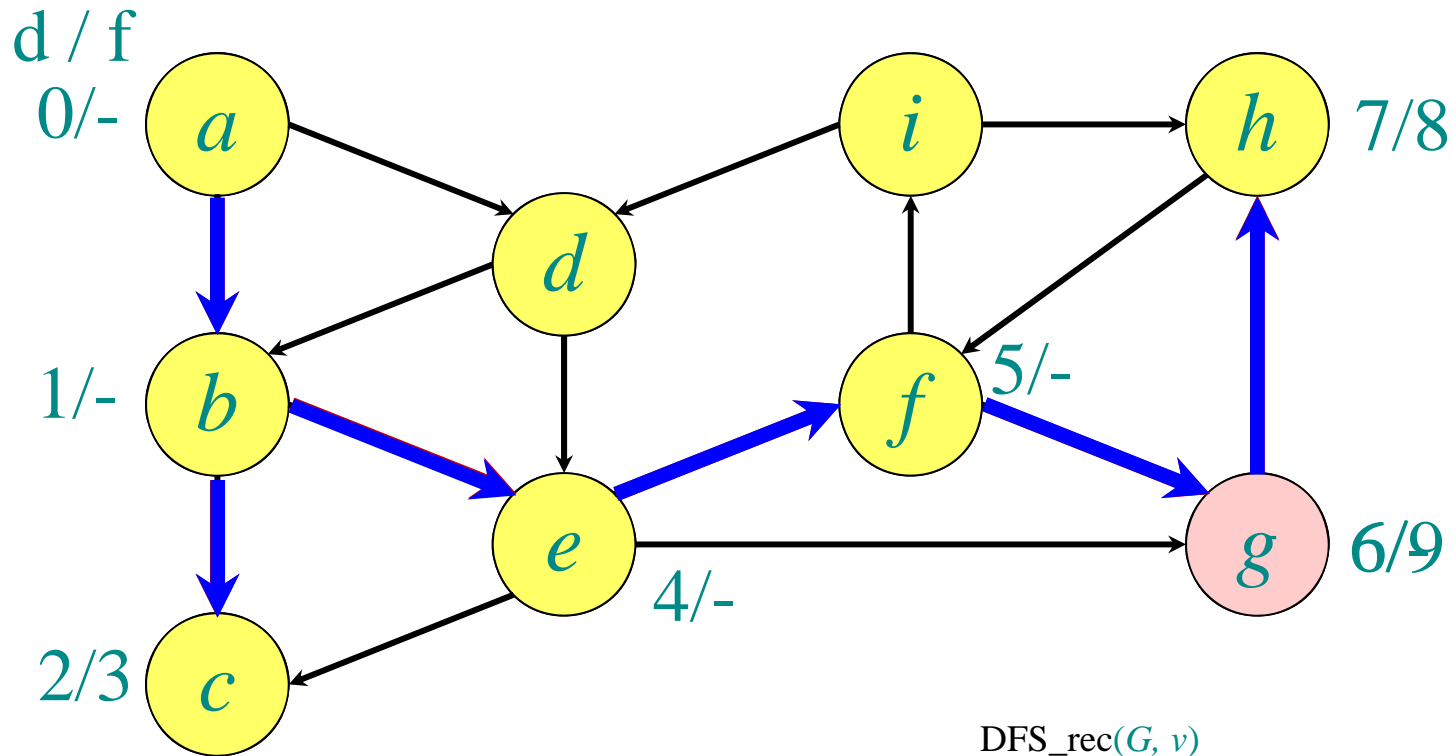
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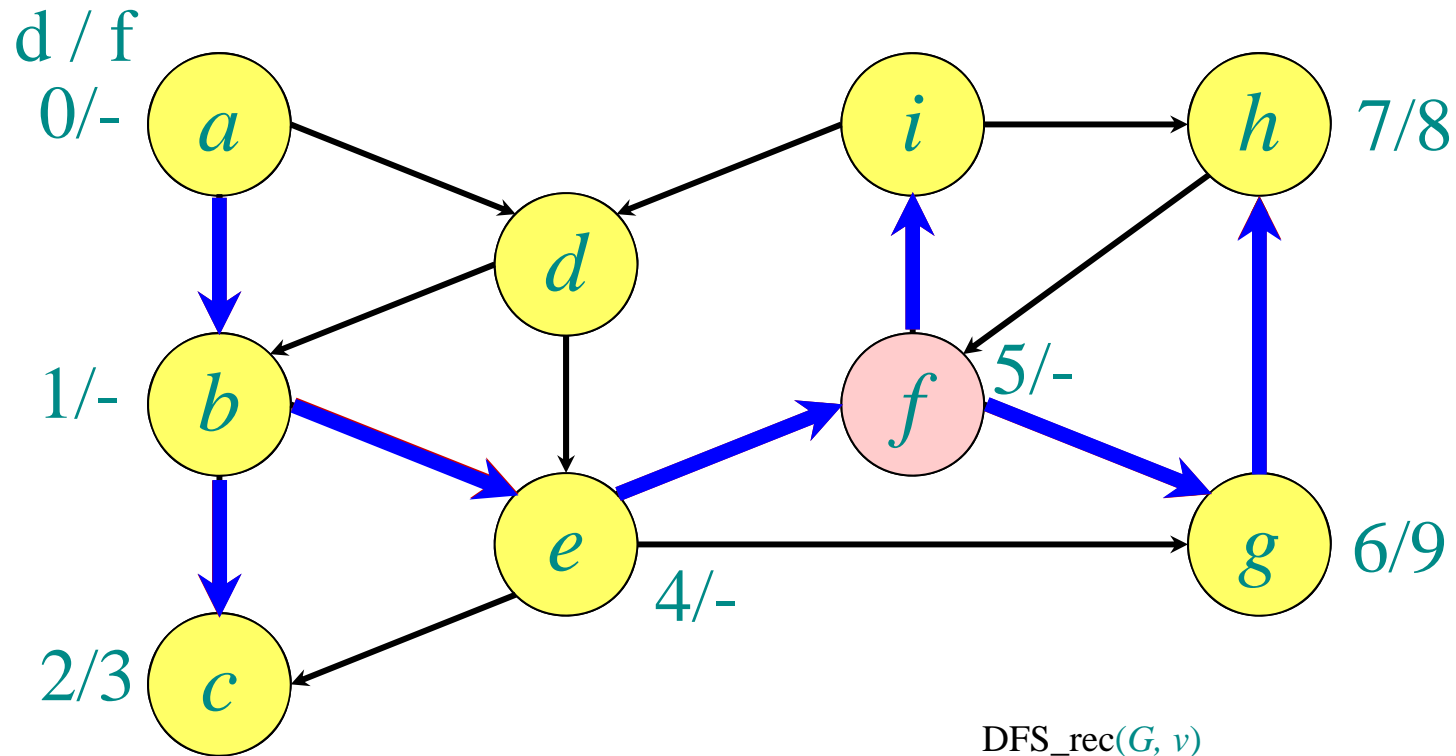
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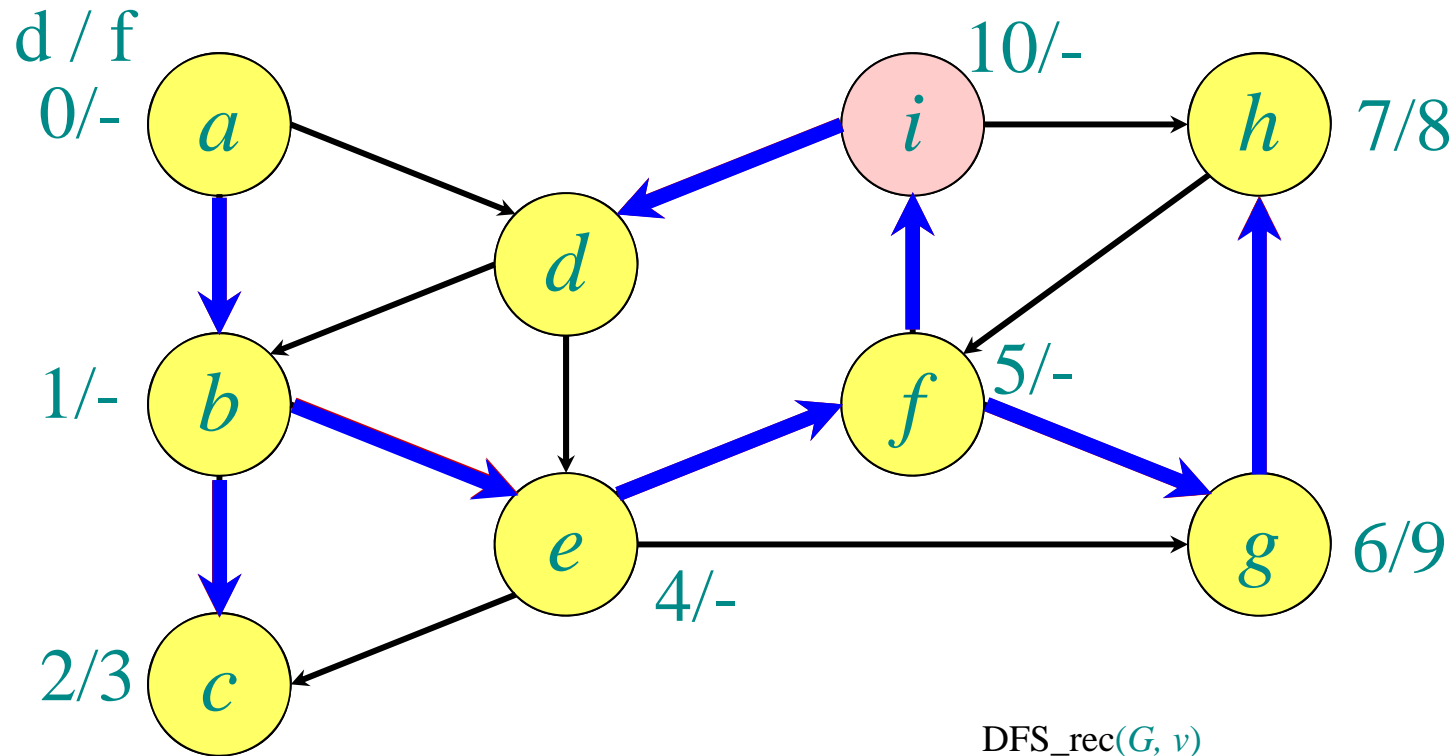


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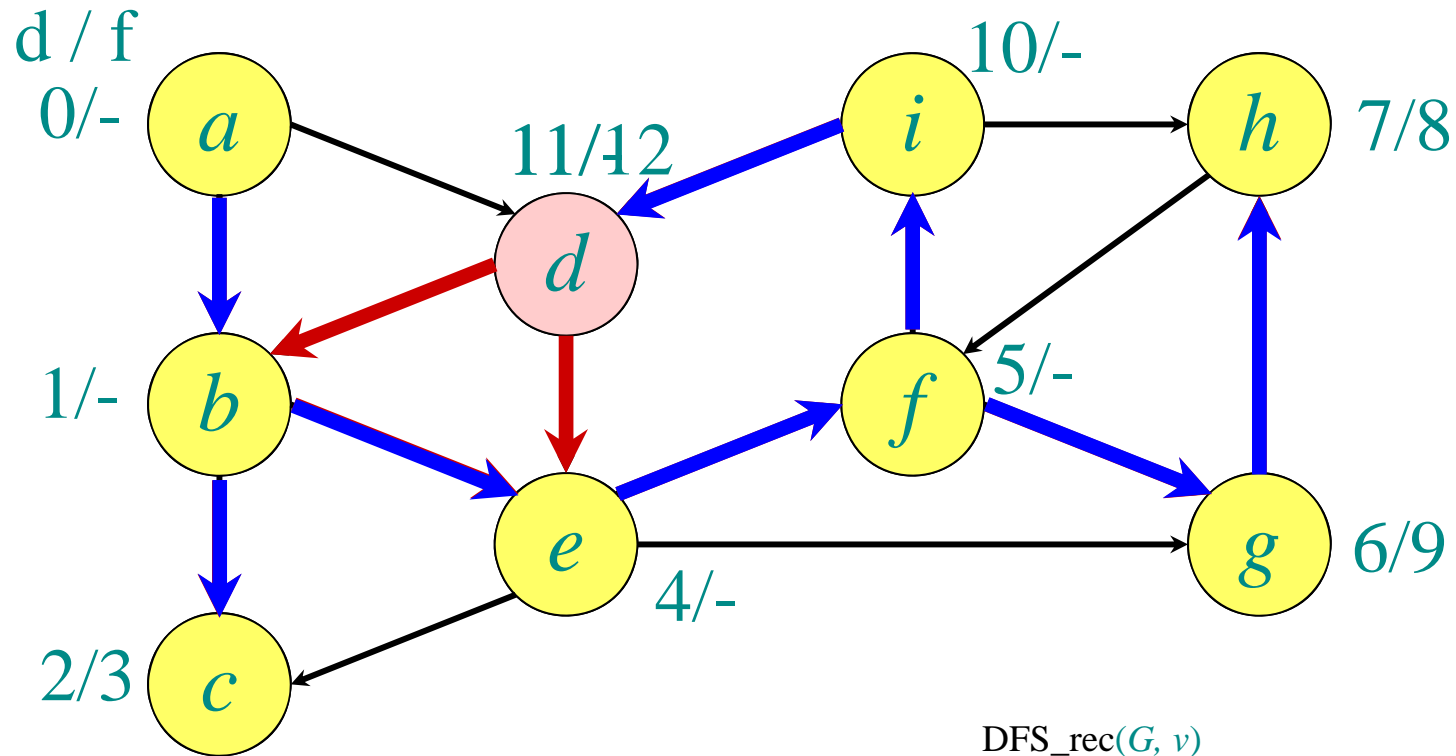
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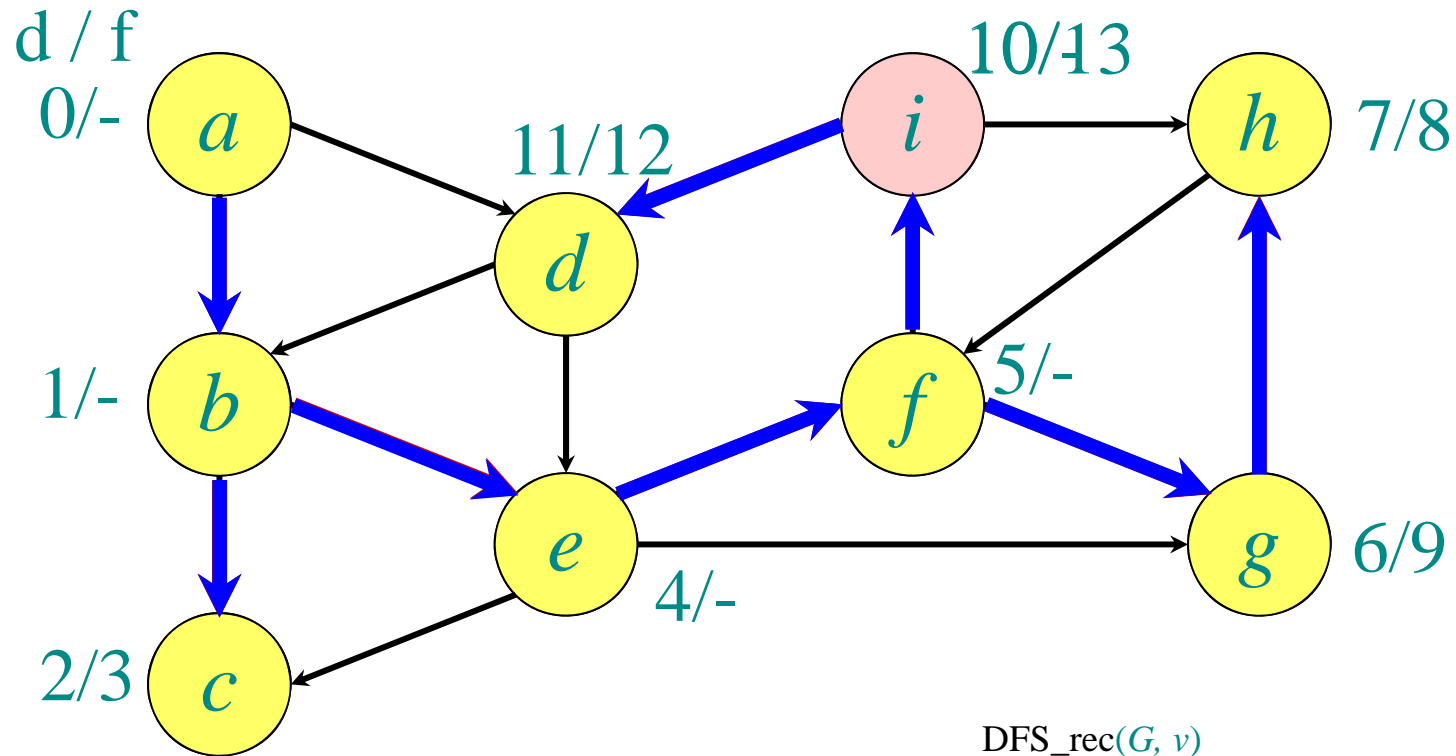
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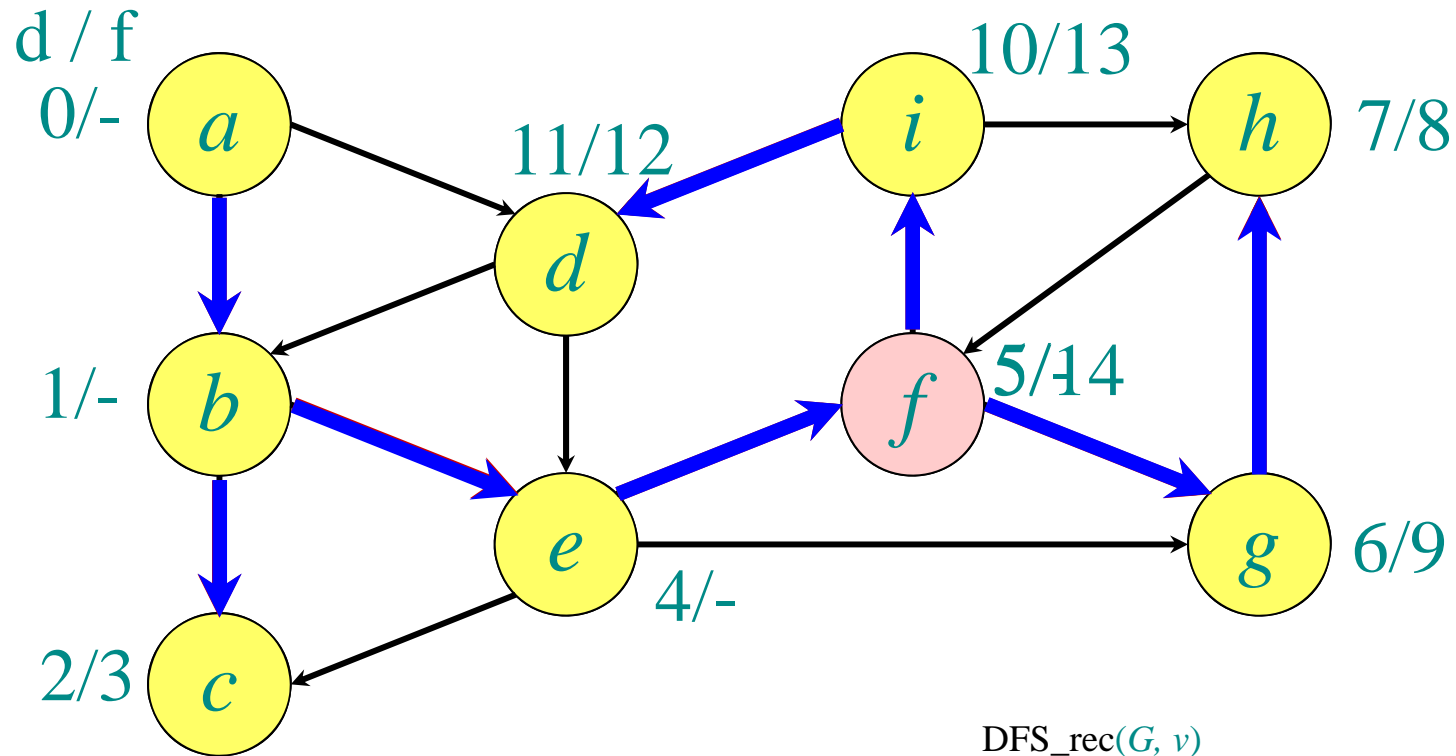
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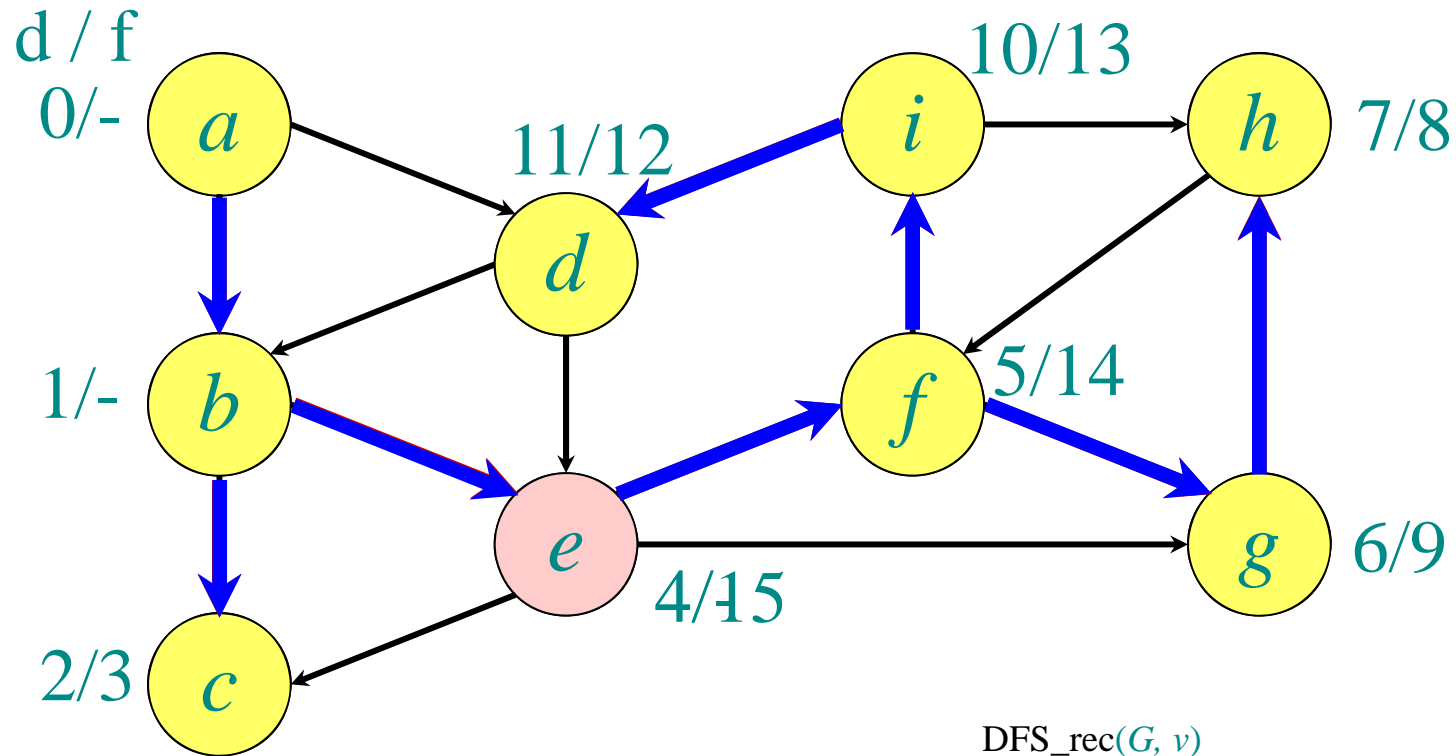
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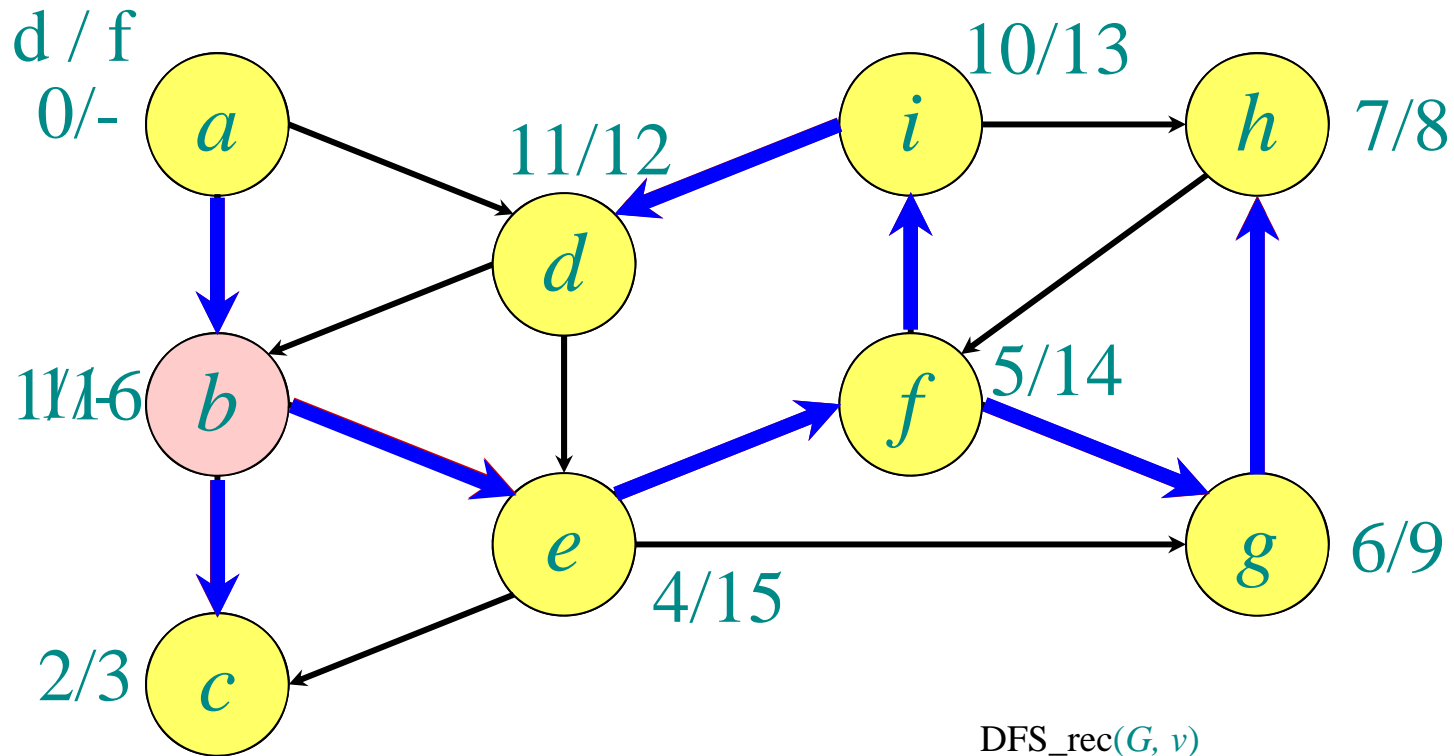
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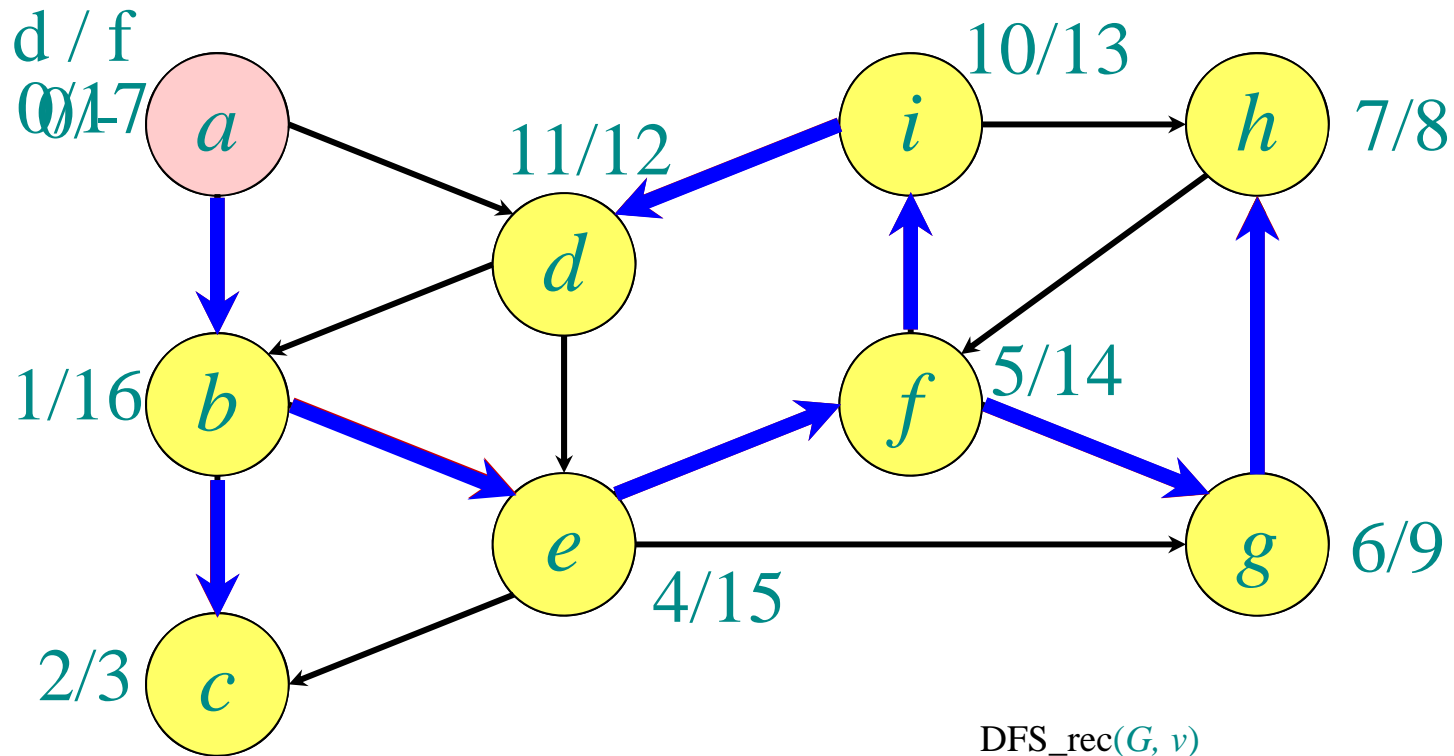
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Example of depth-first search



π : a b c d e f g h i
 - a b i b e f g f

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Depth-First Search (DFS)

$O(n)$

$O(n)$

without
DFS_rec

DFS($G=(V,E)$)

Mark all vertices in G as “unvisited” // **time=0**

for each vertex $v \in V$ **do**

if v is unvisited

DFS_rec(G,v)

$O(1)$

$O(deg(v))$

without
recursive call

DFS_rec(G, v)

mark v as “visited” // **$d[v]=++time$**

for each w adjacent to v **do**

if w is unvisited

Add edge (v,w) to tree T

DFS_rec(G,w)

mark v as “finished” // **$f[v]=++time$**

\Rightarrow With Handshaking Lemma, all recursive calls are $O(m)$, for a total of $O(n + m)$ runtime

DFS runtime

- Each vertex is visited at most once $\Rightarrow O(n)$ time
- The body of the **for** loops (except the recursive call) take constant time per graph edge
- All **for** loops take $O(m)$ time
- Total runtime is $O(n+m) = O(|V| + |E|)$

Paths, Cycles, Connectivity

Let $G=(V,E)$ be a directed (or undirected) graph

- A **path** from v_1 to v_k in G is a sequence of vertices v_1, v_2, \dots, v_k such that $(v_i, v_{i+1}) \in E$ (or $\{v_i, v_{i+1}\} \in E$ if G is undirected) for all $i \in \{1, \dots, k-1\}$.
- A path is **simple** if all vertices in the path are distinct.
- A path v_1, v_2, \dots, v_k forms a **cycle** if $v_1 = v_k$.
- A graph with no cycles is **acyclic**.
 - An undirected acyclic graph is called a **tree**. (Trees do not have to have a root vertex specified.)
 - A directed acyclic graph is a **DAG**. (A DAG can have undirected cycles if the direction of the edges is not considered.)
- An undirected graph is **connected** if every pair of vertices is connected by a path. A directed graph is **strongly connected** if for every pair $u, v \in V$ there is a path from u to v and there is a path from v to u .
- The **(strongly) connected components** of a graph are the equivalence classes of vertices under this reachability relation.